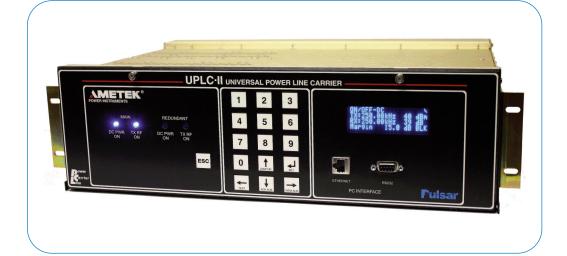
# UPLC-II\*\*

## Universal Power-Line Carrier



System Manual CU44-VER08



AMETEK Power Instruments 4050 N.W. 121st Avenue Coral Springs, FL 33065 1–800–785–7274 +1-954-344-9822 www.ametekpower.com



# 

1	Ordering Information
2	Product Description
3	Applications
4	Test Equipment, Maintenance & Troubleshooting
5	Installation/Commissioning Procedure
6	Testing Facilities
7	Communication Protocols
Α	Appendices & Index

# **UPLC-II™**

**System Manual** 

Table of Contents



## **ESD Warning!**

YOU MUST BE PROPERLY GROUNDED, TO PREVENT DAMAGE FROM STATIC ELECTRICITY, BEFORE HANDLING ANY AND ALL MODULES OR EQUIPMENT FROM AMETEK.

All semiconductor components can be **damaged** by the discharge of static electricity. Be sure to observe all Electrostatic Discharge (ESD) precautions when handling modules or individual components.



We recommend that you become acquainted with the information in this manual before energizing your UPLC-II<sup>TM</sup> system. Failure to do so may result in injury to personnel or damage to the equipment, and may affect the equipment warranty. If you mount the carrier set in a cabinet, it must be bolted to the floor or otherwise secured before you swing out the equipment, to prevent the installation from tipping over.

You should not remove or insert printed circuit modules while the UPLC-II<sup>TM</sup> is energized. Failure to observe this precaution can result in undesired tripping output and can cause component damage.

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#### **Preface**

#### Scope

This manual describes the functions and features of the *Universal Power-Line Carrier*. It is intended primarily for use by engineers and technicians involved in the installation, alignment, operation, and maintenance of the *UPLC-II*<sup>TM</sup>. (The majority of which also applies to the *UPLC*<sup>TM</sup>.)

#### **Equipment Identification**

The *UPLC-II*<sup>TM</sup> equipment is identified by the 11-digit Catalog Number on the label inside the front door or alternatively in the front display when pressing the SET button.

#### Warranty

Our standard warranty extends for 5 years after shipment. For all repaired modules or advance replacements, the standard warranty is 1 year or the remaining warranty time, whichever is longer. Damage clearly caused by improper application, repair, or handling of the equipment will void the warranty.

#### **Equipment Return & Repair Procedure**

To return equipment for repair or replacement:

- 1. Call your AMETEK representative at 1-800-785-7274 (or 954-344-9822).
- 2. Request an RMA number for proper authorization and credit.
- 3. Carefully pack the equipment you are returning.
  - Repair work is done most satisfactorily at the factory. When returning any equipment, pack it in the original shipping containers if possible. Be sure to use <u>anti-static material</u> when packing the equipment. Any damage due to improperly packed items will be charged to the customer, even when under warranty.
- 4. Make sure you include your return address and the RMA number on the package.
- 5. Ship the package(s) to:

AMETEK 4050 NW 121st Avenue Coral Springs, FL USA 33065

February 2018 iii



	Chapter/Topic	Page No.
1.	Chapter/Topic Ordering Information	1–1
	UPLC-II <sup>TM</sup> Catalog Number Digits Explanation	1–3
2.	Product Description	
	2.1 Specifications	
	2.2 Standard Nomenclature	2-5
	2.3 UPLC-II <sup>TM</sup> Chassis	2–5
	2.4 UPLC-II <sup>TM</sup> Modules	
	2.4.1 Power Supply Module	
	2.4.2 Power Amp Module	
	2.4.3 Display Module	
	2.4.4 Input/Output (I/O) Module	2-16
	2.4.5 Transceiver Module	2–18
	2.4.6 Ethernet Module	2-20
	2.5 UPLC-II™ Functional Description	2–24
	2.5.1 Keying Input Logic	
	2.5.2 Receiver Output Logic	2–29
3.	Applications	3–1
	3.1 ON/OFF Mode Protective Relay Applications	3-1
	3.1.1 Directional-Comparison Blocking (DCB)	3-1
	3.1.2 Phase-Comparison Blocking	3–1
	3.2 ON/OFF Mode Special Considerations	
	3.2.1 Multi-Terminal Lines	
	3.2.2 Phase Comparison	
	3.2.3 Hybrids/Series LC Unit	
	3.2.4 Interfacing to Electromechanical Relays	
	3.2.5 External Booster Amplifier	
	3.3 ON/OFF Mode Typical Wiring/Connections	
	3.4 ON/OFF Mode Alarms	
	3.5 FSK Mode Protective Relay Applications	
	3.5.1 Directional Comparison Unblocking	
	3.5.2 Permissive Overreaching Transfer Trip Systems	
	3.5.3 Permissive and Non-Permissive Underreaching Transfer Trip Systems	
	3.5.4 Dual Phase Comparison Unblocking Systems	
	3.5.5 Segregated Phase Comparison System	
	3.6 FSK Mode Direct Transfer-Trip (DTT) Systems	3-27
	3.6.2 Shunt Reactor Protection	
	3.6.3 Remote Breaker-Failure Protection	
	3.6.4 Direct Transfer Trip Channel Considerations	
	3.7 FSK Mode Special Considerations	
	3.7.1 3-Freq. Systems	
	3.7.2 4-Freq. Systems	
	3.7.3 Directional Comparison Unblocking (2-Frequency)	
	3.7.4 Transfer Trip: Overreaching, Underreaching or Direct (2-Frequency)	
	3.7.5 Phase Comparison Unblocking: Dual or Segregated (2-Frequency)	
	3.7.6 Three-Terminal Line Applications	
	3.7.7 External Booster Amplifier	
	3.8 FSK Mode Typical Wiring/Connections	
	3 9 FSK Mode Alarms	



	Chapter/Topic	Page No.
	3.10 Hybrid Applications	3–40
	3.10.1 Examples	
4.	Test Equipment, Maintenance & Troubleshooting	4–1
	Recommended Test Equipment	4–1
	4.1 Periodic Checks	
	4.2 Trouble Detection Sequence	
	4.3 Front Display Alarms	
	4.4 Transceiver NOVRAM Battery	
5	Installation/Commissioning Procedure	
٥.	Quick Installation Guide	
	5.1 Introduction	
	5.1.1 Safety Precautions	
	5.2 Mounting/Connecting	
	5.2.1 Mounting	
	5.2.2 Terminal Block Connections	5–3
	5.2.3 Equipment Ground	
	5.2.4 RF Coax Connections	5–5
	5.2.5 Other Connections	
	5.3 Hardware Jumper Settings	
	5.3.1 Backplane (Rear Panel)	
	5.3.2 I/O Module	
	5.3.3 Power Supply Module	
	5.3.4 Aux. Power Supply Module (for driving EM protective relays)	5–8
	5.3.5 Power Amplifier Module	
	5.4 PC Setup for Communication with the UPLC-II <sup>TM</sup>	5–10
	5.4.1 Ethernet Port – PC/UPLC-II <sup>TM</sup> Setup	5–10
	5.4.2 Front RS-232 Port – PC Setup	
	5.5 Logging In	
	5.5.1 Admin Web Page	
	5.5.2 User Accounts	
	5.6 Making/Saving Settings	
	5.6.1 Loading Settings	
	5.6.2 Saving Settings	
	5.6.3 Working vs Temporary Settings	
	5.7 Settings Pages	
	5.7.1 General Tab	
	5.7.2 Logic Tab	
	5.7.3 Input/Output Tab	
	5.7.4 Checkback (ON/OFF Mode) or Trip Test (FSK Mode) Tab	
	5.7.6 Submit Tab	
	5.8 Calibration	
	5.9 SOE Log	
	5.10 Home Page	
	5.11 Front Panel	
	5.11.1 Password Access	
	5.11.3 Set Button Menu	
	5.11.4 Test Button Menu	



Chapter/Topic H	Page No.
6. Testing Facilities	6–1
Checkback Test Facility (Quick Checklist, if not working)	6-1
ON/OFF Mode Automatic Checkback (CB) Feature	
6.1 General Description	
6.2 Checkback (CB) Settings	
6.2.1 General Information	6-2
6.2.2 Primary Communications Mode	6-2
6.2.3 Checkback Test Sequence	
6.2.4 Last Remote	6-3
6.2.5 Auto tests	
6.2.6 Low Power Tests	6-3
6.2.7 Retries	
6.2.8 Automatic Tests – Time Settings	
6.2.9 Optional Carrier Recovery	
6.3 Checkback Tester Inputs/Outputs	
6.4 Performing Checkback Tests/Functions	
6.4.1 Manual Requests from Web Pages	
6.4.2 Loopback Test Capability (Turn On Remote Transmitter via the power line	)6–7
6.4.3 Remote-Initiated Periodic Tests	
6.4.4 Remote-Initiated "Hours of the Day" Tests	
6.5 System Troubleshooting with Checkback	
FSK Mode Trip Test Feature	
6.6 General Description	
6.6.1 Two Frequency Applications Real Trip Scenario	
6.6.2 Two Frequency Application Checkback Trip Scenario	
6.6.3 Three Frequency Applications Checkback Trip Scenario	
6.6.5 Trip Test Pulse	
7. Communication Protocols	
7.1 DNP 3	
7.1.1 DNP 3 Settings	
7.2 DNP Binary Inputs (UPLC-II <sup>TM</sup> Inputs)	
7.3 DNP Binary Inputs(UPLC-II <sup>TM</sup> Outputs)	
7.4 DNP Analog Inputs (UPLC-II <sup>TM</sup> Analog Values)	
7.5 IEC 61850 Protocol	
7.5.1 UPLC-II <sup>TM</sup> with IEC 61850	7-8 7_8
7.5.2 Private GOOSE Subscription Details	
7.5.3 Overview	
Appendix A: UPLC-II <sup>TM</sup> Serial Connection Configuration	
Appendix B: PC Setting for Static IP Address	
Appendix C: UPLC-II <sup>TM</sup> XML File Format	
Appendix D: User Management Interface (UMI)	
Appendix E: Sequence of Events (SOE) Listing	
Appendix F: Changing the Cat. No. on a UPLC-II <sup>TM</sup>	
Appendix G: Upgrading the firmware in a UPLC-II <sup>TM</sup>	G-1
Index	I 1

## 1. Ordering Information

The UPLC-II<sup>TM</sup> carrier is functionally compatible with earlier type carrier equipment (e.g., KR, TC, TC-10, TC-10A & TC-10B, TCF, TCF-10, TCF-10B, UPLC<sup>TM</sup>) as well as other suppliers' equipment. That is, you may use the UPLC-II<sup>TM</sup> with these other carrier types at the opposite end of the line.

However, the testing options below are only compatible between UPLC-II<sup>TM</sup>, UPLC<sup>TM</sup>, TC-10B/TCF-10B and UCBS.

- Automatic Checkback Testing Facilities for periodic testing of the carrier channel at programmable intervals (in ON/OFF mode)
- Trip Test Facility (in FSK mode)

You may use the UPLC-II™ carrier set with the following types of relay systems:

- All Directional-Comparison Systems
- Phase-Comparison Systems
- Direct Transfer Trip Systems

The equipment identification number (catalog number) is displayed when you press "set" on the front keypad & is shown on all of the webpages. There is also a decal/sticker on the inside of the front door. The UPLC-II<sup>TM</sup> catalog number comprises eleven (11) characters, each specifying a particular feature. This number identifies the unit's capabilities, as well as any optional modules installed in the unit. It is electronically stored in the Transceiver module and controls all features by enabling/disabling them in the unit. Features not enabled are "grayed out" on the web pages. The catalog number can be changed with a software key (alphanumeric code) that AMETEK supplies. It is input into the catalog number tab of the Admin page. Some features can be changed at no charge and others add cost.

The table on the following page provides a complete listing of the options for ordering a UPLC-II<sup>TM</sup>, and a sample catalog number. To order one or more UPLC-II<sup>TM</sup> units, simply identify the features you want for each chassis. For example, - U S 1 N S M 9 A F S X - describes a UPLC-II<sup>TM</sup> with the following features:

Chassis: UPLC-IITM

**Configuration:** Single Transceiver Unit

Power Supply: 110/125/250 Vdc Redundant Power Supply: None

Outputs / Logic: Standard Outputs (7 Solid State & 3 Contacts) / No Special Logic

**Rear Ethernet Ports:** Redundant/Daisy Chain – 2 RJ-45 (10/100 Base T)

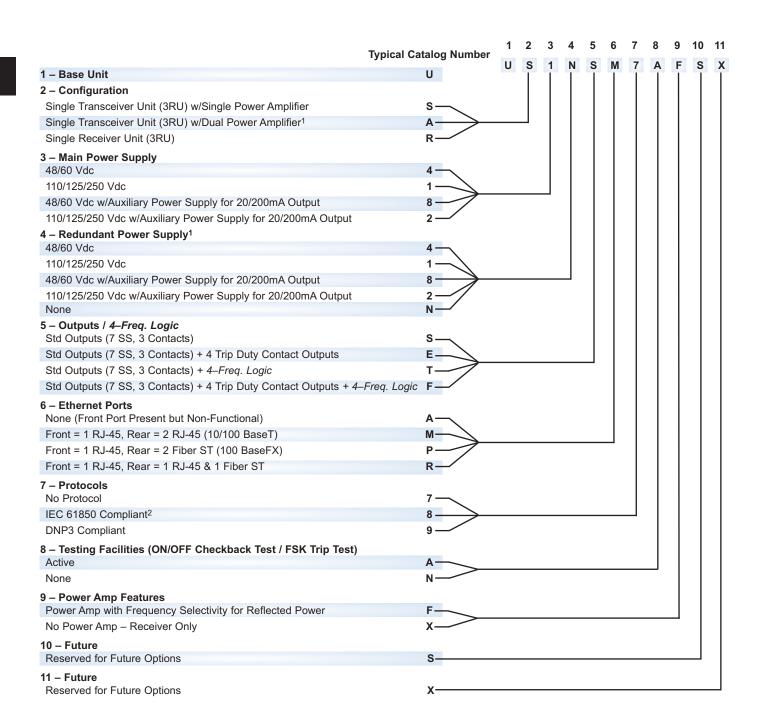
**Protocols:** DNP 3.0

Testing Facilities: ON/OFF Checkback Test / FSK Trip Test

**Power Amp Features:** Power Amp with frequency selectivity for TX reflected power



Table 1–1. UPLC-II™ Catalog Numbers



<sup>1</sup>Dual Power Amps requires 2<sup>nd</sup> Power Supply <sup>2</sup>Must also select an ethernet option



#### UPLC-II™ Catalog Number Digits Explanation

#### **Digit and Description**

- 1. Always starts with letter U
- 2. Configuration
  - Transceiver or Receiver only (RX only eliminates the Power Amp module)
  - Single or dual (redundant) Power Amps
- 3. Main Power Supply Type (Input voltage and auxiliary Power Supply)
  - 48Vdc
  - 110/125/250 Vdc (also runs off 120Vac)
  - With or without Aux. PS module to drive older EM relays with 20/200mA (Aux output is on TB1/TB2 for putting in series with an output to get the correct current.)
- 4. Redundant Power Supply Yes or No
- 5. Outputs (with or without 4 optional Trip Test Duty relay outputs) Yes or No / Special Logic (FSK 4-Frequency) Yes or No
  - (This digit specifies 2 different features with one digit)
- 6. Ethernet Interface Options (Rear Port Connectors)
  - Dual Electrical RJ-45
  - Dual Fiber ST
  - One Electrical, RJ-45 / One Fiber, ST
- 7. Communications Protocol options
  - None, DNP3 or IEC61850
- 8. Testing Facilities Yes or No
  - ON/OFF mode = Checkback Test
  - FSK mode = Trip Test (Shift from guard to trip in test mode without real trip output)
- 9. Power Amp options
  - None, Receiver-only unit
  - Power Amp with Freq. Selectivity for TX Reflected power meter
- 10. Future place holder
- 11. Future place holder

(All UPLC-II™ Catalog numbers end in "SX")



#### **USER NOTES**

# 2. Product Description

### 2.1 Specifications

Table 2–1. Basic Transmit / Receive Specifications

Basic Industry Specification	Meets or Exceeds requirements of C93.5, ANSI Requirements for Single Function Power-Line Carrier TX/RX Equipment
Frequency Range	30–535 kHz
TX / RX Frequency Resolution	10 Hz Increments
Frequency Stability	±5 Hz
TX / RX Connections	2-Wire or 4-Wire
TX RF Output Impedance	50 Ω, 75 Ω Nominal Unbalanced
TX RF Output Power	10W Max (20W w/optional redundant amp), 0.3W Min
TX Harmonic & Spurious Output	55 dB Below TX Freq. at Rated Full Power
TX Output Variation	±1 dB Over Temp / Volt Range
TX Reflected Power Monitor Accuracy with Interference	±10 %
Modulation Type	ON/OFF (Amplitude Modulation) or FSK (Frequency Shift Keyed), Field Programmable
FSK Frequency Shifts	Programmable ±100, ±250 or ±500 Hz (See 4-Freq. Table Below)
Minimum In-Band SNR for Good Channel Operation	13 dB for FSK, 20 dB for ON/OFF
4-Wire Receiver Input Impedance	> 4 kΩ
Receiver Sensitivity (with 15dB Fade Margin)	28 mV (Min. with 15 dB Margin) to 70 V (Max), or –18 dBm (Min. w/15 dB Margin) to +50 dBm (Max.) across 50 Ω
Receiver Sensitivity (Absolute Minimum)	5 mV or –33 dBm across 50 $\Omega$
Hot-swappable	Power Supply & Power Amp Only

#### Table 2-2. IRIG-B Load Specifications

Туре	Connector	Load	Compatability	Signal
Modulated	J13	2.5 k Ω Min. (3.5 k Ω Typical)	IRIG-B123	Mod. 1 kHz Sine Wave
TTL (Unmodulated)	J14	3.8 mA Typical at 5 Vdc	IRIG-B003	0-5 V Pulse Train

Table 2–3. Frequency Specifications for 4-Frequency Special Logic

	RX Bandw	vidth / Shift	
TX Keyed State	600 Hz BW +/- 250 Shift	1,200 Hz BW +/- 500 Shift	Frequency Designation
Non-keyed	+83 Hz	+166 Hz	F3
Command A	+249 Hz	+498 Hz	F4
Command B	–83 Hz	–166 Hz	F2
Command A & B	–249 Hz	–498 Hz	F1



Table 2-4. Output Ratings (All Outputs Non-Wetted & Non-Polarity Sensitive)

Output (Terminal Block)	Max Curr Make & Carry	ent at @ 250 Vdc  Make & Carry Interrupt	c Interrupt	N.O. / N.C. Nominal Selectable Voltage	Nominal Voltage	Voltage Range	Max Operate Time	Max Dropout Time
Power Supply Alarm (TB1 or 2 - 5 & 6)	2 A	A/N	0.25 A	Hardware Jumper (PS)	> 0	15-250 Vdc	15 ms	10 ms
7 Low Level Solid State (TB4 & 5)	0.1 / 1.0 A Hardware Selectable	6 A / 15 ms for 1 A Setting	0.1 / 1.0 A Hardware Selectable	Software Setting	2.5 V	15-250 Vdc	0.5 ms	0.5 ms
3 Low Level EM Contacts (TB5)	2 A	N/A	0.25 A	Hardware Jumper (I/O)	0 V	15-250 Vdc	15 ms	10 ms
4 Trip Duty EM Contacts (TB6)	44 A	30 A / 200 ms w/duty cycle per ANSI C37.90	0.25 A	Hardware Jumper (I/O)	0.2 V 0.2 V 7 V 7 V 30 A	15-250 Vdc	N.O. Contact Closing = 3 ms N.C. Contact Opening = 2 ms	N.O. Contact Opening = 5 ms N.C. Contact Closing = 4 ms

Table 2–5. Keying Input Ratings (All Inputs Current Limited & Non-Polarity Sensitive)

Nominal Input Voltage	Min Keying Voltage	Max Current Draw
15 Vdc	10 Vdc	5 mA
48/60 Vdc	38 Vdc	5 mA
110/125 Vdc	70 Vdc	5 mA
220/250 Vdc	150 Vdc	5 mA



Table 2-6. Minimum Frequency Spacing

ON/OFF Applications			
Wide Band	Directional Comparison Relaying		4000 Hz
Narrow Band	Directional Comparison Relaying		2000 Hz
Extreme Wide Band	Phase Comparison Relaying		4000 Hz
FSK Applications			
Narrow Band:	Directional Comparison or DTT	1 way	500 Hz
Narrow Band	Directional Comparison or DTT	2 way	1000 Hz*
Wide Band	Directional Comparison or DTT	1 way	1000 Hz
Wide Band	Directional Comparison or DTT	2 way	2000 Hz*
Wide Band	Dual Comparator Phase Comp.	1 way	1500 Hz
Wide Band	(50/60Hz sq wave keying)	2 way	3000 Hz*
Wide Band	Segregated Phase Comparison	1 way	2000 Hz
Wide Band	(50/60Hz sq wave keying)	2 way	4000 Hz*
Extra Wide Band:	Directional Comparison or DTT	1 way	2000 Hz
Extra Wide Band	Directional Comparison or DTT	2 way	4000 Hz*
Extra Wide Band	Dual Comparator Phase Comp.	1 way	1500 Hz
Extra Wide Band	(50/60Hz sq wave keying)	2 way	3000 Hz*
Extra Wide Band	Segregated Phase Comparison	1 way	2000 Hz
Extra Wide Band	(50/60Hz sq wave keying)	2 way	4000 Hz*

Specifications Notes:

Table 2-7. Nominal Receiver Bandwidths & Corresponding Channel Delay\*

Mode	Receiver Bandy	width	Channel Delay
ON/OFF	Narrow Band	600 Hz	2.8 ms
	Wide Band	1200 Hz	2.1 ms
	Extra Wide Band	4000 Hz	1.5 ms
FSK	Narrow Band	300 Hz	7 ms
	Wide Band	600 Hz	6.5 ms
	Extra Wide Band	1200 Hz	4.8 ms

\*NOTE: Channel times are nominal values with a 15 dB RX Margin on a back-to-back system. Times are for solid state outputs and do not include logic trip delay or relay output operation times.

<sup>\*</sup>An external hybrid or other device offering at least 20 dB rejection of the adjacent channel must be used in the application. I way represents transmitter to transmitter or receiver to receiver

<sup>2</sup> way represents transmitter to receiver



Table 2–8. Environmental/Surge/Interface Specifications

Ambient Temperature, range of air	-30 C to +70 C (ANSI C37.90)
Relative Humidity	Up to 95% (non-condensing) at 40 C (for 96 hrs cumulative) (ANSI C93.5)
Altitude	Up to 1500 m (without de-rating), 6000 m with de-rating
Surge Withstand Capability	Per ANSI C37.90.1
1 Minute withstand	IEC 255-5 and C37.90 (500 Vdc class)
Coax, center conductor to ground	3000 V impulse level, 1.2 x 50 μs impulse, per ANSI C93.5
Dielectric	Per ANSI C37.90, 500 Vdc class (3,000 Vdc dielectric withstand), IEC 60255-5
Electrostatic Discharge (ESD)	Per ANSI C37.90.3, IEC 61000-4-2
Radiated Electromagnetic Interference from Transceivers	Per ANSI C37.90.2
Carrier Frequency on dc Input Leads When Transmitting 1 W	20 mV (max.)

Table 2-9. Input Power Requirements

Nominal Battery Voltage	Permissible Voltage Range Range	Standby *	1 Watt Transmit Single	10 Watt Transmit Single
48/60 Vdc	38 to 76 Vdc	25 watts	35 watts	60 watts
110/125/250 Vdc	88 to 300 Vdc	20 watts	30 watts	66 watts

<sup>\*</sup>Not transmitting

Permissible ripple on incoming Vdc = 5% Maximum allowable frequency of ripple = 120 Hz Unit can also operate with 110–130 Vac input

Table 2–10. Weight & Dimension Specifications

Equipment	Net V	Veight*	Hei	ight	Width		Depth		Rack
	lbs	Kg	inches	mm	inches	mm	inches	mm	Space
Single Unit	21	9.53	5.218	132.54	17.437	444.88	13.26	336.75	3 RU

<sup>\*</sup> Without redundant Power Supply or Power Amp.



#### 2.2 Standard Nomenclature

The standard nomenclature for AMETEK carrier protection equipment is as follows:

Cabinet – contains fixed-racks, swing-racks, or open racks

Rack – contains one or more chassis (e.g., the UPLC-II<sup>TM</sup>)

Chassis – contains several printed circuit boards, called modules (e.g., Power Supply or Transceiver)

Module/Card/Board – contains a number of functional circuits (e.g., Oscillator or Microprocessor)

**Circuit** – a complete function on a printed circuit board

#### 2.3 UPLC-II™ Chassis

The Front Panel, with the unit's S/N on back of it, requires a screwdriver to open. It is shown in Figure 2–1. See Figure 2–2 for the backplane. The UPLC-II<sup>TM</sup> chassis specifications (see Figure 2–3) include standard dimensions of:

Height – 5.25" (133.35 mm), requiring 3 rack units, each measuring 1.75" (44.45 mm)

Width – 19.00" (482.6 mm) Depth – 13.50" (342.9 mm)

The chassis includes a two-piece metal cover plate on back. The top half of the cover plate is easily removable with 2 or 4 captivated screws fastening it. Loosen screws, pull bottom out then down to remove.

Each chassis is notched for mounting in a standard 19" rack and has adjustable mounting brackets on the sides. It may be flush-mounted against another chassis on top & bottom.

#### 2.4 UPLC-II™ Modules

Each module has a white S/N bar code sticker. The basic UPLC-II<sup>TM</sup> has 7 standard printed circuits boards in a 3RU 19 inch chassis. There are 4 additional boards that may be supplied, based upon the catalog number purchased. The illustration for how these are all interconnected is on Page 2–22.

Table 2-11. UPLC-II<sup>TM</sup> Modules and Part Numbers

Name	Part Number
Power Supply (Main / Optional Redundant) 110/125/250 Vdc	CU20-PS1MN-001
Power Supply (Main / Optional Redundant) 48/60 Vdc	CU20-PS1MN-002
Power Supply (Main / Optional Redundant) 110/125/250 Vdc w/Aux. PS	CU20-PS1MN-101
Power Supply (Main / Optional Redundant) 48/60 Vdc w/Aux. PS	CU20-PS1MN-102
Power Amplifier (Main / Optional Redundant)	CU20-PA1MN-002
Display Board	CU20-DP1MN-001
Aux. Display board – w/Ethernet RJ-45 & RS-232 DB9 connectors	CU20-DP1A3-001
Input/Output Board	CU20-IO1MN-001
Transceiver Board	CU20-XVRMN-001
Ethernet Board (Optional) – 2 RJ-45 (10/100 BaseT)	CU20-XVRA5-001
Ethernet Board (Optional) – 2 Fiber ST (100 BaseFX)	CU20-XVRA6-001
Ethernet Board (Optional) – 1 RJ-45 & 1 Fiber ST	CU20-XVRA7-001
Aux. PS (Optional) – for powering 20V, 20 or 200 mA outputs	CU20-PS1A1-001
Motherboard/Backplane	CU20-BP1MN-101
Front Door (without auxiliary door board)	1088-524
Chassis (complete with backplane & front door)	1087-177



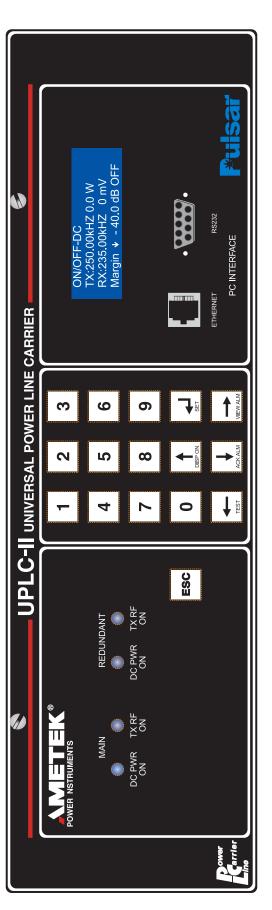
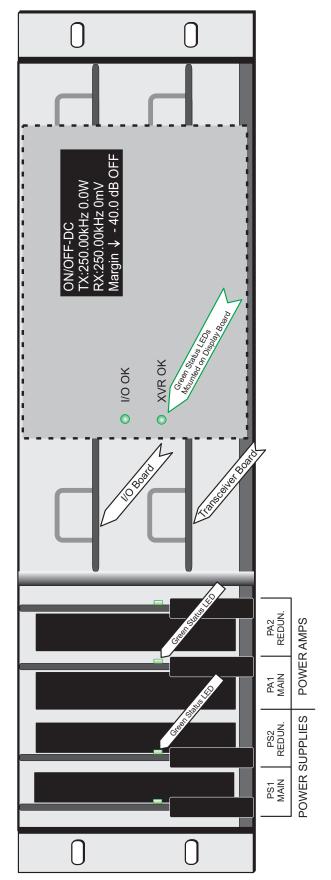


Figure 2-1. UPLC-IITM Front View

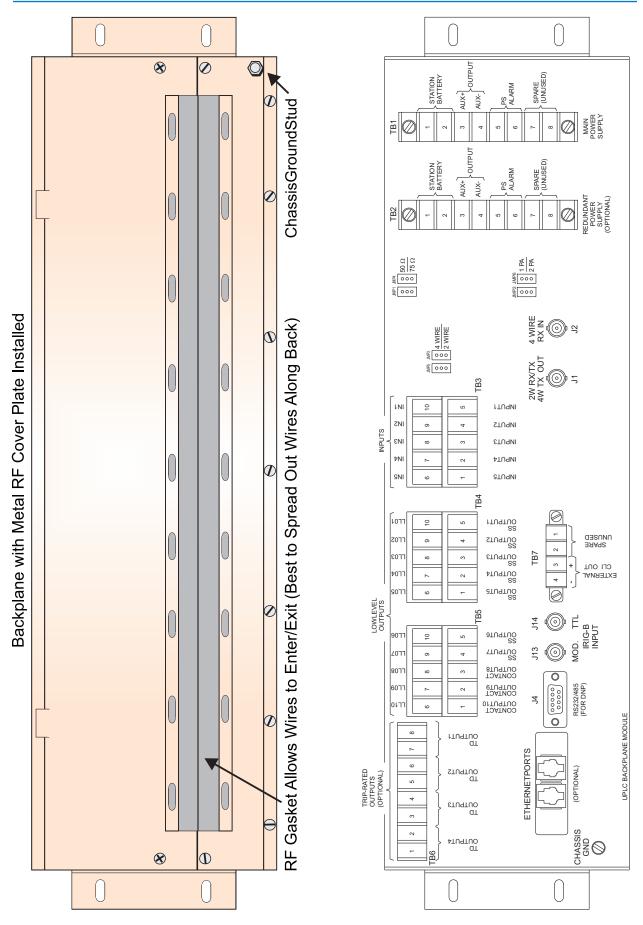
NOTE: S/N for the complete UPLC-IITM unit is located on the silver label on rear of front door.



Chassis with Front Door Open

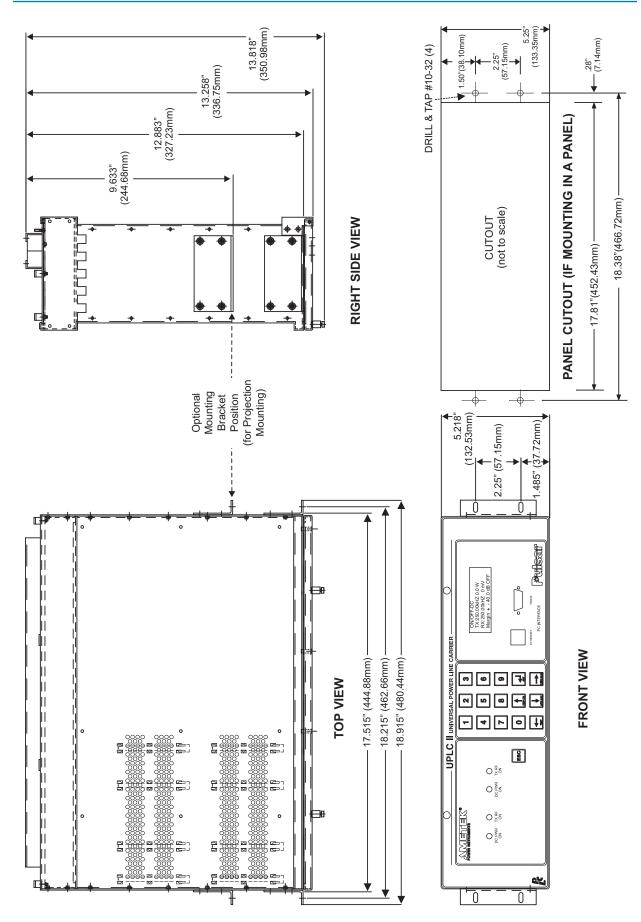
NOTE: Ethernet board mounted on rear of transceiver board.





February 2018 Page 2–7





Page 2–8

Figure 2-3. Chassis Dimensions



#### **USER NOTES**



Description	Part Number	Digit 3 & 4 of UPLC-II Cat. No.
125/250V Power Supply	CU20-PS1MN-001	1
125/250V Power Supply w/ PS Aux	CU20-PS1MN-101	2
48V Power Supply	CU20-PS1MN-002	4
48V Power Supply w/ PS Aux	CU20-PS1MN-102	8

#### 2.4.1 Power Supply Module

#### **Description**

The Power Supply (PS) module takes station battery voltage or 120Vac input and converts it into 4 dc output voltages (+/-16.5V) and +/-6.0V needed for the UPLC-IITM. It mounts into the far left slot of the chassis with the redundant power supply right beside it when used. The two Power Supply modules have separate input terminal blocks and can be run off of different voltages if desired. The Power Supply Module has an alarm relay to indicate failure of the module. This is a "fail-safe" alarm and is therefore energized if the module is functional. The UPLC-IITM was designed without an ON/OFF switch for the Power Supply in order to circumvent a common point of failure. Instead a jumper, J3, is available for keeping the PS in the off state when plugged in if desired. Also, the Power Supply is hot-swappable and may be pulled out to power down the unit.

An optional auxiliary Power Supply daughter board is available for providing an isolated lower voltage output to drive electromechanical relays requiring 20 or 200 mA as well as a 20V output option. This board is soldered onto the main board via headers. When used, it is put in series with one of the UPLC-II<sup>TM</sup> outputs that connects to an EM protective relay or other device requiring 20/200 mA current or low voltage.

#### **Customer interface points:**

#### Main board Jumpers/LED/Fuses

PWR ON/PWR OFF Jumper (J3) –
Normally in PWR ON position. Place in
PWR OFF position for disabling the Power
Supply when it is desired to have the module
plugged in with input power applied but
have the UPLC-II<sup>TM</sup> remain powered off.

- PS FAIL Contact Jumper (JMP1/2) For setting the Power Supply fail alarm contact output on TB1-5 & 6 or TB2-5 & 6 for normally open (N.O.) or normally closed (N.C.)
- PS OK LED (LE1) Status LED for the PS, when on, it indicates that all 4 dc output voltages are within tolerance and not too low in voltage. This LED has a corresponding virtual LED on the home web page of the UPLC-IITM.
- Fuses (F1/F2) For disconnecting input when drawing too much current due to a failure on the PS.

#### Auxiliary board (low voltage output) Jumpers

- 20/200mA Jumper (JMP1/2) For choosing 20 or 200 mA for driving EM relays.
- 20V/46V Jumper (JMP3) For choosing between 20V output versus 46V (20mA) output option.

The jumpers on the auxiliary power supply board need to be set to give the desired output voltage/current per the following:

- $\underline{20\text{mA}}$  for an EM relay with about 2200  $\Omega$  coil resistance: JMP3 = 46V, and JMP1/JMP2 = 46V/20V (20mA).
- $\underline{200\text{mA}}$  for an EM relay with about 25  $\Omega$  coil resistance: JMP3 = setting does not matter, and JMP1/JMP2 = 8V (200mA).
- $\underline{20V}$  output for some other applications: JMP3 = 20V, and JMP1/JMP2 = 46V/20V (20mA).

#### **Backplane Test Points**

• The 4 dc voltage outputs are labeled toward the bottoms of the DIN connector pins close to TB1 & TB2 and can be verified with a meter from the rear of the chassis with the cover off if the "PS OK" LED is off.



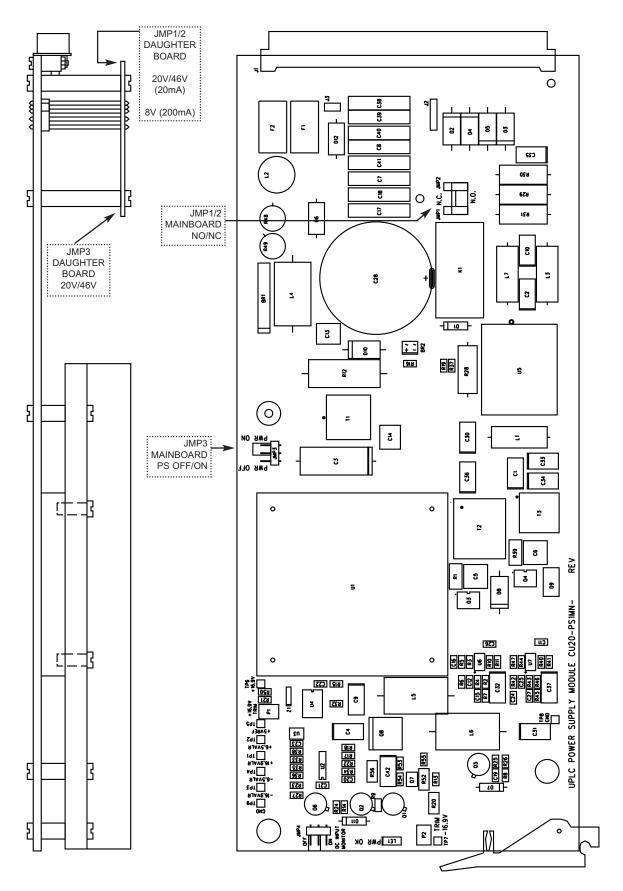


Figure 2-4. Power Supply Component & Jumper Locations



#### 2.4.2 Power Amp Module

#### **Description:**

The Power Amp (PA) input comes from the transmit portion of the Transceiver card and its output goes to the backplane coax connector and boosts the signal level as high as 10W max continuously depending on the software setting. A redundant PA can be plugged into the chassis to give up to 20 W output. There is a transformer, T1, on the backplane that combines the 2 PAs, when used. If one of the 2 PAs fails, the power level drops by 6 dB. So if set for 20 W it would drop to 5 W. The PA contains 2 transmit meters, a Forward Power level meter and a Reflected Power percentage meter. The levels are displayed on the front display as well as the home web page. The forward power level meter only looks at power going out to the coax. It is in a control loop with the Transceiver and automatically adjusts the output power to the correct level when the UPLC-IITM's output level is calibrated. The reflected power meter tracks the TX frequency and only looks at any power coming back into the output of the PA which falls within the narrowband (less than 500 Hz away from the transmit frequency) of the frequency selective circuit of this meter. So this meter reads accurately in the presence of high level interfering signals from transmitters elsewhere on the power line. The PA module is hotswappable.

#### Customer interface points:

 PA OK LED (LE1) – Indicates the status of the Power Amp (PA). It monitors that onboard dc voltages are within specifications

Description	Part Number
Power Amp (PA) Module with Freq. Selectivity	CU20-PA1MN-002

and that the PA is actually amplifying the signal as it should. When one of these 2 parameters is bad, the LED goes off.

- PA IN DC (TP11) A convenient test point for measuring input signal level to the PA from the Transmitter. The level is a dc voltage that is proportional to input signal strength. Normal level is 0.35Vdc for 1W transmit and 1.0Vdc for 10W transmit. Level must be measured between TP11 and the chassis itself as a ground reference.
- FREQ SEL Jumper (JMP1/2) Normally set to the ON position for UPLC-II<sup>TM</sup> but if the power amp is put into a UPLC<sup>TM</sup> this jumper has to be set to the OFF position. It enables the frequency selectivity feature of the reflected power meter in a UPLC-II<sup>TM</sup>.

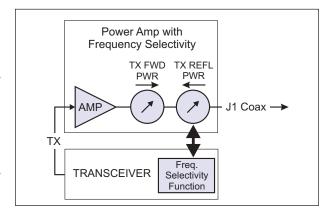


Figure 2-6. Power Amp Block Diagram

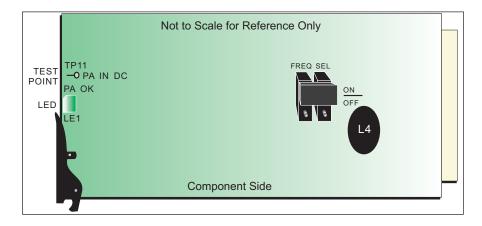


Figure 2–5. Power Amp Jumper Location



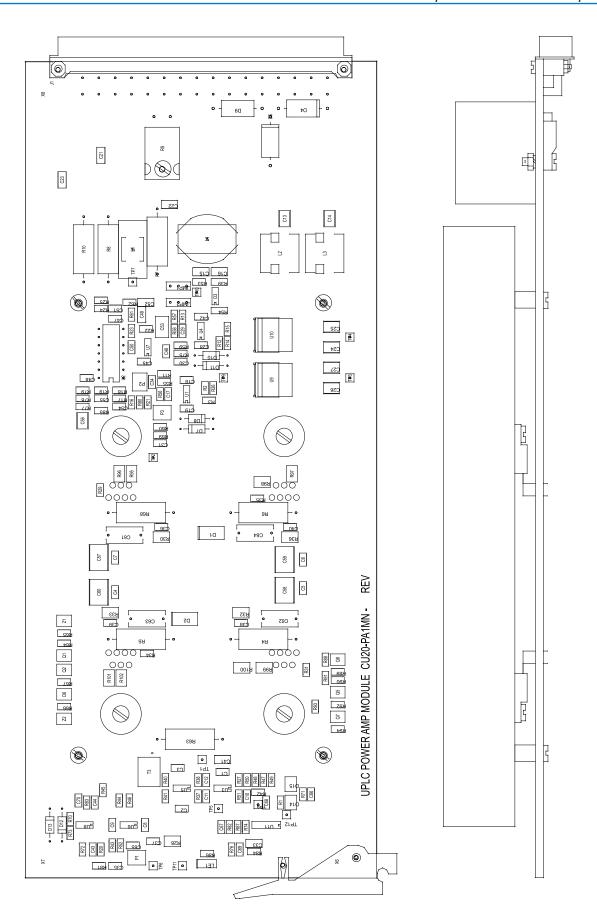


Figure 2–7. Power Amp Module

February 2018 Page 2–13



Description	Part Number	
Display Module	CU20-DP1MN-001	

#### 2.4.3 Display Module

#### **Description**

The Display Module serves 2 purposes:

- 1) It displays the UPLC-II<sup>TM</sup> status, settings menu and test menu for front keypad access.
- 2) It interconnects the Transceiver module to the front door keypad/LEDs and to the I/O module.

Four screws hold it in place on its four corners and have to be removed when accessing the Transceiver or I/O boards. Care should be taken to not bump the glass display against a hard surface accidentally causing it to crack.

It has larger guide pins in addition to 2 DIN connectors that connect it to the Transceiver and I/O boards. These guide pins allow it to align correctly when connecting to the two horizontal boards behind it. Firm pressure should be applied to the middle of the board when plugging it back in.

A permanently affixed ribbon cable connects it to the mating connector on the front door auxiliary board. This connector has 2 latches on its sides for unplugging or plugging in the ribbon cable.

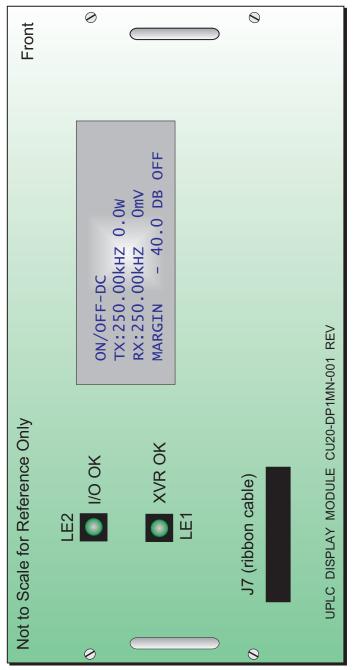
Customer interface points:

- XVR OK LED Indicates Transceiver board is functioning properly.
- I/O OK LED Indicates I/O board is functioning properly.
- J1 connector (on back side) Used only for UPLC™ retrofits when adding a front Ethernet port option. Requires a ribbon cable assy P/N 1088-256 to be plugged into it for interconnecting to a new Ethernet daughter board on the existing old Transceiver board CU50-XVRMN rev 8 or lower.

#### NOTE:

During troubleshooting and to view LEDs on internal boards behind the display board, the UPLC-II™ may be operated without a display board plugged in. But the display board should never be connected or disconnected while powered on.





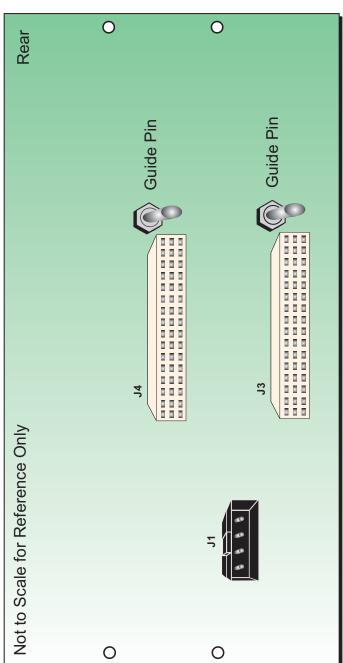


Figure 2-8. Display Board, Rear/Inside & Front/Outside Views



Description	Part Number
Input/Output (I/O) Module	CU20-IO1MN-001

#### 2.4.4 Input/Output (I/O) Module

#### **Description:**

The Input/Output (I/O) module interfaces the Transceiver module to all the inputs and outputs on the backplane terminal blocks. All inputs and outputs are non-polarity sensitive. It has several hardware jumpers that require setting before being put into service. All jumpers are "ganged" type jumpers that sense the jumper setting and report it back to the Transceiver processor for displaying status on the web pages. The I/O module mounts in the top right horizontal slot of the chassis behind the front display board. The corresponding I/O OK LED that gives status of this module is located on the display board.

# **Customer interface points: Inputs (5 Standard)**

There are 5 current-limited inputs that draw 5 mA maximum.

• INPUT 1 – INPUT 5 Voltage Selection jumpers – Choose between 15V, 48V, 125V, and 250V. These are high voltage threshold inputs that require at least greater than half high station battery voltage to operate as long as the correct voltage is chosen.

#### **Outputs (10 Standard Low Level)**

There are 7 standard low level solid state outputs.

 LL01-LL07 Current Selection jumpers – Choose between 0.1A and 1.0A continuous. Use 0.1A for driving low current loads such as microprocessor relays, and use 1.0A for devices that draw up to 1A continuous. The 0.1A setting exists because there is a very low leakage current when the output is turned off for the 1.0A setting, especially at 250V input, which could cause a low current device to potentially misoperate. The 1.0A output should also be used when having to interrupt currents that are over 0.25A, as it can interrupt up to 1A currents at 250Vdc, unlike all the other UPLC-II<sup>TM</sup> outputs which have lower current interrupting capability.

There are 3 standard low level EM contact outputs normally used for low current alarm circuits. Typically, these are used for fail-safe alarming where loss of DC power causes the same alarm also.

 LL08-LL10 Contact Selection jumpers – Choose between N.O./N.C. (Normally Open/Normally Closed)

#### **Outputs (4 Extra Optional Trip Duty)**

These are able to make and carry up to 30A for 200 msec, which is long enough to trip a breaker directly.

 TD01-TD04 Contact Selection jumpers – Choose between N.O./N.C. (Normally Open/Normally Closed)

#### NOTE:

See the Specifications Tables at the beginning of this chapter for full ratings of inputs and outputs.



#### Rear Edge (Plugs into Backplane)

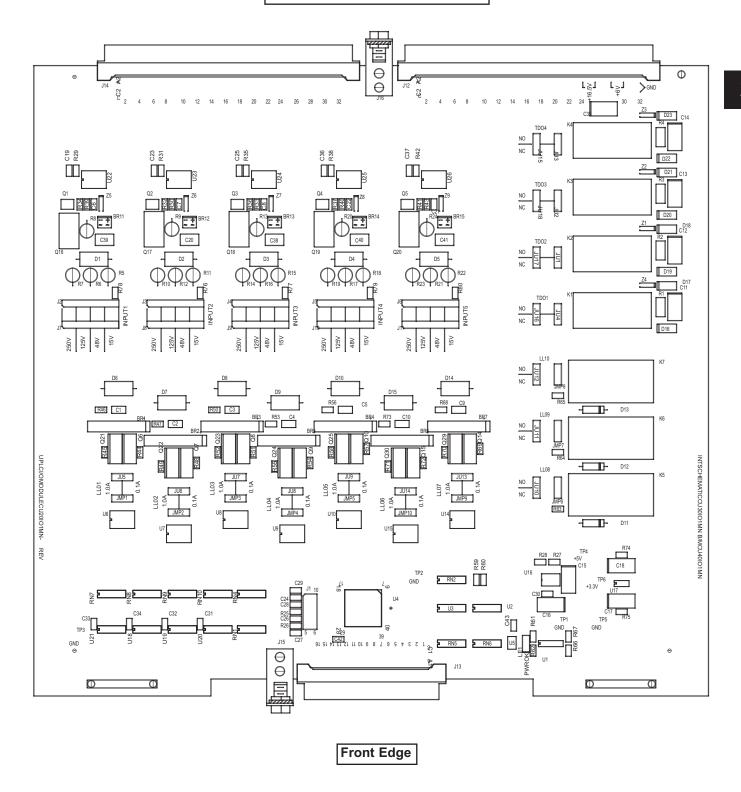


Figure 2–9. I/O Module Component & Jumper Locations (Rev. 9)



Description	Part Number
Transceiver Module	CU20-XVRMN-001

#### 2.4.5 Transceiver Module

#### **Description:**

The Transceiver (XCVR) module is the brains of the UPLC-II<sup>TM</sup> containing both the transmitter and receiver as well as the processing circuitry (Power PC chip), flash memory, NOVRAM, IRIG-B timing, etc. All firmware, settings, SOEs, Catalog/Model number and IP address/MAC address are stored in this module. It mounts in the bottom right horizontal slot of the chassis behind the front display board. The corresponding XVR OK LED that gives status of this module is located on the display board itself. Remember to remove any rear Ethernet connections connected to the optional Ethernet daughter board before removing the Transceiver module from the chassis.

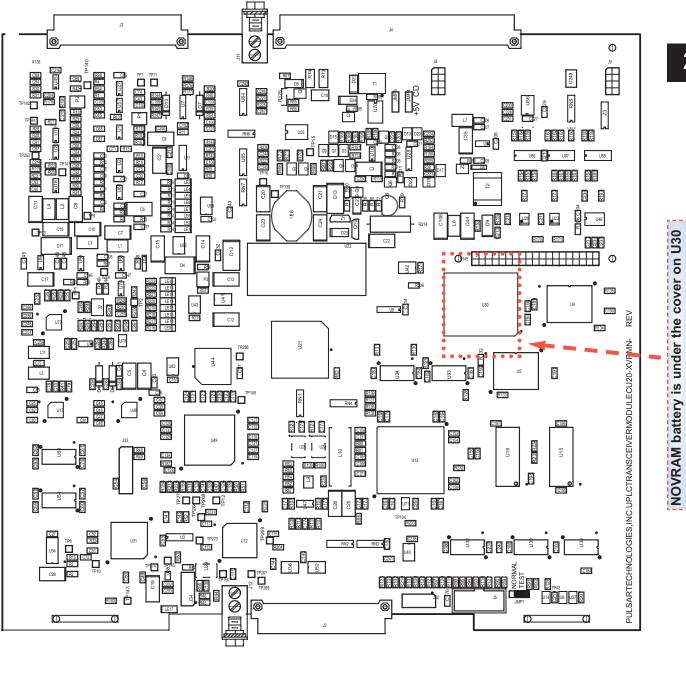
#### **Customer interface points:**

- Battery for NOVRAM (U30) Normal life is well over 20 years. If you receive a "Battery Failure" event in the SOEs, the NOVRAM battery has expired. It is a Dallas Semiconductor DS9034PCX and is located under the cover on U30. To access use a small flathead screwdriver in the slot on the plastic cover and gently pry the cover off. Replace the battery and snap the cover back on. There are no other user-serviceable items on the board.
- Other LEDs, jumpers, and headers on the board are for factory use only. No jumper positions should be changed.



Rear Edge (Plugs into Backplane)

Jumpers for Factory Use Only



Front Edge

Figure 2–10. Transceiver Component Locations



Description	Part Number	Digit 6 of UPLC-II Cat. No.
Ethernet Module dual RJ-45 electrical	CU20-XVRA5-001	М
Ethernet Module dual ST Fiber	CU20-XVRA6-001	Р
Ethernet Module dual 1 RJ-45 elec, 1 ST Fiber	CU20-XVRA7-001	R

#### 2.4.6 Ethernet Module

#### Description

The Ethernet module is an optional daughter board that plugs onto the Transceiver board and is attached by 3 screws. If this option is not purchased, then none of the Ethernet ports will be available on the UPLC-II<sup>TM</sup>, although the front port will physically be present, it will not work. The Ethernet board supports 3 Ethernet ports, two on the rear which are part of this board, and one on the front panel. The front port is completely isolated from the 2 rear ports and is intended solely for PC interface. The rear Ethernet ports can be used for PC interface, connection to an Ethernet network, or for other features such as DNP3 or IEC61850 communication.

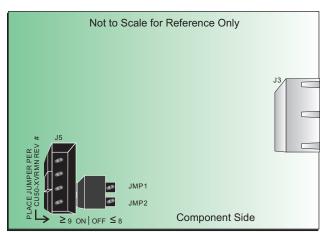
There are 2 modes of operation for the 2 rear ports. This mode of operation is selected on the ADMIN web page of the UPLC-II<sup>TM</sup>. They can operate:

- One as a standby/redundant port for the other. (Default Mode)
- Like Ethernet switch ports allowing daisy chaining of other UPLC<sup>TM</sup>/UPLC-II<sup>TM</sup>s or Ethernet connected devices with itself.

#### **Customer interface points:**

Connector (J5) – Only used when placing this board on older style Transceiver boards in UPLCs to add front port Ethernet when doing hardware upgrades. Requires a ribbon cable assembly, part # 1088-256, to be plugged into connector J5 of this Ethernet board with the other end plugged into connector J1 on the back of the front display board. The UPLC-II<sup>TM</sup> does not need this cable.

- Jumper (JMP1/2) Always set to the ON (A) position for UPLC-II<sup>TM</sup>s but, if putting this board into a UPLC<sup>TM</sup> with an older Transceiver PC board CU50-XVRMN rev 8 or lower, this jumper has to be set to the OFF (B) position. It works in conjunction with connector J5 above when adding a front Ethernet port to an existing older UPLC<sup>TM</sup> allowing the older Transceiver board to still be used.
- Ethernet connectors (J3 RJ45 or U2/U4-Fiber ST) - Located on rear of board and sticks out through a rectangular cutout in the back of chassis backplane.



(A | B on older boards)

Figure 2–11. Ethernet Module Connectors/Jumpers



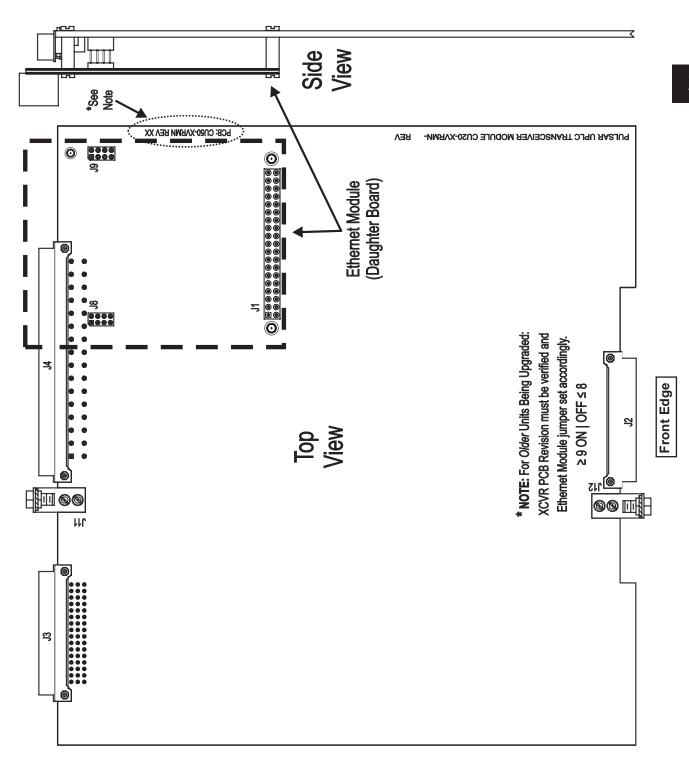
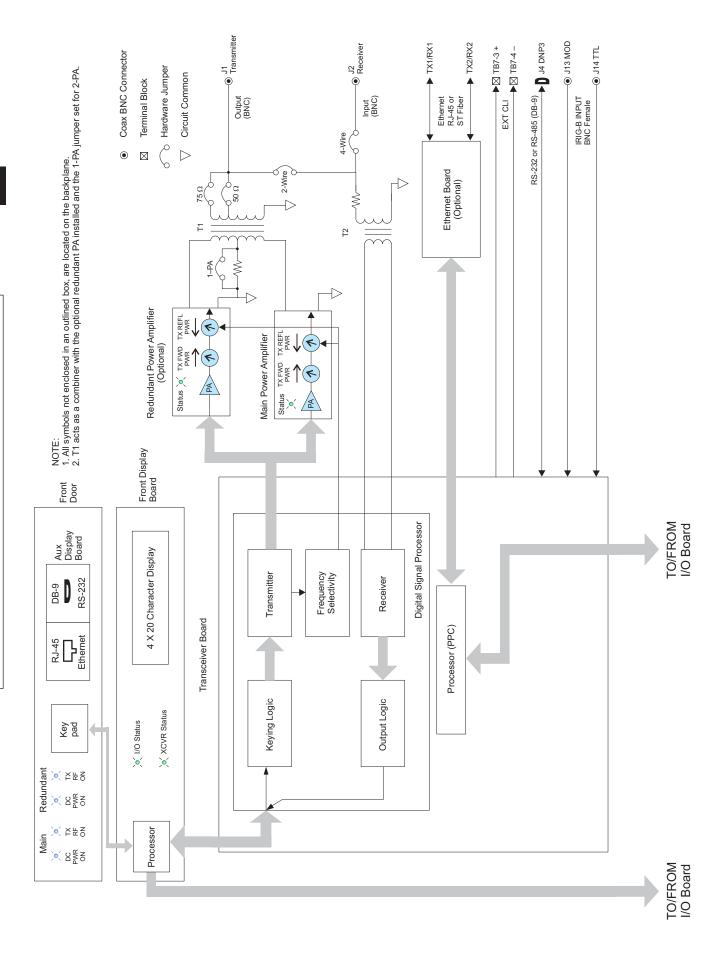
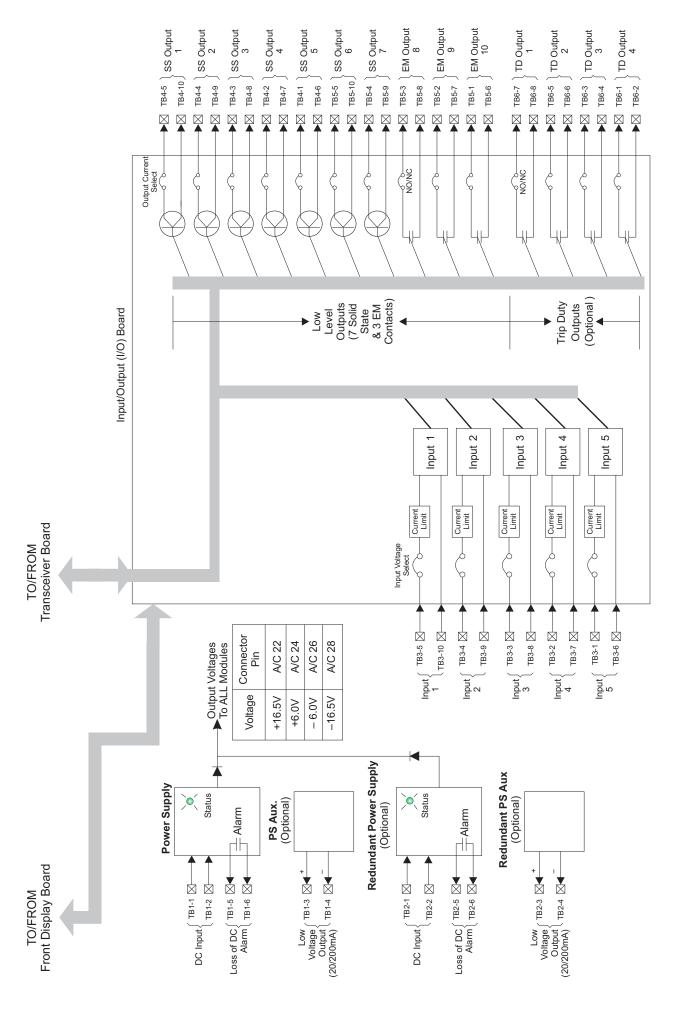


Figure 2-12. Transceiver Module, Ethernet Module Location





February 2018 Page 2–23



# 2.5 UPLC-II™ Functional Description

The UPLC-II™ was designed to be universal with one unit performing both of the primary modes of operation.

- ON/OFF Mode = amplitude shift keying.
- FSK Mode = frequency shift Keying.

The UPLC-II<sup>TM</sup> has a transmitter section and a receiver section on the transceiver board. If the unit is purchased as a receive-only system, then only the receiver logic and associated information applies and the Power Amp module is not present. The 2-page block diagram (Fig. 2–13a/b) illustrates the interconnection of the UPLC-II<sup>TM</sup> hardware.

The transmitter is made up of the keying inputs (on the I/O board), the keying input logic (in the digital signal processing (DSP) firmware on the transceiver board) the power amplifier(s) board and the RF interface circuit (on the motherboard). The state of the keying inputs will determine what output is produced, both frequency and RF power level. For example, an ON/OFF system will be turned on when the START input is asserted. The signal produced will be at the programmed frequency and at the high-level power output. In an FSK system, with no keying input asserted, the GUARD frequency is produced at the low-level power output. When one or more of the keying inputs are asserted, then the appropriate signal will be produced. The following keying tables describe the different combinations available.

The receiver is made up of the RF interface circuit (on the motherboard), input filters, ON/OFF level detector / FSK discriminator, the output logic described herein (in the DSP on the transceiver board), and the associated outputs (on the I/O board). The incoming RF signal is level detected or frequency discriminated according to the programming, and based on the signal received, produces the appropriate output. For ON/OFF systems, the outputs are simple – if the signal is detected (i.e. – the RF signal is the desired frequency and is above the minimum sensitivity), then the receiver output is produced. For FSK systems, it is more complicated and there are several logic choices available.

The FSK logic diagrams at the end of this chapter describe the choices available.

Besides the main function of the UPLC-II<sup>TM</sup> as a Power-Line carrier channel, there are several other ancillary functions and optional features available.

The processor on the transceiver board handles many of the "housekeeping" functions. It handles the web pages that are served up when connected to a personal computer (pc). The web pages allow you to set up user accounts, make settings, and download settings in either an XML file or a report file. The XML file is used for re-loading settings on a UPLC-II<sup>TM</sup>. Upgrading the firmware and TX/RX calibration are also done via the web pages.

The Sequence of Events (SOEs) reside in the processor on the transceiver board. These track events that occur in the UPLC-II<sup>TM</sup>. They are viewed via the web pages and can be downloaded into a CSV (comma separated values) file format. The I/O programming allows for up to three external events to be fed into the UPLC-II<sup>TM</sup> SOEs. For example, you can monitor the breaker auxiliary contact position in relationship to keying inputs or receiver outputs. SOEs are stored in non-volatile-random-access memory (NOVRAM) so that they are maintained even when the unit is powered down.

The settings files also reside in the processor on the transceiver board and are stored in NOVRAM. There are three sets of the file stored for redundancy purposes.

Status indication is provided by the four line by 20-character display on the front panel. The basic programming - Channel type, function, TX/RX frequencies/levels, and RX margin are displayed. It also has a 16-button keypad that allows for minor setting changes, testing of the PLC channel, calibration of the transmitter and receiver, and configuration of the Internet Protocol functions. The display turns off automatically 30 minutes after input from the user has stopped. To turn it back on requires pressing the DISP ON button or any other button on the keypad. There is also a front panel ethernet port



(RJ-45) and serial port (DB9 connector) to connect a pc to allow settings, etc through web pages.

Also on the front panel are four blue indicator lights that indicate if the main and optional redundant power supplies and power amplifiers are on.

Each printed circuit board that comprises the UPLC-II<sup>TM</sup> has a green status LED associated with it. The power supplies and power amplifiers have an LED on the front edge of the printed circuit board that is visible with the front cover down. The Transceiver and Input/Output board have LEDs that are located on the front panel display board, visible with the front cover down. The Ethernet board has green and yellow indicating lights visible from the rear of the unit. If any of these lights are not illuminated, it indicates a problem with that board. There are also 4-character alarm indications on the front panel display when an alarm occurs.

In addition to the standard testing from the front panel, there is also available as a purchased option, integrated testing facilities. When used as an ON/OFF PLC, the channel status is not known until called upon to perform its operation, so therefore could have failed without warning. The UPLC-II<sup>TM</sup> has an option for performing automatic checkback tests. Please see chapter 6 for details. When used as an FSK, sometimes it is desired to perform a "shift to trip" test from end to end. The trip test feature is available when purchased. Please see chapter 6 for details.

Network protocols are available to allow device-to-device communications. These include DNP3.0 and IEC61850. Please see chapter 7.

### 2.5.1 Keying Input Logic

Depending upon the channel type and function set, different keying logic is selected. Following are tables, which describe the functionality of the keying logic for each channel type and function combination.

### **ON/OFF Channels**

ON/OFF channels typically are not keyed normally and are keyed on to block tripping for an external fault. A choice is made to give priority to either the stop input or the start input should they both be present at the same time. Typical Directional Comparison and Phase Comparison relaying systems utilize a stop priority; giving the relay system priority to trip vs to not trip, thereby making the system dependable.

Table 2–12 applies to the majority of modern relay systems in service that use the ON/OFF type of PLC channels.

Relay Systems that use the older-style electromechanical relays such as ABB/Westinghouse's KA-4/KD-10 series of relays have one lead that serves the function of both start and stop. Table 2–13 would apply in this situation. Please see chapter 3 for details on how to connect this type of system. The "common start/stop input" box must be checked in order for this table to be applied.

### **FSK Channels**

FSK channel functions are used for Direct Transfer Tripping Systems or Line Relay Systems. If the DTT/POTT or the Unblocking-2 F selection is set for the function, then Table 2–14 will apply. When the FSK 3-frequency channel is used for both a DTT and Line relaying channel, Table 2–15 will apply. If both the DTT Key and LR key are present, the DTT key will have precedence. If using the FSK channel for Phase Comparison Relaying systems, Table 2–16 will apply. If using the FSK channel for 2 protection channels A & B, where both channels are allowed to trip simultaneously with a fourth frequency shift (unlike the 3-frequency), then Table 2-17 applies.



Table 2–12. Channel: ON/OFF, function: Directional or Phase Comparison Relaying w/Stop Priority

START	STOP	LOW LEVEL KEY	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Transmitter off
Not Activated	Not Activated	Activated	Send Low Output Power
Not Activated	Activated	Not Activated	Transmitter off
Not Activated	Activated	Activated	Transmitter off
Activated	Not Activated	Not Activated	Send High Output Power
Activated	Not Activated	Activated	Send High Output Power
Activated	Activated	Not Activated	Transmitter off
Activated	Activated	Activated	Transmitter off

Table 2–13. Channel: ON/OFF, function: Directional Comparison Relaying with KA-4 type EM Relaying System

START	STOP	LOW LEVEL KEY	CB TEST INITIATE	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Not Activated	Input States not Likely to Exist
Not Activated	Not Activated	Not Activated	Activated	Input States not Likely to Exist
Not Activated	Not Activated	Activated	Not Activated	Input States not Likely to Exist
Not Activated	Not Activated	Activated	Activated	Input States not Likely to Exist
Not Activated	Activated	Not Activated	Not Activated	TX Off, CB Not Allowed
Not Activated	Activated	Not Activated	Activated	TX Off, CB Not Allowed
Not Activated	Activated	Activated	Not Activated	TX Off, CB Not Allowed
Not Activated	Activated	Activated	Activated	TX Off, CB Not Allowed
Activated	Not Activated	Not Activated	Not Activated	Send High Output Power, CB Not Allowed
Activated	Not Activated	Not Activated	Activated	Send High Output Power, CB Not Allowed
Activated	Not Activated	Activated	Not Activated	Send High Output Power, CB Not Allowed
Activated	Not Activated	Activated	Activated	Send High Output Power, CB Not Allowed
Activated	Activated	Not Activated	Not Activated	Transmitter Off
Activated	Activated	Not Activated	Activated	Transmitter Off, CB Allowed
Activated	Activated	Activated	Not Activated	Send Low Level Output, CB Not Allowed
Activated	Activated	Activated	Activated	Send Low Level Output, CB Not Allowed

CB = Checkback



Table 2–14. Channel: FSK, function: 2 Frequency Directional Comparison Relaying

TRIP or UB Key	TX POWER OFF	POWER BOOST (52B)	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Send HF at Low Level Output
Not Activated	Not Activated	Activated	Send HF at High Level Output
Not Activated	Activated	Not Activated	Transmitter Output Power off
Not Activated	Activated	Activated	Transmitter Output Power off
Activated	Not Activated	Not Activated	Send LF at High Level Output
Activated	Not Activated	Activated	Send LF at High Level Output
Activated	Activated	Not Activated	Transmitter Output Power Off
Activated	Activated	Activated	Transmitter Output Power Off

Table 2–15. Channel: FSK, function: 3 Frequency, Directional Comparison Relaying

DTT KEY	LR KEY	TX POWER OFF	POWER BOOST (52B)	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Not Activated	Send CF at Low Power Output
Not Activated	Not Activated	Not Activated	Activated	Send CF at High Power Output
Not Activated	Not Activated	Activated	Not Activated	Transmitter Output Power Off
Not Activated	Not Activated	Activated	Activated	Transmitter Output Power Off
Not Activated	Activated	Not Activated	Not Activated	Send HF at High Power Output
Not Activated	Activated	Not Activated	Activated	Send HF at High Power Output
Not Activated	Activated	Activated	Not Activated	Transmitter Output Power Off
Not Activated	Activated	Activated	Activated	Transmitter Output Power Off
Activated	Not Activated	Not Activated	Not Activated	Send LF at High Power Output
Activated	Not Activated	Not Activated	Activated	Send LF at High Power Output
Activated	Not Activated	Activated	Not Activated	Transmitter Output Power Off
Activated	Not Activated	Activated	Activated	Transmitter Output Power Off
Activated	Activated	Not Activated	Not Activated	Send LF at High Power Output
Activated	Activated	Not Activated	Activated	Send LF at High Power Output
Activated	Activated	Activated	Not Activated	Transmitter Output Power Off
Activated	Activated	Activated	Activated	Transmitter Output Power Off



Table 2-16. Channel: FSK, Function: 2 Frequency Phase Comparison Relaying

PC Key	TX POWER OFF	POWER BOOST 52B	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Send HF at Low Power Output
Not Activated	Not Activated	Activated	Send HF at High Power Output
Not Activated	Activated	Not Activated	Transmitter Output Power off
Not Activated	Activated	Activated	Transmitter Output Power off
Activated	Not Activated	Not Activated	Send LF at Low Power Output
Activated	Not Activated	Activated	Send LF at High Power Output
Activated	Activated	Not Activated	Transmitter Output Power Off
Activated	Activated	Activated	Transmitter Output Power Off

Table 2–17. Channel: FSK, Function: 4 Frequency Directional Comparison Relaying

TRIP A KEY	TRIP B KEY	TX POWER OFF	TX OUTPUT CONDITION FOR THIS KEYING INPUT STATE
Not Activated	Not Activated	Not Activated	Send F3 (Guard) at Low Level Output
Not Activated	Not Activated	Not Activated	Send F3 (Guard) at Low Level Output
Not Activated	Not Activated	Activated	Transmitter Output Power Off
Not Activated	Not Activated	Activated	Transmitter Output Power Off
Not Activated	Activated	Not Activated	Send F2 (Trip B) at High Level Output
Not Activated	Activated	Not Activated	Send F2 (Trip B) at High Level Output
Not Activated	Activated	Activated	Transmitter Output Power Off
Not Activated	Activated	Activated	Transmitter Output Power Off
Activated	Not Activated	Not Activated	Send F4 (Trip A) at High Level Output
Activated	Not Activated	Not Activated	Send F4 (Trip A) at High Level Output
Activated	Not Activated	Activated	Transmitter Output Power Off
Activated	Not Activated	Activated	Transmitter Output Power Off
Activated	Activated	Not Activated	Send F1 (Trip A & B) at High Level Output
Activated	Activated	Not Activated	Send F1 (Trip A & B) at High Level Output
Activated	Activated	Activated	Transmitter Output Power Off
Activated	Activated	Activated	Transmitter Output Power Off



### 2.5.2 Receiver Output Logic

### 2.5.2.1 ON/OFF Receiver Logic/Timers

There is only one logic setting affecting the receiver in an ON/OFF system and that is a blocking output hold timer. Typically it is set to disabled (0 ms) and caution should be taken when using it so that protective relaying logic such as transient blocking is not affected.

### 2.5.2.2 FSK Receiver Output Logic

### 2-Frequency Directional Comparison Logic

Figure 2–14 illustrates this logic. The logic can be configured for a typical Direct Transfer Trip or Directional Comparison Unblock System. To provide the utmost security, this logic provides for 120ms of guard before trip logic. It requires that after loss of signal, there must be at least 120ms of guard before the system is allowed to trip. This may be disabled or overridden according to system requirements. Details follow. There is also a 120ms trip after guard requirement that requires within 120 ms of losing guard that trip is received, otherwise the channel locks out from tripping.

Hold timers are available for both the trip and guard outputs that can be set from 1 to 100 ms in 1 ms increment or be disabled (0 ms). These timers are on the output side of the logic and therefore only affect the solid state or electromechanical outputs. They have no affect on the functionality of the internal logic.

The pre-trip timer allows for higher security by delaying the trip output by the time set. It is settable from 0 to 30 ms in 1 ms increments. Unblock functions will typically be 2 to 8 ms but DTT functions will typically be on the order of 20 or 30 ms for pre-trip time. This pre-trip time delay is critical to providing security against noise causing a false trip and for every msec added the security increases exponentially.

The logic also provides for line protection of the transmission line when the remote end's breaker is open. Upon receiving a trip signal from the other end for longer than 1000 ms, indicating an open breaker, the logic disables the guard before trip requirement such that if the channel is lost and returns in the trip state, the line relay system will be allowed to trip for a fault. To allow for this scenario,

the guard before trip should be set for "override". After guard is restored, the logic is reset after 200 ms. Typical line relaying or DTT systems do not disable guard before trip logic. Unblock logic is provided in the UPLC-IITM logic to force a trip on loss of channel. If a fault causes a loss of channel, there is a window setting between 1 and 500 ms that will produce a trip output. A setting of 0 ms will disable this feature. After this time, the channel is locked out from tripping until it receives 120ms of guard. The assertion of the trip output for unblock can be delayed by 1 to 100 ms if desired, with a setting of 0 ms disabling this delay. Typical permissive overreaching transfer trip systems over Power-Line Carrier take advantage of the Unblock Logic and are Directional Comparison Unblock systems. A checkback trip output (meaning trip frequency received) is provided for testing purposes. The checkback trip will always assert anytime a trip is asserted by the logic. However, if a trip frequency is received after a loss of channel (without guard return), then only a checkback trip is asserted, and not an actual trip output.

### 3-Frequency Directional Comparison Logic

Figure 2–15 illustrates this logic. This logic is similar to the 2-frequency logic except with the addition of logic to handle the Direct Transfer Trip logic separately, in addition to providing for a Directional Comparison Unblock System. The Guard Before Trip and Trip After Guard Logic are duplicated for the DTT portion as well as the Trip hold and Guard hold timers. Note that when the 3-frequency system goes to an Unblock trip, the DTT Guard does not drop out but the Unblock Guard does. Likewise, on a DTT Trip, the Unblock Guard does not dropout but the DTT Guard does.

### 4-Frequency Directional Comparison Logic

Figure 2–16 illustrates this logic. This logic is like having two independent sets of the 2-Frequency logic. In the 2-Frequency logic there are two inputs to the logic, Guard and Trip. In the 4-Frequency logic, there are four inputs (frequencies) to the logic, Guard (F3), CMD A Trip (F4), CMD B Trip (F2), and CMD A&B Trip (F1). Like in the 3-Frequency logic, a receipt of CMD A Trip does not cause the guard for the CMD B to drop out.

Functional block diagrams for these configurations can be found at the end of this chapter.



### **2.5.2.3 FSK Timers**

Following are explanations of all the timers available on the UPLC-II<sup>TM</sup>. Those not available on certain functions are so noted.

### **Pre-Trip Timer**

The Pre-Trip Timer does not allow tripping until the trip signal has been present for the time set. This timer is settable from 0 to 30 ms in 1ms increments. A typical application of this timer in Direct Transfer Trip systems is to set it for the maximum delay possible, 20 to 30 ms. Limitations on the critical clearing time of the power system will have a direct impact on this setting. In Directional Comparison/POTT systems, we recommend a minimum setting of 2 ms with 4 ms being typical.

### **Trip Hold Timer**

The Trip Hold Timer lets you stretch the trip output. You can set it for 0 to 100 ms or disable (0 ms) it. We recommend that you use the disabled setting in the Unblock/POTT to avoid problems with transient blocking.

### **Guard Hold Timer**

The Guard Hold Timer stretches the guard output by the amount you set. You can set it for 1 to 100ms or disable (0ms) it. The disabled setting is appropriate for most applications.

# Unblock Timer (not available on 2 Frequency DTT/POTT)

The Unblock Timer provides a trip output for the time set on loss of channel, which is defined as low level and loss of guard. You can set it for 1 to 500ms in 1 ms increment with 0 ms disabling the feature.

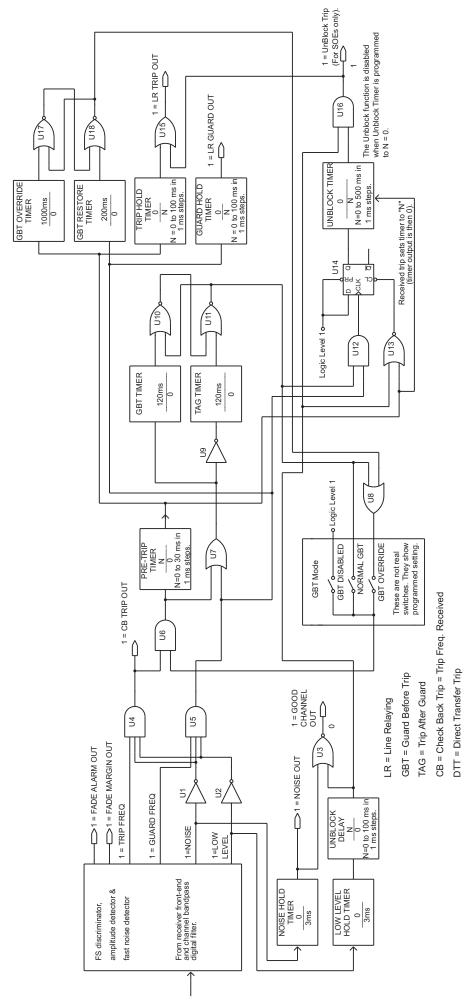
The normal setting is 150ms in the Unblock system and disabled for all other applications. This is what differentiates the Unblock system from the POTT.

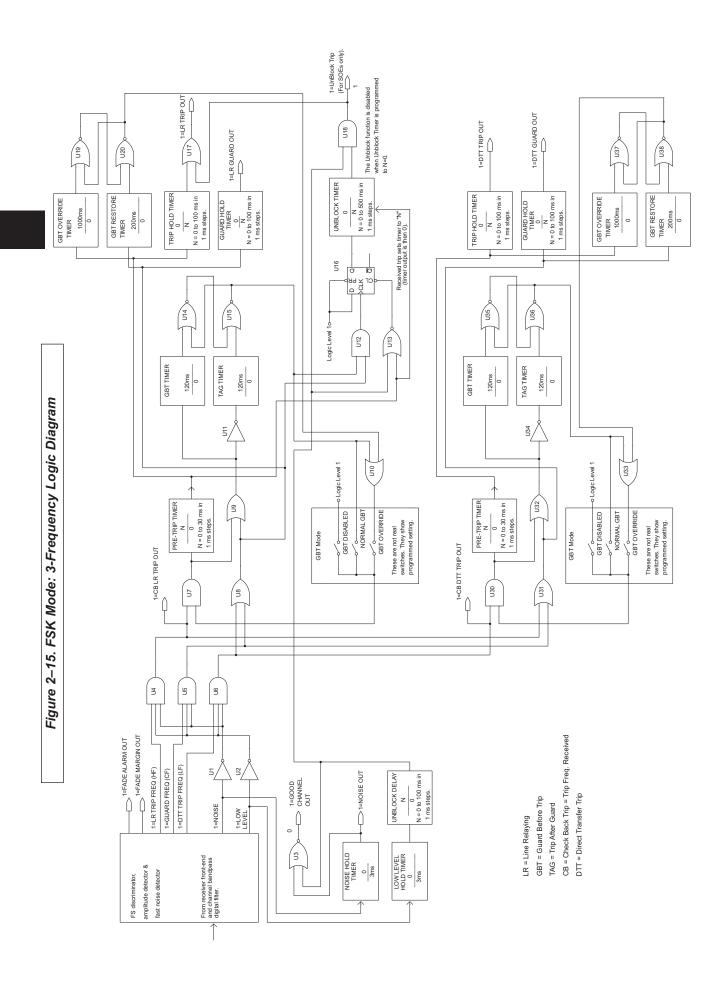
### **Guard before Trip**

With this function set to "on without override", the logic requires guard to be received for 120 ms before the system is allowed to trip. With it set to "on with override", the 120 ms guard return is required except where trip has been received for over 1,000 ms; if there is a loss of channel, then the guard is not required prior to tripping. Typically, you would use this where open breaker keying is required.

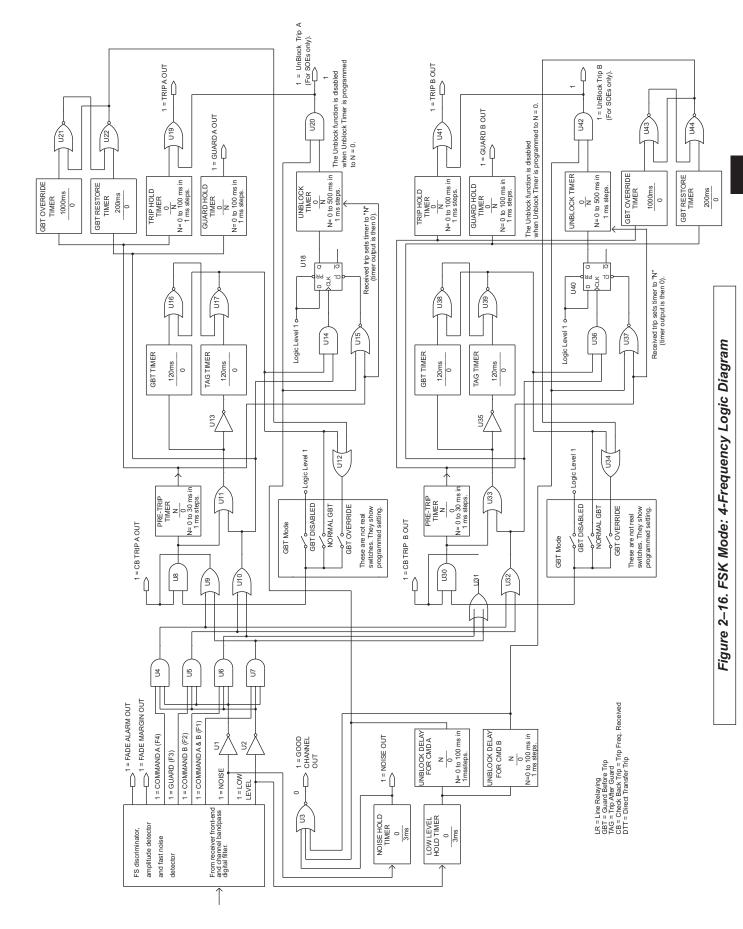
# Unblock Delay Timer (not available on 2 Frequency DTT/POTT)

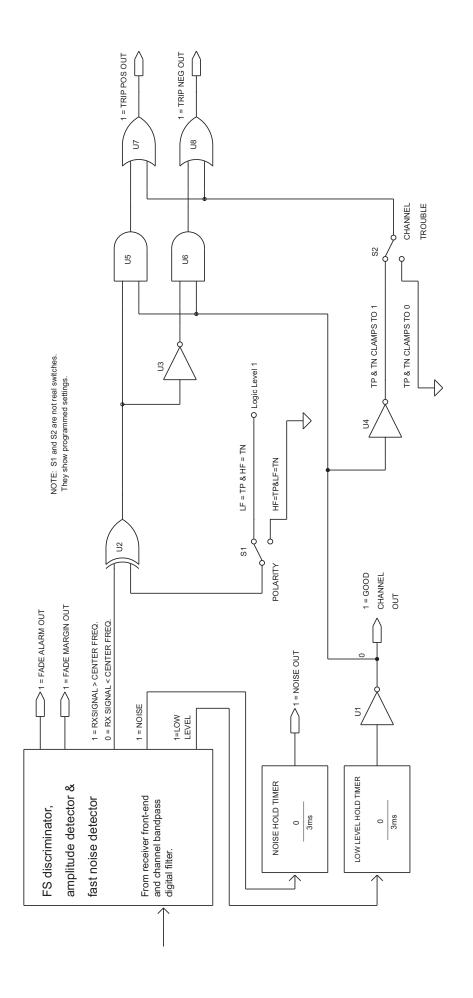
The Unblock Delay Timer delays the Unblock timer from initiating a trip output on loss of channel; it also delays the low level output. You can set it from 1 to 100 ms or disable it (0 ms).











## 3. Applications

# 3.1 ON/OFF Mode Protective Relay Applications

The UPLC-II<sup>TM</sup> carrier set is particularly suitable for the following types of protective relay systems:

- · Directional-Comparison Blocking
- · Phase-Comparison Blocking
- Phase-Comparison Blocking, Current Only
- Phase-Comparison Blocking, Distance Supervised

# 3.1.1 Directional-Comparison Blocking (DCB)

The basic elements for directional-comparison blocking (DCB) systems are shown in Figure 3-1a and Figure 3-1b. At each terminal, the phase and ground trip units (P) must be directional and set to overreach the remote terminal; that is, they must be set to operate for all internal faults. Nominal settings of the distance units are 120 to 150 percent of the line. The start units (S) must reach farther, or be set more sensitively, than the remote trip units. Thus S1 must be set more sensitively than P2 or reach farther behind bus G. Likewise, S2 must be set more sensitively than P1 or reach farther behind bus H. In any case, the S and P relays should be similar in type. If the trip unit (P) is a directional overcurrent ground relay, the start (S) ground relay should be a similar nondirectional overcurrent unit. The same principle applies for the phase relays.

When the UPLC-II<sup>TM</sup> is set for ON/OFF Power-Line Carrier applications, except for possible aux-

iliary functions, **no signal is normally transmitted**, since the S units operate only during fault conditions.

Operation of the directional-comparison scheme in Figure 3–1a, Figure 3–1b & Table 3–1 is shown for external and internal faults. Subscript 1 indicates relays at station G for breaker 1; subscript 2, relays at station H for breaker 2. (Figure 3–1c shows a solid-state logic version of Figure 3–1b.)

The schemes shown are still widely used for their flexibility and reliability. Since the communication channel is not required for tripping, internal faults that might short and interrupt the channel are not a problem. Over tripping will occur, however, if the channel fails or is not established for external faults within the reach of the trip fault detectors. Since the carrier transmitter is normally OFF, or non-transmitting, channel failure cannot be detected until the system is tested or until an external fault occurs. This limitation can be overcome by using the optional checkback test system with the UPLC-II<sup>TM</sup> carrier.

A sample schematic for the KA-4 relaying system is shown in Figure 3–5a. A sample schematic for a basic microprocessor relay system is shown in Figure 3–6. Figures 3–7a & 3–7b illustrate some GE EM relay schematics.

### 3.1.2 Phase-Comparison Blocking

Basic elements of the phase-comparison systems are shown in Figure 3–2. The system uses a composite sequence current network to provide a sin-



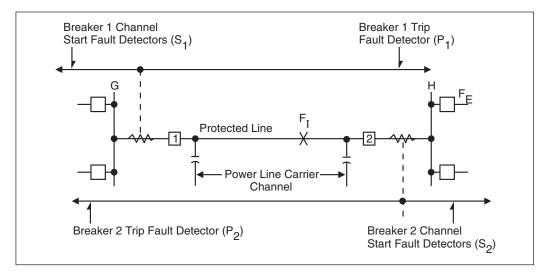


Figure 3-1a. - Basic Elements for directional-comparison blocking systems

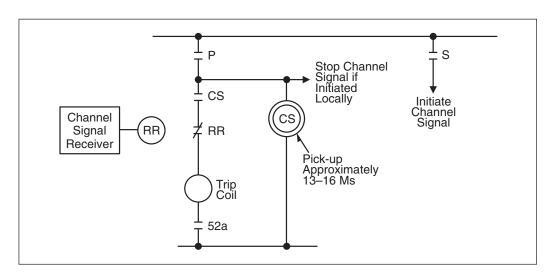


Figure 3–1b. – Contact Logic (per Terminal)

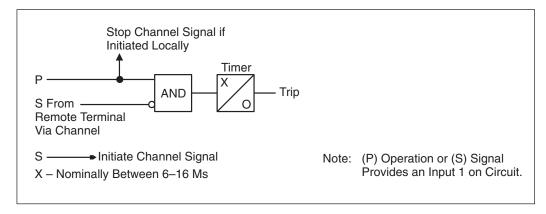


Figure 3-1c. - Solid State Logic (per Terminal)



Table 3-1. Directional Con	parison Blocking	Operations for	r External and	d Internal Faults

OPERATIO	ON FOR EXTERNAL AND INTERN	AL FAULTS
Type of Fault	Events at Station G	Events at Station H
External (F <sub>E</sub> )  For external faults, the CS unit or timer x/o assure that a blocking signal is established.	P <sub>1</sub> operates; S <sub>1</sub> does not see fault. Blocking signal received from station H. RR back contacts open (or 1 signal negates AND).  No trip.	S <sub>2</sub> operates to key transmitter. Blocking signal sent to station G. P <sub>2</sub> does not see fault. No trip.
Internal (F <sub>I</sub> )	P <sub>1</sub> operates; S <sub>1</sub> may or may not operate, but P <sub>1</sub> operation prevents transmission of a blocking signal.  Breaker 1 tripped.	P <sub>2</sub> operates, S <sub>2</sub> may or may not operate but P <sub>2</sub> operation prevents transmission of a blocking signal.  Breaker 2 tripped.

<sup>\*</sup> For external faults, the CS unit or timer x/o assure that a blocking signal is established.

gle-phase voltage output proportional to the positive, negative, and zero sequence current input. Sensitivity to different types of faults depends on the weighting factors or constants designed into the sequence current network. Adjustments to the network are provided.

A squaring amplifier in the controlling relay converts the single-phase voltage output to a square wave. The positive voltage portion corresponds to the positive half-cycle of the filter voltage wave and the zero portion corresponds to the negative half-cycle. The square wave is used to key the UPLC-II<sup>TM</sup>, transmitting to the remote terminal. The square wave from the remote terminal is compared to the local square wave, which has been delayed by an amount equal to the absolute channel delay time. This comparison of the local and remote square waves at each terminal determines whether a fault is internal or external.

Fault detectors are used to determine whether a fault has occurred and to supervise tripping. The fault detectors must be overreaching, i.e., set sensitively enough to operate for all internal phase and ground faults.

Because overcurrent fault detectors are normally used, voltage transformers are not required. Such a scheme is current only. Fault detectors should be set above maximum load, yet operate for all internal faults. Distance fault detectors, which require voltage transformers, are used on heavy-loaded or long lines when distance supervision is required.

### 3.1.2.1 Single Phase-Comparison Blocking, Current Only

In the current only system, the UPLC-II<sup>TM</sup> is used with two overcurrent fault detectors (FD<sub>1</sub> and FD<sub>2</sub>). FD<sub>1</sub>, the carrier start unit, is set more sensitively than FD<sub>2</sub> and permits the local square wave



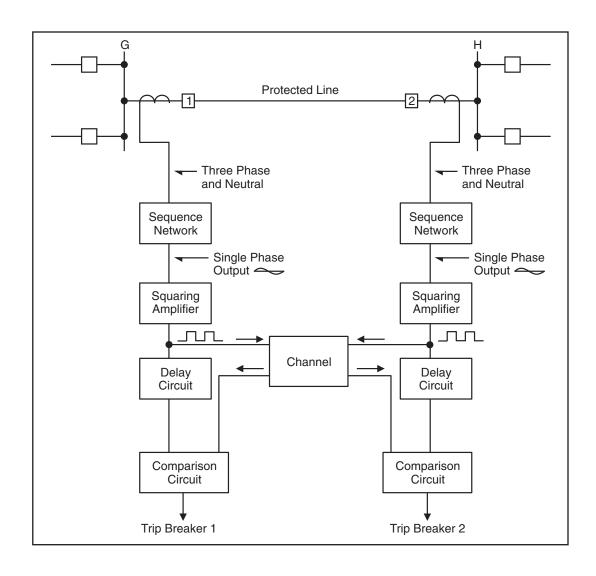


Figure 3-2. Phase-Comparison Blocking, Basic Elements



signal to key the "ON/OFF" carrier transmitter. FD<sub>2</sub>, set with a higher pickup than FD<sub>1</sub>, is used to arm the system for tripping. For transmission lines less than 100 miles long, the FD2 pickup is set at 125 percent of FD<sub>1</sub>. For lines longer than 100 miles, the FD<sub>2</sub> pickup is set at 200 percent of FD<sub>1</sub>. On a three-terminal line, FD2 is set at 250% of FD1, provided the line length between any two breakers is less than 100 miles. Phase-Comparison cannot occur until FD2 operates. The purpose of the two fault detectors is to coordinate the comparison of the local and remote square waves with the keying of the carrier square wave. The carrier must be started before the comparison is allowed to ensure that the remote square wave has been received.

The basic operation of the system is shown in Figure 3–3, at the end of this section. FD<sub>1</sub> and FD<sub>2</sub> at both terminals operate for an internal fault (F<sub>1</sub>). The square wave inputs to the AND from the local currents are essentially in phase with those transmitted via the channel from the remote terminal. The local square wave turns the carrier "ON" and "OFF" to provide the square wave receiver output for the remote terminal.

A flip flop is energized if the inputs to the AND continue for 4ms, providing a continuous trip output supervised by FD2 operation. The 4ms correspond to a phase angle difference of 90°, on a 60-Hz base, between the currents at the two terminals. The currents at the two ends of the line may be out of phase by up to 90° and still trip. This is a blocking system, since the receipt of a signal from the channel prevents tripping. The carrier signal, therefore, does not have to be transmitted through the internal fault. No received signal puts a "1" on the AND input. With the remote terminals open, this system provides sensitive instantaneous overcurrent protection for the entire line. As is characteristic of blocking systems, the channel is not required for tripping on internal faults.

For an external fault, such as FE in Figure 3–3, blocking is essentially continuous, since the remote wave input to the AND is out-of-phase with the local square wave. The secondary ct currents are essentially out-of-phase for an external fault. The

currents can, however, be in-phase by up to 90° on a 60-Hz base and still block.

### 3.1.2.2 Single Phase-Comparison Blocking, Distance-Supervised

A distance-supervised scheme should be used if the minimum internal three-phase fault current is less than twice the maximum load current. Twice maximum load current allows FDI to operate positively on the minimum internal three-phase fault, yet reset when an external fault is followed by a maximum load current flowing through the line. The UPLC-II<sup>TM</sup> operates in the same manner as when used with the current-only scheme, except for the fault detection and arming techniques.

Two sequence current networks and two distance relays supplement the two overcurrent fault detectors.

One sequence current network responds only to negative and zero sequence currents, detecting all phase-to-phase and ground faults (but not three-phase faults). The output of this adjustable network operates the conventional overcurrent FD1 and FD2 fault detectors. The two distance relays operate only for three-phase faults. Thus, FD2 provides the arming function for all unbalanced phase and ground faults, through the adjustable filter, and one of the distance relays (21P) provides arming for all three-phase faults.

The second and non-adjustable sequence current network operates through the squaring amplifier, providing the local square wave and the carrier-keyed square wave required for phase comparison. This signal is keyed by FD1 and the second distance relay (21S) to provide the carrier start functions. This second network responds to positive, negative, and zero sequence currents. Separate networks provide greater sensitivity: with phase-to-phase faults, for example, more than twice the sensitivity is gained.

The setting coordination of FD1 and FD2 overcurrent units is the same as for the current-only system. Settings for the two three-phase distance units are shown in Figure 3–4. Both 21S and 21P distance relays must be set to overreach both the local and remote terminal buses; 21S must be set further than 21P, as shown.



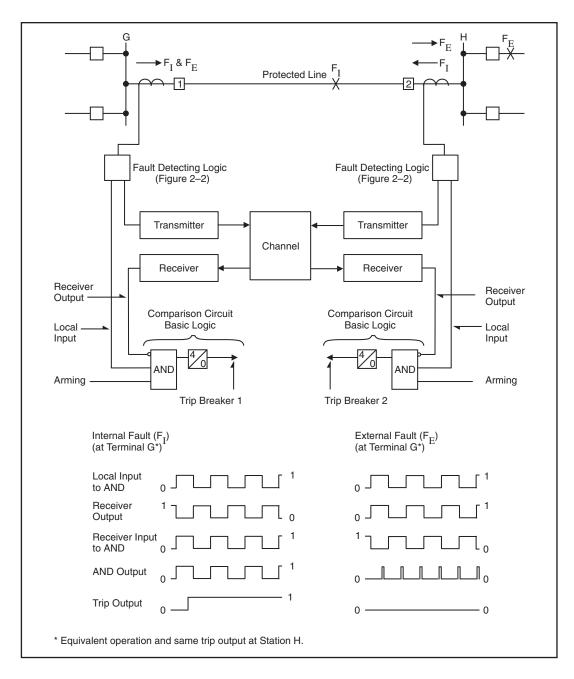


Figure 3–3.
Single Phase-Comparison Blocking, Current Only Operation



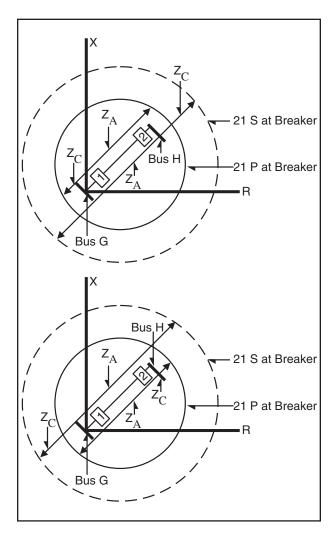


Figure 3–4. Single Phase-Comparison Blocking, Distance-Supervised Operation

# 3.2 ON/OFF Mode Special Considerations

### 3.2.1 Multi-Terminal Lines

Because the UPLC-IITM is ON/OFF modulated, only one frequency ( $f_{\rm C}$ ) is required for line protection. When applied to **three terminal lines**, phase cancellation will occur when two or more transmitters are keyed simultaneously at the same frequency. To prevent this, you should offset transmitters TX frequencies by  $\pm 100$  Hz. The three frequencies should be:

- f<sub>C</sub>
- f<sub>C</sub> 100 Hz
- $f_C + 100 \text{ Hz}$

The three receivers' frequencies should all be set to  $f_{\rm C}$ . If there is some scenario where both ends of a 2-terminal line could be keyed simultaneously, the same applies, but you only need to offset one transmitter by  $\pm 100$  Hz. The UPLC-II<sup>TM</sup> does not have an adjustable filter or hybrid attached to the output of the transmitter.

### 3.2.2 Phase Comparison

If you are using the UPLC-II<sup>TM</sup> in an ON/OFF application where no other Power-Line Carrier equipment is attached to the power line, then no other devices are required. However, in the application of Single Comparator Phase Comparison relaying, the UPLC-II<sup>TM</sup> is to be operated in the four-wire mode, with an external skewed hybrid between the transmitter and receiver.

### 3.2.3 Hybrids/Series LC Unit

If you are applying the carrier set with other transmitters, coupled through the same tuning equipment, you must apply a hybrid or a series LC unit to the transmitter output to isolate the other transmitters from the UPLC-IITM transmitter. This will avoid the problems of intermodulation distortion. We suggest that you use a hybrid if the frequency spacing between all transmitters is within the bandwidth of the hybrid (usually 6%). Check the manufacturers instructions for the actual spacing limitations of the hybrid you are using. If you cannot use a hybrid, then you may use a series LC unit to isolate the transmitters. In this case, the transmitters must have spacing such that the LC you are using will attenuate the external frequencies by at least 20 dB (if the other frequency is a 10 W transmitter), and 30 dB (if the other frequency is a 100 W transmitter).

# 3.2.4 Interfacing to Electromechanical Relays

You may need to make special connections/settings for connecting to the inputs of the UPLC-II<sup>TM</sup>, but you definitely will need to do this for connecting to its outputs.

Your connections should be per what is shown in Figures 3–5a,b,c.



For the relay's outputs to the UPLC-II<sup>TM</sup> inputs, if and only if you have one output from your relay that does both carrier start/stop instead of a separate carrier start and carrier stop output coming from your EM relay, then the following conditions must be met. (Otherwise you would ignore the following steps for your application and use the standard connections/settings for the UPLC-II<sup>TM</sup> carrier start/stop input.)

- 1. Both carrier start and carrier stop inputs (Input 1 & 2) need to have the physical jumper on the I/O module set for 48 V if you are using a 125 V station battery (use one position below the station battery voltage).
- On the web page settings, under the "LOGIC" tab you must have PRIORITY set for STOP and the box *enabled* for COM-MON START/STOP KEYING INPUT.
- 3. On the "INPUTS" tab both carrier start and carrier stop inputs must be set for application of voltage.

Figure 3–5b includes a table that shows the voltages that actually get applied to the UPLC-II<sup>TM</sup> with the KA4 common start/stop lead setup and how the UPLC-II<sup>TM</sup> inputs respond.

For the relay's inputs to the UPLC-II<sup>TM</sup> outputs, you need a power source with voltage less than station battery to drive the lower impedance of the EM relay coils, which normally only require either 20 or 200 mA. The UPLC-II<sup>TM</sup> has an optional auxiliary power supply output, which is a daughter board on the Power Supply module. This polarity sensitive output comes out on TB1 & TB2 on terminals 3(+) and 4(-). It needs to be connected in series with one of the UPLC-II<sup>TM</sup> outputs for supplying the correct voltage/current to the EM relay when the output activates.

The two ganged jumpers on the auxiliary power supply board need to be set to give you the desired output voltage/current per the following:

20 mA for EM relay with 2200  $\Omega$  coil resistance (JMP3 = 46 V, and JMP1/JMP2 = 46 V/20 V (20 mA)).

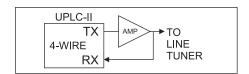
200 mA for EM relay with 25  $\Omega$  coil resistance (JMP3 = setting does not matter, and JMP1/JMP2 = 8 V (200 mA)).

20 V is for some other low voltage applications (JMP3 = 20 V, and JMP1/JMP2 = 46 V/20 V (20 mA)).

After setting the jumpers when you plug the power supply module back in the UPLC-II<sup>TM</sup>, then it is ready to output voltage/current on TB1-3 (+) and TB1-4 (-) for the main Power Supply and TB2-3 (+) and TB2-4 (-) if there is a redundant Power Supply with the auxiliary board.

### 3.2.5 External Booster Amplifiers

When using an external booster 50 W or 100 W amplifier, for high attenuation power-line applications, make sure the UPLC-II<sup>TM</sup> backplane 2-wire/4-wire jumper is set for 4-wire. *This is critical to avoid causing damage to the amplifier.* The usual connection is shown. The transmit output power of the UPLC-II<sup>TM</sup> will need to be set lower than normal depending on the particular external amplifier used.

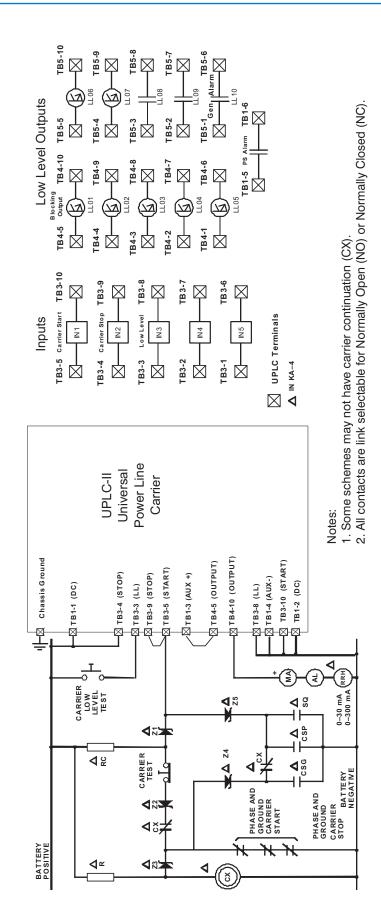


DCB Application w/External Booster Amplifier.

# 3.3 ON/OFF Mode Typical Wiring/Connections

Common wiring/connection diagrams for ON/OFF applications can be found on the following pages.





AMETEK® POWER INSTRUMENTS



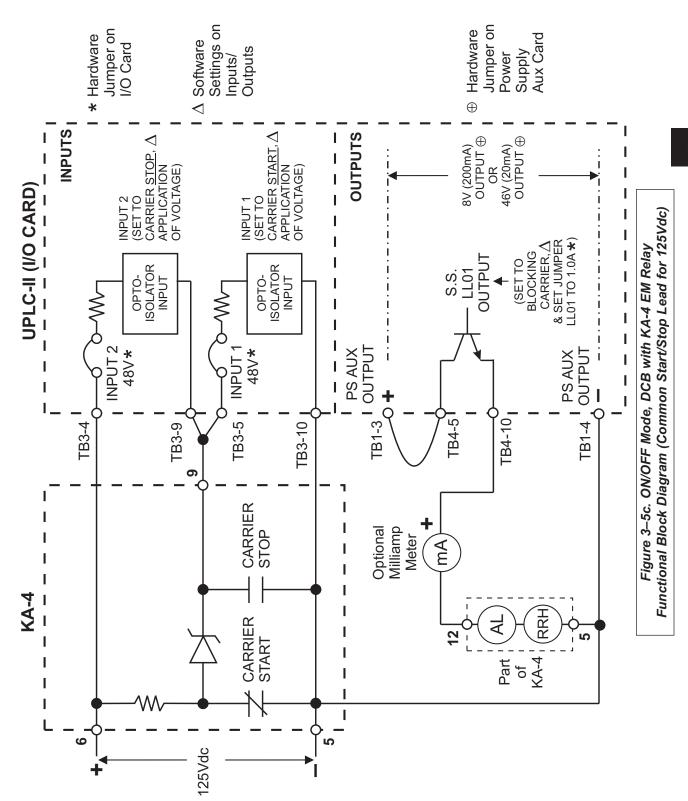
# Figure 3-5b. ON/OFF Mode, DCB With KA-4 EM Relay - Volt Levels/Settings

Conditions of UPLC-II inputs for use with KA4 electromechanical relay (Stop Priority)	for use with K	(A4 electrome	chanical relay (Sto	op Priority)
Condition	Carrier Start	Carrier Stop	Carrier Start   Carrier Stop   Idle (no start/stop)   Both start & stop	Both start & stop
Voltage across Stop Input	15V	125V	62.5V	125V
Voltage across Start Input	110V	00	62.5V	/0
Result	Start Carrier	Start Carrier   Stop Carrier   Stop Carrier	Stop Carrier*	Stop Carrier

arrier \*But allows checkback or low level test.

Module Coax E Backplane Coax E # of PA Coax I Power Supply Power					
ylq	Function	Software Selection	Hardware Selection	Label on board	Recommendation
	Coax Setting		2 wire/4 wire	JMP3/JMP5	2 Wire
	# of PAs		1 PA/2PA	JMP2/JMP6	Per factory
	Coax Impedance		20 Ω/22 Ω	JMP1/JMP4	50 Ω *
	ver		PwrOn/ PwrOff	JMP3	PwrOn
Ala	Alarm Contact		NO/NC	JMP1/JMP2	Per Engineering
Aux Power Supply Hol	Holding current		20 mA/200 mA	8V(200 mA) or 46/20V(20 mA)	JMP1/JMP2 Per carrier relay requirement (JMP3 is used only for 46/20V outputs when JMP1/JMP2 is in 46/20V position)
Logic Cor Key	Common Start/Stop Keying Input	Enable			
Input/Output					
Input 1 Car	Carrier Start	Application of Voltage	15/48/125/250 Vdc	Input 1	Set to voltage setting one step below station battery, ie – 125 Vdc battery, use 48 volt jumper
Input 2 Car	Carrier S top	Application of voltage	15/48/125/250 Vdc	Input 2	Set to voltage setting one step below station battery, ie – 125 Vdc battery, use 48 volt jumper
Input 3 Low	Low Level Key	Application of voltage	15/48/125/250 Vdc	Input 3	Per Engineering
Input 4			15/48/12 5/250 Vdc	Input 4	Per Engineering
Input 5			15/48/125/250 Vdc	Input 5	Per Engineering
ut 1	Blocking Output	(ON)	0.1/1.0 A	LL01	1.0 A
LL Output 2			0.1/1.0 A	LL02	Per Engineering
LL Output 3			0.1/1.0 A	LL03	Per Engineering
LL Output 4			0.1/1.0 A	LL04	Per Engineering
LL Output 5			0.1/1.0 A	LL05	Per Engineering
LL Output 6			0.1/1.0A	PT-06	Per Engineering
LL Output 7			0.1/1.0 A	LL07	Per Engineering
LL Output 8			NO/NC	TL08	Per Engineering
L Output 9			NO/NC	1L09	Per Engineering
LL Output 10 Ger	General Alarm		NO/NC	LL10	Per Engineering

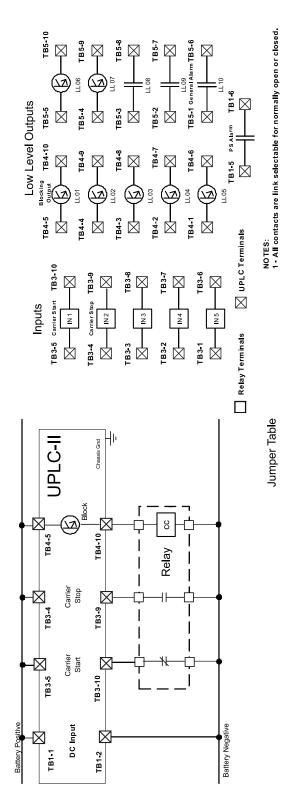




February 2018 Page 3–11



Figure 3-6. ON/OFF Mode, DCB with Microprocessor Relay - Connections/Settings



Module	Function	Software Selection	Hardware Selection	Label on board	Recommendation
Backplane	Coax Setting		2 wire/4 wire	JMP3/JMP5	2 Wire
	# of PAs	<u> </u>	1 PA/2PA	JMP2/JMP6	Per factory
	Coax Impedance	İ	50 Ω/75 Ω	JMP1/JMP4	± 0 0 €
Power Supply	Power	1	PwrOn/PwrOff	JMP3	PwrOn
	Alarm Contact		NO/NC	JMP1/JMP2	Per Engineering
Input/Output					
Input 1	Carrier Start	Removal of Voltage	15/48/125/250 Vdc	Input 1	Station Battery
Input 2	Carrier Stop	Application of Voltage	15/48/125/250 Vdc	Input 2	Station Battery
Input 3	(not used)		15/48/125/250 Vdc	Input 3	Per Engineering
Input 4	(not used)		15/48/125/250 Vdc	Input 4	Per Engineering
Input 5	(not used)		15/48/125/250 Vdc	Input 5	Per Engineering
LL Output 1	Blocking		0.1/1.0 A	LL01	0.1 A
	(Carrier Received)				
LL Output 2	(not used)		0.1/1.0 A	LL02	Per Engineering
LL Output 3	(not used)	1	0.1/1.0 A	LL03	Per Engineering
LL Output 4	(not used)		0.1/1.0 A	LL04	Per Engineering
LL Output 5	(not used)		0.1/1.0 A	LL05	Per Engineering
LL Output 6	(not used)		0.1/1.0 A	TL06	Per Engineering
LL Output 7	(not used)		0.1/1.0 A	LL07	Per Engineering
LL Output 8	(not used)		NO/NC	RTO8	Per Engineeri ng
LL Output 9	(not used)		NO/NC	FL09	Per Engineering
LL Output 10	General Alarm		NO/NC	LL10	Per Engineering



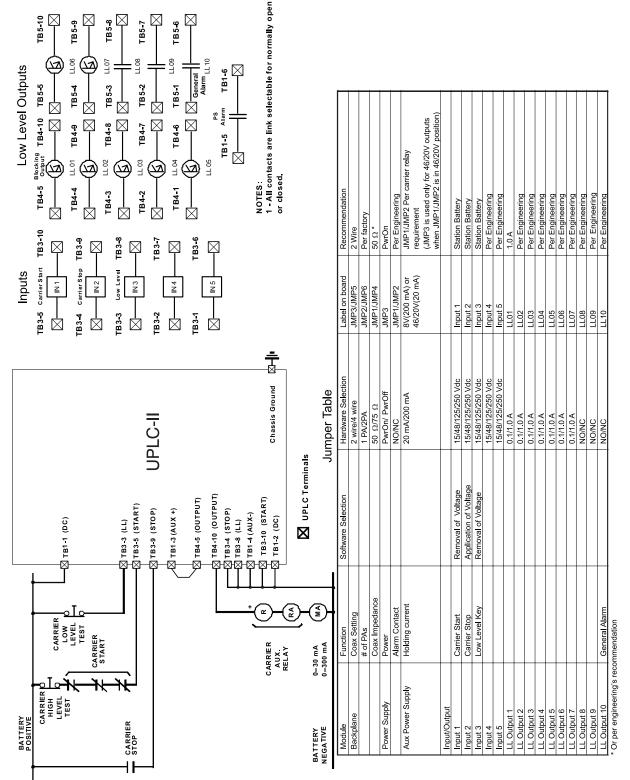
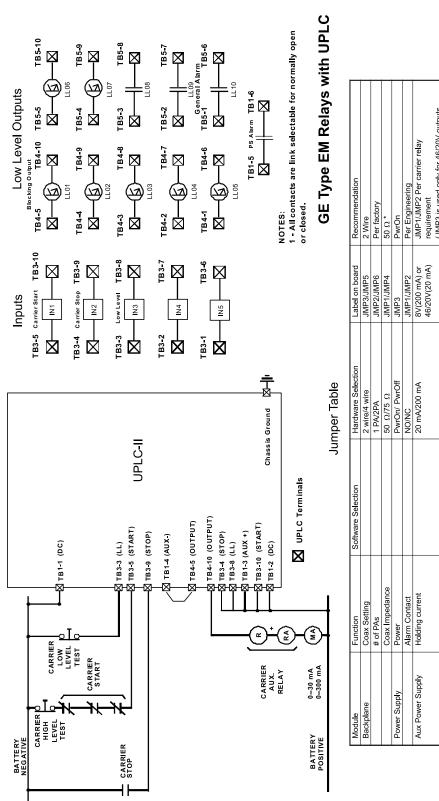


Figure 3-7a. ON/OFF Mode, DCB with GE type EM Relays - Connections/Settings



Figure 3–7b. ON/OFF Mode, DCB with GE Type EM Relays (Opposite Battery Polarity – Connections/Settings



Module	Function	Software Selection	Hardware Selection	Label on board	Recommendation
Backplane	Coax Setting		2 wire/4 wire	JMP3/JMP5	2 Wire
	# of PAs		1 PA/2PA	JMP2/JMP6	Per factory
	Coax Impedance		υ 52/0 09	JMP1/JMP4	* C O O *
Power Supply	Power		PwrOn/ PwrOff	JMP3	PwrOn
	Alarm Contact		NO/NC	JMP1/JMP2	Per Engineering
Aux Power Supply	Holding current		20 mA/200 mA	8V(200 mA) or 46/20V(20 mA)	JMP1/JMP2 Per carrier relay requirement
					(JMP3 is used only for 46/20V outputs when JMP1/JMP2 is in 46/20V position)
Input/Output					
Input 1	Carrier Start	Removal of Voltage	15/48/125/250 Vdc	Input 1	Station Battery
Input 2	Carrier Stop	Application of Voltage	15/48/125/250 Vdc	Input 2	Station Battery
Input 3	Low Level Key	Removal of Voltage	15/48/125/250 Vdc	Input 3	Station Battery
Input 4			15/48/125/250 Vdc	Input 4	Per Engineering
Input 5			15/48/125/250 Vdc	Input 5	Per Engineering
LL Output 1	Blocking	NO	0.1/1.0 A	LL01	1.0 A
LL Output 2			0 1/1 0 A	LL02	Per Engineering
LL Output 3			0.1/1.0 A	LL03	Per En gineering
LL Output 4			0.1/1.0 A	LL04	Per Engineering
LL Output 5			0 1/1 0 A	LL05	Per Engineering
LL Output 6			0.1/1.0 A	9077	Per Engineering
LL Output 7			0.1/1.0 A	LL07	Per Engineering
LL Output 8			NO/NC	LL08	Per Engineering
LL Output 9			NO/NC	FL09	Per Engineering
LL Output 10	General Alarm	ON	NO/NC	LL10	Per Engineering



### 3.4 ON/OFF Mode Alarms

The following tables show alarms for ON/OFF Mode.

Table 3–2.

Hardware Fixed Alarm (from Power Supply Board)

All Modes

PS Hardware Failure Alarm for All UPLC-II™ Units			
Alarm Reason:	One of the PS outputs is too low in voltage		
Alarm Name: (Available Outputs)	Power Supply Alarm Output (TB1-5 & 6)**		
	De-Energized State		
Contact Type:	N.O. Contact N.C. Contact		
UPLC-II™ Condition			
PS Good	Closed	Open	
PS Bad	Open	Closed	
**For the Redundant Power Supply, use TB2-5 & 6			

Table 3–3.
Software Programmable Alarms/(Outputs from I/O Board)
ON/OFF Mode

Hardware Failure Alarm for All UPLC-II™ Units			
Alarm Reason:	Hardware health of at least one card is bad		
Alarm Name: (Available Outputs)	General Alarm Output (LL08 – LL10)		
	De-Energized State		
Contact Type:	N.O. Contact N.C. Contact		
UPLC-II™ Condition			
All OK	Closed	Open	
Hardware Failure	Open	Closed	
Loss of DC Power	Open	Closed	



### Table 3–3 Continued: Software Programmable Alarms/(Outputs from I/O Board) ON/OFF Mode

Transmit Monitor for ON/OFF Units Only		
Output Reason:	TX signal level is ≥ TX low level setting	
Output Name: (Available Outputs)	Main RF Output (LL01 – LL10)	
	De-energized State	
Output Type:	N.O. Output	N.C. Output
UPLC-II™ Condition		
Transmit ON	Closed	Open
Transmit OFF	Open	Closed

TX / RX Alarms for ON/OFF Units with Checkback (CB) Option Only				
Alarm Reason:	UPLC-II™ failed all checkback tests performed at the <b>10 W</b> level		UPLC-II™ failed all checkback tests performed at the <b>1 W</b> level	
Alarm Name: (Available Outputs)	Checkback Major Alarm (LL01 – LL10)		Checkback Minor Alarm (LL01 – LL10)	
	De-energized State		De-energized State	
Output Type:	N.O. Output	N.C. Output	N.O. Output	N.C. Output
UPLC-II™ Condition				
Passed CB Test	Open	Closed	Open	Closed
Failed CB Test	Closed	Open	Closed	Open

<sup>\*</sup> If a UPLC-II™ has both Major & Minor Checkback alarms, then that unit is faulty and needs to be checked.



# 3.5 FSK Mode Protective Relay Applications

The UPLC-II™ carrier set is particularly suitable for the following types of protective relay systems:

- Directional Comparison Unblocking
- Permissive Overreaching Transfer Trip (POTT)
- Permissive Underreaching Transfer Trip (PUTT)
- Dual Phase Comparison Unblocking
- · Segregated Phase Comparison Unblocking
- Direct Transfer Trip

# 3.5.1 Directional Comparison Unblocking

The Directional Comparison Unblocking systems transmit a continuous blocking signal, except during internal faults. The channel is generally a Frequency-Shift Keyed (FSK) Power-Line Carrier. For an internal fault, the FSK transmitter is shifted to the "unblock" frequency. The transmitted power in many applications is normally 1 W, boosted to 10 W during unblock operation.

The frequency-shift channel is monitored continuously to prevent tripping when a loss of channel occurs. The carrier receiver logic is shown in Figure 3–8. Under normal conditions, a block frequency is transmitted and OR-1 has no input. Because AND-1 and AND-2 are not satisfied, OR-2 is not energized. For an internal fault, the block frequency is removed. Assuming that the unblock signal is shorted out by the fault, OR-1 provides a direct input to AND-2 to satisfy its input requirements for 150 ms. AND-2 inputs to OR-2 to oper-

ate the RR or to provide input to the AND shown in Figure 3–8. Without an unblock signal, typically 150 ms is allowed for tripping. After this period, lock out is initiated as one of the inputs to AND-2 is removed. This resets the RR or removes the input to AND. If the unblock signal is received, it inputs directly to OR-2 to energize the RR or to provide input to AND. The unblock signal also removes an input to AND-1 to stop the timer. A channel failure (no block or unblock signal) provides input to AND-1 and, after 150ms, locks out the relaying and triggers an alarm. The operation of the scheme shown in Figure 3-9 is given in Table 3–4 for external and internal faults. The phase and ground trip fault detectors at both stations must operate for all internal faults; that is, they must overreach the remote bus.

The dependability and security of Directional Comparison Unblocking systems make them the most attractive of the protective schemes for transmission lines using Power-Line Carrier channels. Over-tripping is avoided by continuous blocking and continuous channel monitoring. Only an external fault within a certain time delay after channel failure can result in over-tripping. This time is selectable from 0-500ms.

The scheme is most appropriate for two-terminal lines, but is applicable to multi-terminal lines. Separate channels are required between each terminal and the remote terminal(s). A sample schematic is shown in Figure 3–23, near the end of this chapter.

You may conserve frequency spectrum by using a narrow band frequency shift carrier, but at the expense of channel speed.

Block OR AND O-500 AND 2 OR TO RR or AND Frequency (0=disabled)

Figure 3-8. Simplified Unblock Receiver Logic

Another consideration is an open breaker situation. When the remote breaker is open for an extended period of time, the relay system must be able to trip. The remote relay system sends a trip signal when detecting a remote open breaker. If this



remote signal is received for 1,000 ms (1 sec) or longer, the carrier receiver logic interprets this as an open breaker and allows the local end to trip whenever the local relays detect a fault.

An older system (STU unblock) is shown in Figure 3–25a & 25b, near the end of this chapter.

Table 3-4. Operation of the Directional Comparison Unblocking Scheme

OPERATION FOR EXTERNAL AND INTERNAL FAULTS			
Type of Fault	Events at Station G	Events at Station H	
External (F <sub>E</sub> )	P <sub>1</sub> operates.  f <sub>1</sub> channel shifts to unblock.  f <sub>2</sub> channel continues to block.  No trip.	P <sub>2</sub> does not see fault.  Loss of block and/or receipt of unblock (f <sub>1</sub> ) operates RR or inputs AND.  No trip.	
Internal (F <sub>I</sub> )	P <sub>1</sub> operates.  f <sub>1</sub> channel to unblock.  Loss of block and/ or receipt of unblock (f <sub>2</sub> ) operates RR or inputs AND.  Trip.	P <sub>2</sub> operates.  f <sub>2</sub> channel shifts to unblock.  Loss of block and/or receipt of unblock (f <sub>1</sub> ) operates RR or inputs AND.  Trip.	

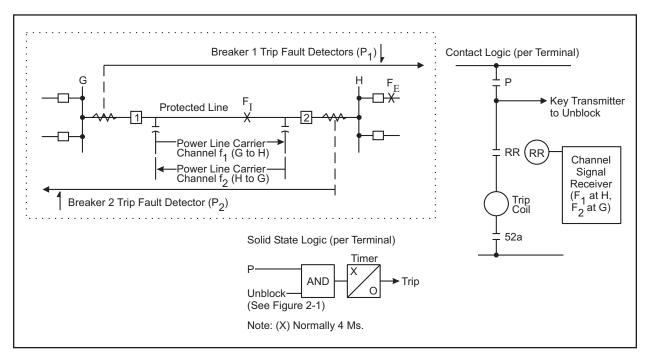


Figure 3-9. Basic Logic Diagrams for Directional Comparison Unblocking



### 3.5.2 Permissive Overreaching Transfer Trip Systems

Overreaching transfer trip systems require a channel signal to trip, and are used with a frequency-shift audio tone, modulated on a communication channel (e.g., public or private telephone lines). These systems are generally not used with Power-Line Carriers. There are, however, successful applications of Power-Line Carrier on POTT schemes where parallel lines allow for cross-coupling of the carrier signal.

### 3.5.3 Permissive and Non-Permissive Underreaching Transfer Trip Systems

For overreaching systems, the directional phase and ground trip fault detectors (P) must be set to overlap within the transmission line and not overreach any terminals (see Figure 3–10).

That is, at least one trip fault detector (P) must operate for all internal faults, and none should operate for any external fault. In practice, distance relays are normally required for both ground faults and phase faults, although directional instantaneous ground-overcurrent relays might meet these requirements in some cases.

Though it is the least complex, the non-permissive system is rarely used because of the high potential for false outputs from the channel, which would cause incorrect tripping. If a non-permissive system is used, the channel considerations should be as described later for direct trip systems. The system is made permissive by the additional set of phase and ground overreaching fault detectors (FD), which must operate for all internal faults (see Figure 3–10).

Operation of the underreaching transfer trip scheme shown in Figure 3–10 is described in Table 3–5 for external and internal faults.

Because the trip fault detectors (P) do not operate for external faults, underreaching transfer trip systems do not require external fault-clearing coordination circuits (transient blocking) and are, therefore, inherently simpler than any of the other schemes. You obtain maximum security if you use additional permissive fault detectors. These schemes also provide minimum operating times for many faults that are tripped directly, without using the channel.

### 3.5.4 Dual Phase Comparison Unblocking Systems

Dual comparison systems require a duplex channel: one frequency for each line terminal. The UPLC-II<sup>TM</sup> frequency-shift channel equipment is available for this purpose; normally used in an unblocking system. Continuous channel monitoring is also provided, because either a trip positive or trip negative carrier signal is always transmitted.

The transmitter is keyed to its trip positive frequency when the square wave from the filter goes positive, and is keyed to its trip negative frequency when the square wave is at zero. There are two outputs at the receiver: the trip positive output is a square wave that goes positive when a trip positive frequency is received; the trip negative output goes positive when a trip negative frequency is received.

The basic operation of the Dual Phase Comparison system is shown in Figure 3–11. For internal faults, the single phase outputs of the sequence current networks are essentially in phase, although such output represents currents 180° apart in the power system. The network output goes through a squaring amplifier that keys the frequency shift transmitter. An adjustable delay circuit delays the local square wave by a time equal to the channel delay time.

The network output is then used to develop two complementary square waves. One wave, which has a positive state during the positive half-cycle of the sequence current network, is compared with



Table 3–5. Operation of the Underreaching Transfer Trip Scheme

OPERATION FOR EXTERNAL AND INTERNAL FAULTS			
Type of Fault	Events at Station G	Events at Station H	
External (F <sub>E</sub> )	P <sub>1</sub> does not operate. No channel signal sent to H. No trip.	P <sub>2</sub> does not operate. No channel signal sent to G. No trip.	
Internal (F <sub>I</sub> )  (Fault near station H)  † Omitted in non-permissive systems.	P <sub>1</sub> does not operate.  No channel signal sent to H.  †(FD <sub>1</sub> operates).  Transfer-trip (f <sub>2</sub> ) from station H operates RR or inputs to AND (or OR if nonpermissive).	P <sub>2</sub> operates and trips directly.  Transfer-trip signal keyed to station G.  †(FD <sub>2</sub> operates).  Trip.	
,	Trip.		

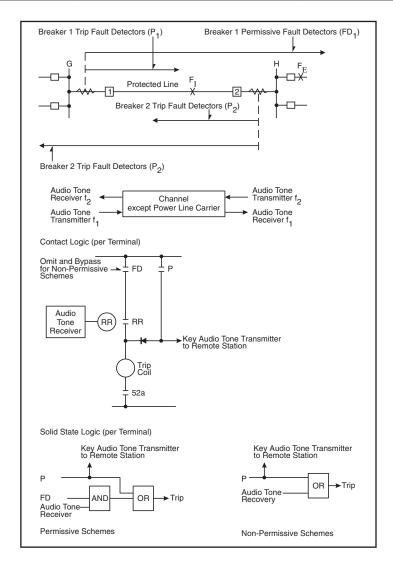


Figure 3-10. Basic Logic Diagrams for Underreaching Transfer Trip Systems



the receiver's trip positive output. The other wave, which has positive output during the negative half-cycle of the sequence current network, is compared to the receiver's trip neg. output in a second comparison circuit.

On internal faults, the positive half-cycle of the local square wave lines up with the received trip positive output to provide an AND-1 output. On the negative half-cycle, this local square wave lines up with the received trip negative output to provide an AND-2 output. If an arming signal is received (FD<sub>2</sub> and/or 21P) and either AND-1 or AND-2 output exists for 4ms, an input to the trip flip flop initiates breaker tripping. The same operation occurs at both terminals, tripping breakers 1 and 2 simultaneously on either half-cycle of fault current.

For tripping, both the trip positive and trip negative frequencies must be transmitted through the internal fault via Power-Line Carrier channels. If these frequencies are not received, the receiver detects a loss of channel and clamps both outputs to a continuous positive state. This loss of channel clamp enables both comparison circuits, allowing the system to trip on the local square wave input only. After 150ms, the system output clamps these to the zero state. At this point, the system cannot trip and is locked out. An alarm indicates loss of channel.

For external faults, the reversal of current at one end shifts the square waves

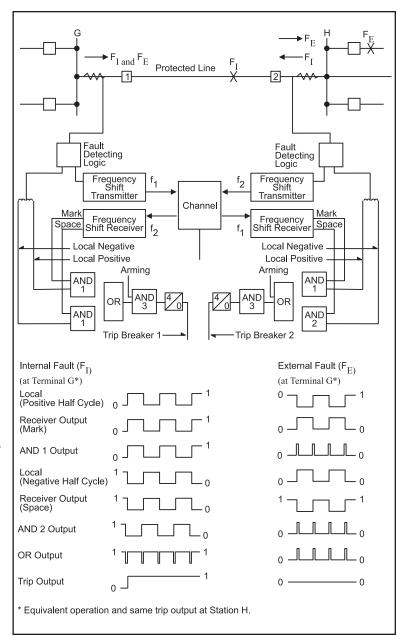


Figure 3–11. Basic Operation of the Dual Phase Comparison Pilot Relaying System

essentially 180°. As a result, neither AND-1 nor AND-2 has the sustained output required to operate the 4ms timer. No trip occurs at either line terminal.



### 3.5.5 Segregated Phase Comparison System

The Segregated Phase Comparison system has been developed to improve pilot relay protection, particularly for the long EHV series capacitorcompensated transmission lines. Long EHV series capacitor-compensated lines are a source of significant transients during the fault period. Under these circumstances, sequence current networks designed to operate at normal system frequency may present a problem. The experience with these Phase Comparison systems has, however, been remarkably good. Directional Comparison systems, on the other hand, are subject to mis-operation on series capacitor-compensated lines, particularly if the capacitor gaps do not short the capacitors on faults. Segregated phase comparison systems, which are current-only, are independent of the following phenomena:

- · Power system frequency and wave form
- Effects of impedance unbalance between the power system phase circuits.
- Maximum load/minimum fault current margin.

The segregated phase comparison system can be divided into two types: a two-subsystem scheme and a three-subsystem scheme. In the two-subsystem scheme, one subsystem operates from delta current (I<sub>a</sub>-I<sub>b</sub>) for all multi-phase faults, and a ground (3I<sub>0</sub>) current subsystem operates for all ground faults. The three-subsystem scheme has a subsystem for each phase (I<sub>a</sub>, I<sub>b</sub>, and I<sub>c</sub>). Each subsystem consists of one channel (UPLC-II<sup>TM</sup>) and one Phase Comparison relay.

Both segregated Phase Comparison systems incorporate "offset keying", enabling them to trip for internal high-resistance ground faults and internal faults with outfeed at one terminal. No other system can clear these types of faults without extra logic or channels. On a 500 kV line with a 2,000:5 current transformer ratio, for example,

the three-subsystem scheme will operate for ground-fault resistances up to about  $100 \Omega$  primary impedance. Under the same conditions, the two-subsystem scheme will operate up to about  $200 \Omega$  primary fault resistance.

The two-subsystem package is suitable for all applications except single-pole tripping, where the three-subsystem package must be applied. The basic operation of the scheme is illustrated in Figure 3–12. Each current is fed through a noninductive resistor, supplying a voltage output to the squaring amplifier (SA) that is exactly proportional to the primary currents. The output of these amplifiers is used to key the individual channels and, through the local delay timers (LDT), to provide the local square waves for comparison. The timers are adjustable between 2 and 20ms to compensate for the delay time of the channel. This digital delay circuit translates the pulse train independently of the pulse width ratio, in contrast to the ac phase angle shift used in the other systems. The ac phase shift delay uses frequency-dependent components, which are accurate only at system frequency and can "ring" during transient conditions.

The square wave comparison is made independently for each current in the separate subsystems. Separate channels are required for each of the subsystems. One of the comparison circuits is shown in simplified form in Figure 3–13. In this dual comparison circuit, AND-P is used for the positive half-cycles and AND-N for the negative half-cycles. As shown in Figure 3–13, the received positive square wave corresponds to a "1" input to AND-P, and the received negative square wave to a "0" input, negated to "1", into AND-N. Except for this variation, operation is as shown by the square wave blocks in the lower half of Figure 3–11.



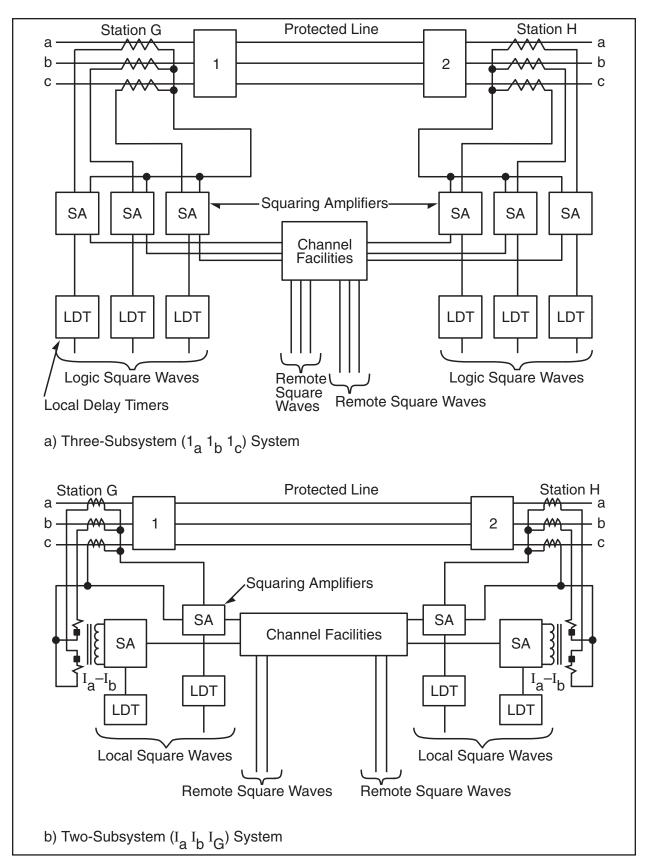


Figure 3–12. Basic Segregated Phase Comparison Systems



To generate the local and keying square waves, conventional phase comparison systems use thresholds equivalent to (or very near) the zero axis. As a result, an internal fault with outfeed looks like an external fault to those systems (see Figure 3–14). The offset keying technique permits the relay system to trip for internal faults with outfeed current out at one terminal. While the outfeed condition is very unusual, it presents difficult problems to the great majority of pilot relaying systems when it does occur. Outfeed can occur in any of the following cases:

- Series-capacitor-compensated parallel lines.
- Weak-feed or zero-feed applications, particularly with heavy through load.
- Some multi-terminal applications.
- Series-compensated (line-end compensation) line with a source inductive reactance smaller than series capacitor reactance.
- Some single-line-to-ground faults, occurring simultaneously with an open conductor, where the fault is on one side of the open conductor.
- Some single-line-to-ground faults with high fault resistance and heavy through load (such conditions can cause outfeed only in the faulted phase current, not in the ground subsystem).

The offset keying technique allows the relay system to work like a true current differential scheme. The scheme takes advantage of the fact that, for the outfeed condition, the current into the line is greater in magnitude than the current out of the line for the internal fault.

This relationship is illustrated in Figure 3–14, where  $I_G$  equals  $I_F$  plus  $I_H$ . While the two terminal

currents may have any angular relationship with one another, most outfeed conditions display a nearly out-of-phase relationship. The out-of-phase condition illustrated is the most difficult case for phase comparison, as well as the most common outfeed condition.

In the offset keying technique, the keying threshold is displaced in the positive direction, away from the zero axis. The local square wave thresholds are displaced negatively. To maintain security, the local thresholds are separated from each other, providing "nesting" during external faults. Typical settings are shown in Figure 3–15.

Figure 3–16 illustrates the square wave characteristics of offset keying for normal internal faults, external faults, and internal faults with outfeed.

The segregated Phase Comparison scheme incorporates a high degree of security. Its design is based on extensive field experience and the model line tests for the very long, series capacitor-compensated EHV lines.

Output trip signals are supervised by an arming input and a number of security checks (see Figure 3–14). Phase arming is performed by a current rate-of-change detector that responds to sudden increases, decreases, or angular shifts in current. It operates on current changes of 0.5 A or more, with an operating time of 2 ms. Ground arming is 3I magnitude—typically 0.8 A secondary.

Security checks to comparison AND (see Figure 3–14) include (1) low channel signal blocking, (2) lockout for sustained low channel signal, (3) channel noise clamp, and (4) receive guard block. For the phase subsystems, a trip signal occurs if comparison AND has an output for more than 3ms (4ms for the ground subsystem).



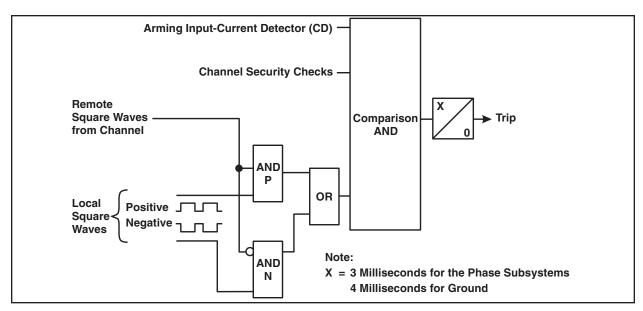


Figure 3-13. Basic Operation of the Segregated Phase Comparison System

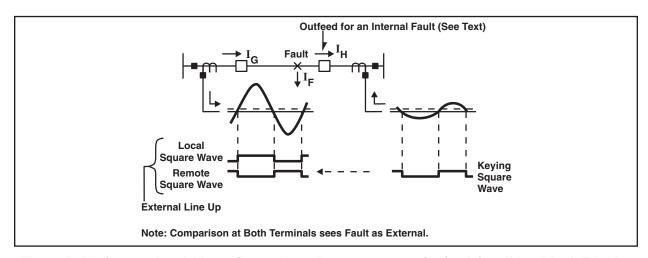


Figure 3-14. Conventional Phase Comparison Response to an Outfeed Condition Block Tripping

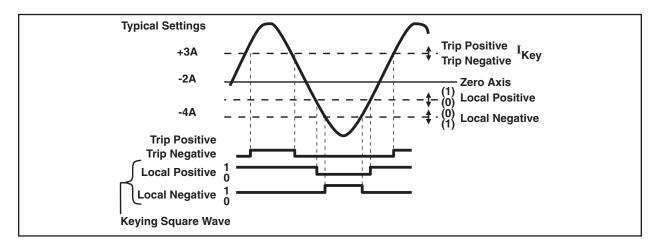


Figure 3-15. Typical Threshold Setting for Offset Keying



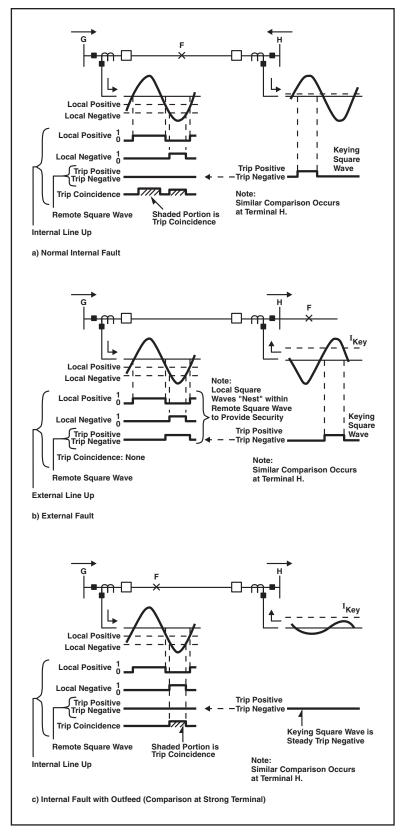


Figure 3–16. Response of Segregated Phase Comparison System with Offset Keying



# 3.6 FSK Mode Direct Transfer-Trip (DTT) Systems

Direct transfer-trip systems provide circuit-breaker tripping at remote or receiver terminals, without any supervision by fault detectors. The most important consideration in a direct transfer-trip system is the type of channel applied. The communications equipment must carry the total burden of system security and dependability.

Direct transfer-trip systems are applied for:

- Line protection with non-permissive under reaching transfer-trip systems.
- Transformer protection where there is no circuit breaker between the transformer and transmission line.
- Shunt reactor protection.
- Remote breaker failure protection.

A sample schematic is shown in figure 3-26, near the end of the chapter.

#### 3.6.1 Transformer Protection

A typical transformer protection scheme is illustrated in Figure 3–17. A direct trip channel is keyed to the trip state when the transformer protective relays operate. The received trip signal will then trip the remote end breaker and lock out reclosing.

Although it is no longer widely used, you may use a ground switch operated by the transformer protective relays for transformer protection. In this technique, a ground fault is initiated on the transmission line at G, providing adequate

fault current for the ground relays at H to

trip the breaker at H. This system is slower but is widely used on lower voltage systems and is fairly simple and straightforward. It does not require any secure communication medium between G and H. For this type of application, the ground relays at H can be set to operate for 100 percent of the line and not overreach to bus G.

While a single switch on one phase is normally applied, you may use a double switch on two phases to initiate a double-phase-to-ground fault. In the latter case, both phase and ground relays can operate to ensure redundancy. Fault grounding is not applicable to all systems because of high short-circuit capacity.

#### 3.6.2 Shunt Reactor Protection

Shunt reactors are frequently used on HV and EHV lines. These line reactors are connected on the line side of the circuit breakers (Fig. 3–18). A remote trip channel is thus required for a fault in the shunt reactor.

## 3.6.3 Remote Breaker-Failure Protection

A remote breaker-failure system is necessary where a multi-breaker bus, such as a breaker-and-a-half or ring bus scheme, is applied at a transmission line terminal. A direct transfer-trip system will be a part of the remote breaker-failure protection.

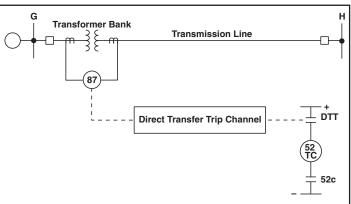


Figure 3-17. Direct Transfer Trip for Transformer Protection



# 3.6.4 Direct Transfer Trip Channel Considerations

The channel and its terminal equipment are major factors in the proper operation of the direct transfer-trip system. The DTT channel must neither fail to provide a correct trip signal nor provide a false signal.

While other types of modulation are possible, FSK equipment offers the best compromise between noise rejection capability and equipment complexity. Two frequencies are usually transmitted in an FSK system: the "guard" frequency is transmitted during non-trip conditions and the "trip" frequency is transmitted when a breaker trip is required. Because a signal is always present, the FSK system will allow the channel to be continuously monitored. Continuous channel monitoring is necessary in a direct trip system, because breaker tripping is not supervised by any local relays.

As noise in the channel increases, a point is reached where there is a high probability of false tripping. The level of noise at which the channel becomes unreliable must be determined by tests. Signal-to-noise ratio monitors must then be included with any direct trip channel, to block possible false tripping. It is important, however, not to get the noise monitors any more sensitive than required, since their operation will prevent tripping.

There are three important aspects to the application of FSK channels to direct trip systems: channel bandwidth, dual channel systems, and channel protection.

Although faults should be cleared in the shortest possible time, speed is not the only criterion for selecting equipment. *It is important to use the narrowest bandwidth equipment possible.* A wide bandwidth channel may give the desired speed, but more noise enters the system. Thus, the channel will block tripping sooner than a narrower bandwidth channel with the same received signal level. A wideband channel will consequently not be as dependable as a narrower channel under equal receive-level conditions.

A dual channel system is recommended for direct trip applications. Two FSK channels should be used in series, so that both must trip before the breaker is tripped. Many tests have indicated that dual channels improve the security of the direct trip system by several orders of magnitude. Use of a dual channel system has very little effect on dependability, even if both channels are on the same transmission medium.

If you want to increase the dependability, you can modify the dual channel transfer trip scheme to allow a single channel trip when there is failure of the other channel. A typical Dual Channel Throwover to Single Channel Scheme is illustrated in Figures 3–19 & 3–20.

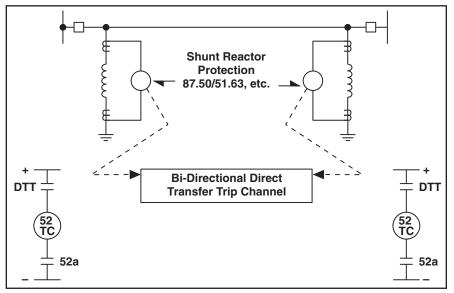


Figure 3-18. Direct Transfer Trip for Shunt Reactor Protection



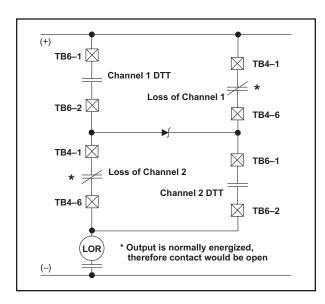


Figure 3–19.

Dual Channel Direct Transfer Trip with

Throwover

to Single Channel

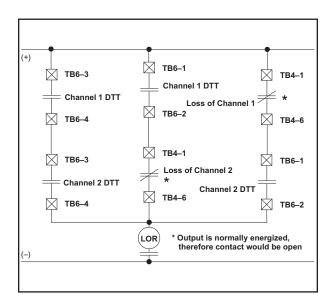


Figure 3–20.

Dual Channel Direct Transfer Trip with

Throwover

to Single Channel

# 3.7 FSK Mode Special Considerations

The UPLC-II<sup>TM</sup> frequency-shift equipment can operate in either the two- or three-frequency mode. The three basic frequencies are as follows (see Figure 3–21):

- f<sub>C</sub> Center frequency
- $f_H$  High-frequency, is a frequency shift ( $\Delta f$ ) above  $f_C$
- $f_L$  Low-frequency, is a frequency shift ( $\Delta f$ ) below  $f_C$

The value of  $\Delta f$  depends on the bandwidth of the UPLC-II<sup>TM</sup> set. For a bandwidth of 1200 Hz,  $\Delta f$  is 500 Hz. A bandwidth of 300 Hz yields a  $\Delta f$  of 100 Hz, while the 600 Hz bandwidth  $\Delta f$  can be either 250 or 100 Hz. The center channel frequency ( $f_C$ ) can vary from 30 to 535 kHz (in .01 kHz steps).

In the two-frequency systems, only  $f_H$  and  $f_L$  are used. The two frequencies function differently and take on different labels when operating with the different types of protective relay systems.

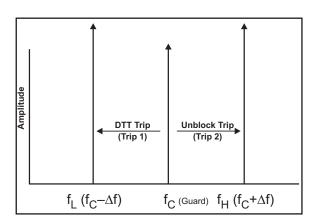


Figure 3-21. UPLC-II™ 3-Frequency System



## 3.7.1 3-Freq. Systems

The UPLC-II<sup>TM</sup> also provides for three-frequency system applications (Fig. 3–21), e.g., Directional Comparison Unblocking with Direct Transfer Trip, or Permissive Overreaching Transfer Trip with Direct Transfer Trip. All three frequencies are closely-controlled discrete frequencies within the equivalent spacing of a single wideband or extra wideband channel. In applying a three-frequency system, the Direct Transfer Trip keying inputs shifts the channel low (i.e., –250 Hz for 600 Hz bandwidth) and the unblock key shifts the channel high (i.e., +250 Hz for 600 Hz bandwidth).

See figure 3-27, near the end of this chapter, for a sample schematic.

## 3.7.2 4-Freq. Systems

The UPLC-II<sup>TM</sup> can be purchased with the option of setting it for a four-frequency system (Fig. 3–22). The purpose is to use one PLC channel to perform two independent trips. It is similar to the three-frequency system but is able to key two relaying inputs simultaneously, where as with the three-frequency system, if both inputs are keyed simultaneously, only the DTT frequency is output.

Four frequencies are utilized within either a 600Hz bandwidth or a 1200Hz bandwidth system. For frequencies, refer to the specifications in chap. 2.

Bandwidth/Shift can be 600Hz, +/-250Hz or 1,200Hz +/- 500Hz. The receiver is able to discriminate between these four frequencies and provide the necessary input to the logic portion.

The logic is two sets of the full unblock logic. This allows you to select either command function, DTT or Unblock. Should both inputs be keyed simultaneously, the frequency that is sent will engage both Trip A and Trip B outputs.

The trip test feature is not available in the four-frequency system.

# 3.7.3 Directional Comparison Unblocking (2-Frequency)

The higher frequency (f<sub>H</sub>), or "Guard" frequency, is transmitted continually as a blocking-type signal during normal conditions, to indicate that the channel is operative and to prevent remote relay tripping when external faults occur.

For a fault sensed by the local overreaching pilot relay, the transmitter is frequency-shifted to a low frequency ( $f_L$ ), called "Unblock" frequency. The transmitted power is normally 1 W, boosted to 10 W for the "Unblock" operation.

The Directional Comparison Unblocking system will generally use the wide band, wide shift (600 Hz BW, ±250 Hz Shift) UPLC-II<sup>TM</sup> setting. Also, the most common power output level used will be the 1 watt block and 10 watt trip. The type of carrier applied with this scheme may be varied from the normal for special circumstances, e.g., when matching the new UPLC-II<sup>TM</sup> equipment at one end of the line with the older TCF, TCF-10, TCF-10A or TCF-10B equipment at the other end. In this case, you must apply the wide band, narrow shift carrier (600 Hz BW, ±100 Hz Shift) to match the older carrier characteristics.

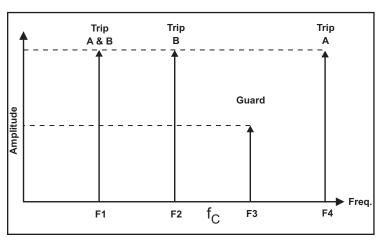


Figure 3-22. UPLC-II™ 4-Frequency System



# 3.7.4 Transfer Trip: Overreaching, Underreaching or Direct (2-Frequency)

The higher frequency ( $f_H$ ), or "Guard" frequency, is transmitted continually during normal conditions. For a fault sensed by the overreaching (or underreaching) pilot relay, the transmitter is shifted to the low frequency ( $f_L$ ), called "Trip" frequency.

When using the UPLC-IITM or any permissive overreaching or underreaching line relay system, you can apply any bandwidth setting. However, the best all around setting to use will be the wide band, wide shift (600 Hz BW, ±250 Hz Shift) equipment. If frequency spacing between other Power-Line Carrier units is not an issue and relay speed is critical, you may apply the extra wide band (1200 Hz, ±500 Hz Shift) equipment. Security against noise causing a false trip is also increased some with the extra-wide band, but increasing RX pre-trip delay has the largest improvement on security. In any of these systems, the usual power level combination will be 1 W for guard and 10 W for the trip signal.

# 3.7.5 Phase Comparison Unblocking: Dual or Segregated (2-Frequency)

Phase Comparison relays use square wave signals for operation. The transmitter is keyed to a "Trip Positive" frequency when the relay square wave goes positive, and is keyed to a "Trip-Negative" frequency when the relay square wave is at zero. The Trip Positive frequency is frequency-shifted

below  $f_C$ ; the "Trip Negative" frequency is frequency-shifted above  $f_C$ . Either frequency can function as a trip or block, depending on the local square wave.

For Phase Comparison systems, you can use only the wide band with wide shift or extra wide band UPLC-II<sup>TM</sup>. In the interest of conserving spectrum, the wide band, wide shift channel is most common. However, if speed is important, you may apply the extra wide band set.

The most often applied power level will be 10 watts for both "Trip-Positive" and "Trip-Negative".

## 3.7.6 Three-Terminal Line Applications

When a three terminal line protection requires Power-Line Carrier equipment, each terminal must have one transmitter and 2 receivers, since each terminal must receive a signal from each of the 2 other ends of the line. Fig. 3–23 is a representation of the transmitter/receiver complement required to implement a single function: Hybrids or other isolation devices are required between transmitters and transmitters to receivers. See the hybrid section, at the end of the chapter, for details.

## 3.7.7 External Booster Amplifier

When using an external booster 50 W or 100 W amplifier, for high attenuation power-line applications, make sure the UPLC-II<sup>TM</sup> backplane 2-wire/4-wire jumper is set for 4-wire. *This is critical to avoid causing damage to the amplifier*. Normally a skewed hybrid is used to combine the booster amplifier's TX output and the UPLC-II<sup>TM</sup> RX input onto a common coax. The transmit output power of the UPLC-II<sup>TM</sup> will need to be set lower than normal depending on the particular external amplifier used.

# 3.8 FSK Mode Typical Wiring/Connections

Common wiring/connection diagrams for FSK applications can be found on the following pages.

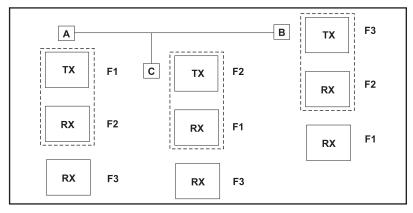
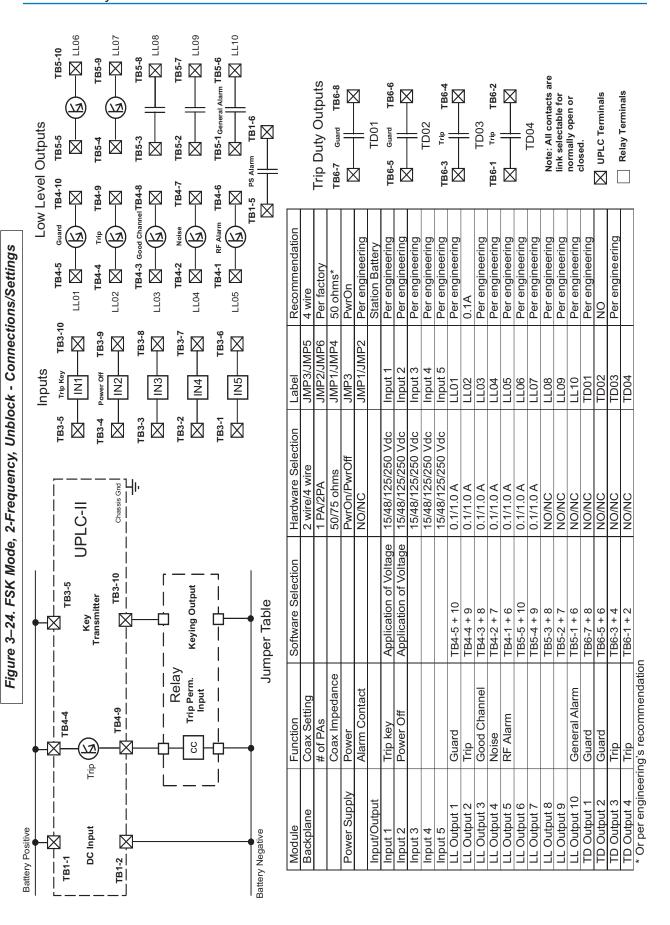


Figure 3-23. FSK Three Terminal Line Application







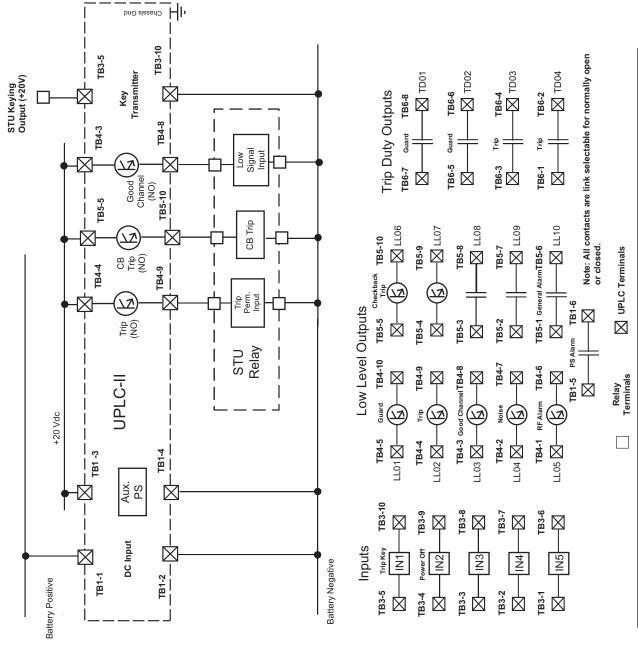


Figure 3–25a. FSK Mode, 2-Frequency, Unblock with STU Relay System - Connections



Figure 3–25b. FSK Mode, 2-Frequency, Unblock with STU Relay System - Settings

Programming / Jumper Table

Module	Function	Software Selection	Hardware Selection	Label	Recommendation
Backplane	Coax Setting		2 wire/4 wire	JMP3/JMP5	4 wire
	# of PAs		1 PA/2PA	JMP2/JMP6	Per factory
	Coax		50 \Q/75 \Q	JMP1/JMP4	± 50 ℃ *
	Impedance				
Power Supply	Power		PwrOn/PwrOff	JMP3	PwrOn
	Alarm Contact		NO/NC	JMP1/JMP2	Per Engineering
Aux PS				JMP1/JMP2	46/20V
				JMP3	20V
Input/Output					
Input 1	Trip Key	Application of Voltage	15/48/125/250 Vdc	Input 1	15V
Input 2	Power Off	Removal of Voltage	15/48/125/250 Vdc	Input 2	Per Engineering
Input 3			15/48/125/250 Vdc	Input 3	Per Engineering
Input 4			15/48/125/250 Vdc	Input 4	Per Engineering
Input 5			15/48/125/250 Vdc	Input 5	Per Engineering
LL Output 1	Guard		0.1/1.0 A	LL01	Per Engineering
LL Output 2	Trip	NO	0.1/1.0 A	LL02	0.1 A
LL Output 3	Good Channel	NO	0.1/1.0 A	LL03	0.1 A
LL Output 4	Noise		0.1/1.0 A	LL04	Per Engineering
LL Output 5	RF Alarm		0.1/1.0 A	LL05	Per Engineering
LL Output 6	Checkback Trip	ON	0.1/1.0 A	9077	0.1 A
LL Output 7			0.1/1.0 A	LL07	Per Engineering
LL Output 8			NO/NC	RT-08	Per Engineering
LL Output 9			NO/NC	6077	Per Engineering
LL Output 10	General Alarm		NO/NC	LL10	Per Engineering
TD Output 1	Guard		NO/NC	TD01	Per Engineering
TD Output 2	Guard		NO/NC	TD02	Per Engineering
TD Output 3	Trip		NO/NC	TD03	Per Engineering
TD Output 4	Trip		NO/NC	TD04	Per Engineering

<sup>\*</sup> Or per engineering's recommendation

Note: UPLC-II<sup>TM</sup> programmed for 2F-Unblock Standard Configuration. If used opposite a TCF/TCF-10/TCF-10A, the transmitter and receiver shift needs to be 100 Hz.



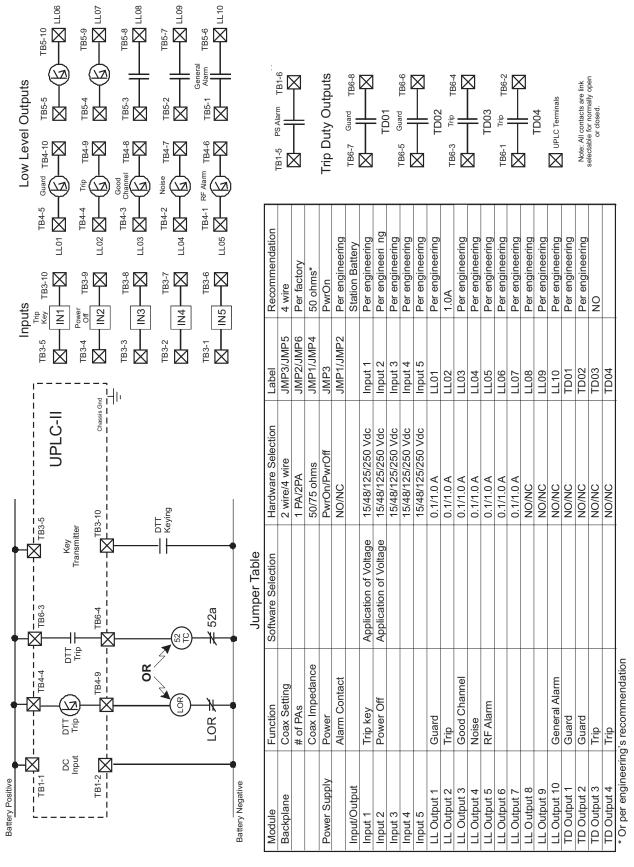
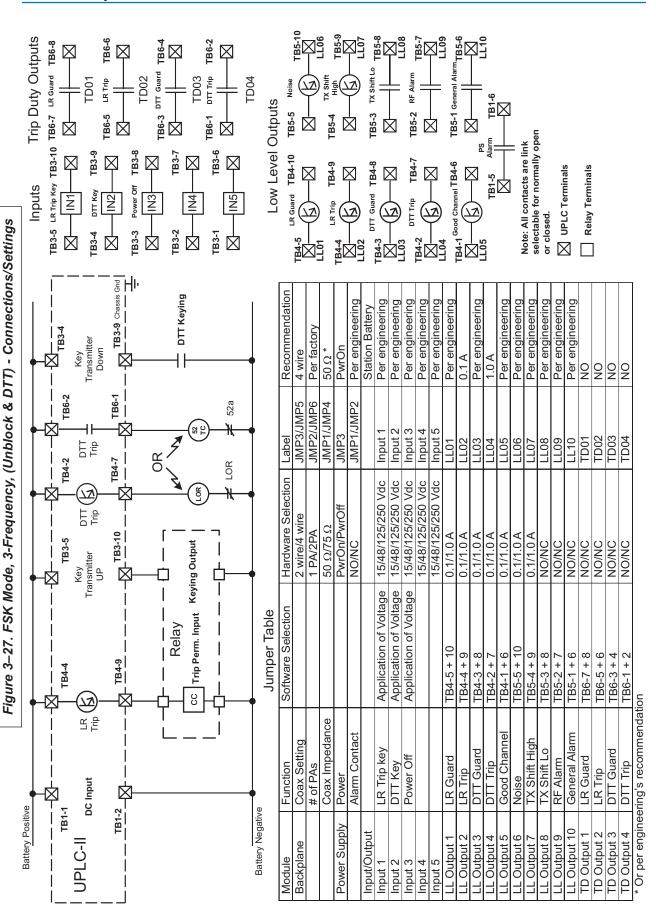


Figure 3–26. FSK Mode, 2-Frequency, DTT (Single Channel Transceiver) - Connections/Settings







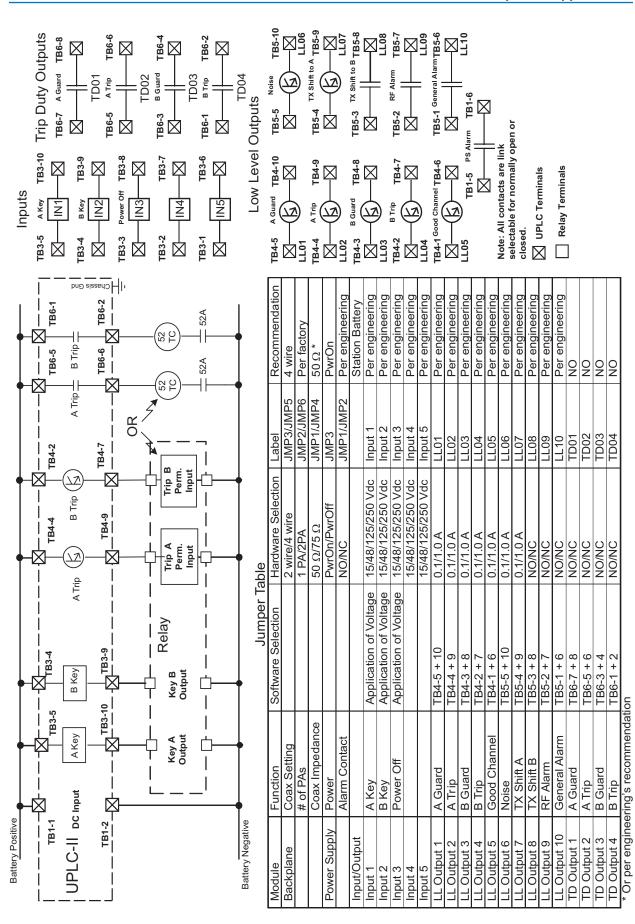


Figure 3-28. FSK Mode, 4-Frequency, (Unblock & DTT) - Connections/Settings



## 3.9 FSK Mode Alarms

The following tables show alarms for FSK mode.

Table 3–6.
Hardware Fixed Alarm (from Power Supply Board)
All Modes

Hardware Failure Alarm for All UPLC-II™ Units				
Alarm Reason:	One of the PS outputs is too low in voltage			
Alarm Name: (Available Outputs)	Power Supply Alarm Output (TB1-5 & 6)**			
	De-Energized State			
Contact Type:	N.O. Contact N.C. Contact			
UPLC-II™ Condition				
PS Good	Closed	Open		
PS Bad	Open Closed			
**For the Redundant Power Supply, use TB2-5 & 6				

Table 3–7.
Software Programmable Alarms/(Outputs from I/O Board)
FSK Mode

Hardware Failure Alarm for All UPLC-II™ Units					
Alarm Reason:	Hardware health of at least one card is bad				
Alarm Name: (Available Outputs)	General Alarm Output (LL08 – LL10)				
	De-Energized State				
Contact Type:	N.O. Contact N.C. Contact				
UPLC-II™ Condition	UPLC-II™ Condition				
All OK	Closed	Open			
Hardware Failure	Open	Closed			
Loss of DC Power	Open	Closed			



## Table 3–7 Continued: Software Programmable Alarms/(Outputs from I/O Board) FSK Mode

Transmit Alarm for FSK Units Only				
Alarm Reason:	TX signal level is ≥	TX low level setting		
Alarm Name: (Available Outputs)	Main RF Output (LL01 – LL10)			
	De-Energized State			
Output Type:	N.O. Output N.C. Output			
UPLC-II™ Condition				
Transmit ON	Closed Open			
Transmit OFF	Open	Closed		

Receive Alarms for FSK Units Only					
Alarm Reason:	Early Warning alarm, RX signal level has dropped below settable Fade Alarm threshold		Receiver stoppe signal has drop Margin or RX F	ped below Fade	
Alarm Name: (Available Outputs)	Fade Alarm Output (LL01 – LL10)		Good Channe (LL01 – LL10)	l Output	
	De-Energized State		De-Energized State		
Output Type:	N.O. Output N.C. Output		N.O. Output	N.C. Output	
UPLC-II™ Condition					
RX Signal Normal	Open Closed		Closed	Open	
RX Signal Low	Closed Open		Open	Closed	
Loss of DC Power	Open	Closed	Open	Closed	

<sup>\*</sup> Fade alarm is not fail-safe and has a different state for the alarm condition vs loss of DC power. Also Good Channel output must be used on outputs LL08-LL10 in order to be fail-safe as shown in this table.



	2-RU Type (Old Style)		1-RU Type (New Style)		
Description	Туре	Part No.	Type	Part No.	
Balanced Resistive Hybrid	H1RB	6266D72G05	Balanced	CH20-BALMN-001	
Balanced Resistive Hybrid (40W)	H1RB-40	6266D72G07	Balariood	OTIZO BITEINIT COT	
Skewed Hybrid (50Ω) with terminating resistor	H1SB-R	1609C45G03	Skewed	CH20-SKWMN-001	
Balanced Reactance Hybrid	НЗХВ	6266D71G03		None	
19" panel for mounting 3 Hybrids	2-RU	670B695H01			
19" Chassis for Mounting 4 Hybrids			1-RU	1088-780	

Table 3–8. Hybrid Options

For more details, please refer to the Hybrids System manual.

# 3.10 Hybrid Applications

The table shows the type of Hybrids and their associated part numbers. The purpose of the hybrid is to enable the connection of two or more transmitters together on one coaxial cable without causing intermodulation distortion due to the signal from one transmitter affecting the output stages of the other transmitter. Hybrids are also required between transmitters and receivers, depending on the application. The hybrid circuits can, of course, cause large losses in the carrier path and must be used appropriately. High/low-pass and band-pass networks may also be used, in some applications, to isolate carrier equipment from each other. A summary of some of the more important application rules are given below:

- All Ametek/Pulsar ON/OFF Carrier systems are designed to have their TX & RX bridged directly together in 2-wire mode without hybrids.
- 2. A Balanced Hybrid should always be used if combining 2 Transmitters. Never use a Skewed hybrid for this application.
- 3. A Skewed Hybrid will give 3 dB less TX loss and thus a 3 dB improvement in signal to noise ratio so it is the recommended hybrid for combining a FSK carrier set TX & RX together.
- 4. Hybrids should be arranged with the lesser losses in the transmitter path and the greater

- losses in the receiver path to provide more transmitter signal levels onto the power line.
- 5. ON/OFF DCB Carrier systems should be arranged with less losses than FSK systems when combining together with hybrids where possible, as they need higher signal/noise ratios than FSK systems.
- 6. If possible, transmitters used for common applications should be arranged for equal attenuation. For example, it is ideal to have Dual channel DTT Transmitters combined through the same balanced hybrid.

Specific Rules for Reactance Hybrids Only:

- 1. When applying transmitters to balanced reactive Hybrids, the frequency spacing between the widest spaced transmitters is about 4% for frequencies below 50 kHz and 6% for frequencies above 50 kHz. If this rule is not followed then the Hybrid cannot be adjusted to provide the best possible isolation between all transmitters.
- 2. When applying transmitters and receivers to a balanced reactive Hybrid the frequency spacing between the transmitter group and receiver group is of no concern; however, all the transmitter frequencies must meet the frequency spacing rule above. This rule is based on receivers with high input impedance.



## 3.10.1 Examples

Following are several figures that illustrate possible hybrid applications. A short description of each follows.

In these illustrations, Balanced (resistive Hybrids) are denoted as R Hybrids, Reactive Hybrids as X Hybrids and Skewed Hybrids as S Hybrids. Fig. 3–29 illustrates two transmitters being combined onto a single coax cable for connection to a line tuner. This would be a typical application for a dual channel, uni-directional trip system. The receive end of the system would not require a hybrid so that the receivers would be tied together via a T-connector and coax cable before connection into the line tuner. However, a single 50  $\Omega$  non-inductive resistive load should be bridged across the high impedance receivers to terminate the line tuner because there is no 50  $\Omega$  output transmitter also present.

When only one transmitter and one receiver are required as in a single channel bi-directional transfer trip system or a directional comparison unblocking system Fig. 3–30 can be applied. A skewed hybrid may be used in place of the reactive hybrid (X hybrid). The skewed hybrid has a designated transmit port and receive port.

When two transmitters and two receivers are being applied to a single coax cable, as in a dual channel bi-directional direct transfer trip system, Fig. 3–31 is appropriate.

When combining a DCB blocking carrier with a dual channel bi-directional DTT, Fig 3–32 is appropriate. The setup gives less hybrid loss for the ON/OFF DCB vs the FSK DTT, because the ON/OFF DCB requires a better signal/noise ratio.

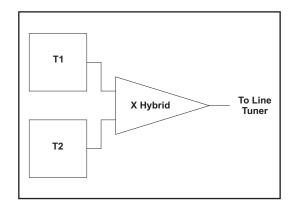


Figure 3–29. Hybrid Connections – Two Transmitters

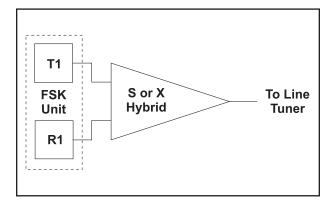


Figure 3–30. Hybrid Connections – Single Bi-Directional Channel



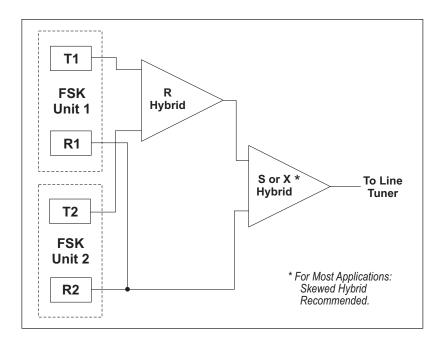


Figure 3-31. Hybrid Connections - Dual Bi-Directional Channel

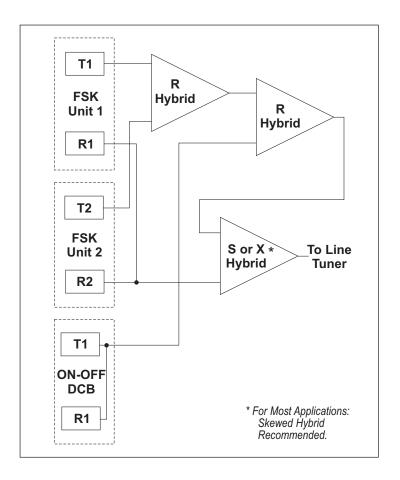


Figure 3-32. Hybrid Connections - DCB with Dual Bi-Directional DTT

# 4. Test Equipment, Maintenance & Troubleshooting

# Recommended Test Equipment

Table 4–1 shows the equipment used to test, service and verify your UPLC-II™ unit.

Table 4-1. Recommended Test Equipment

Equipment	Application
High-Impedance Frequency Selective Level Meter 1 kHz to 1 MHz • PowerComm Solutions PCA-4125 • Signal Crafters Model 110 • Spectrum Analyzer	Checking TX/RX Levels Checking Noise Levels
Reflected Power Meter • Signal Crafters Model 70 • PowerComm Solutions PCA-4125	Adjusting Line Tuner to Match UPLC-II™ Output Impedance
Signal Generator • Signal Crafters Model 90 or 110 • PowerComm Solutions PCA-4125	For Setting RX Sensitivity when no Remote TX is Available
<ul> <li>Non-Inductive Resistor, 50 or 75Ω</li> <li>Opek DL-60: 50Ω, 20W Load ¹</li> <li>DX Engineering DL30A: 50Ω, 15W Load ¹</li> <li>Loads Also Included in the Following Equipment</li> <li>PowerComm Solutions PCA-4125: 50Ω, 18W Input</li> <li>PowerComm Solutions Model 630: 50Ω, 25W Load</li> <li>Signal Crafters Model 70: 50Ω, 50W Load</li> </ul>	Transmitter Termination (For Calibration)



# **CAUTION**

We recommend that the user of this equipment become thoroughly acquainted with the information in these instructions before energizing the UPLC-II™ and associated assemblies. You should not remove or insert printed circuit modules while the UPLC-II™ is energized². All integrated circuits used on the modules are sensitive to and can be damaged by the discharge of static electricity. You should always observe electrostatic discharge precautions when handling modules or individual components. Failure to observe these precautions can result in component damage.

Requires a UHF Female to BNC Female Adapter to Interface Directly to the UPLC-II<sup>TM</sup>.

<sup>&</sup>lt;sup>2</sup> Except for Power Amp and Power Supply Modules, which are hot-swappable.



#### 4.1 Periodic Checks

Every 12 months, take the following readings on the UPLC-II<sup>TM</sup>. These values can also be accessed via the optional DNP3 protocol with SCADA.

- Transmitted Power Output
- TX Reflected Power
- Receive Level
- Receive Margin

Additionally, we recommend, inspecting, cleaning & re-adjusting any air spark gaps or replacing damaged gas tubes in the channel such as in the tuners and CCVTs.

We recommend that you keep a *log book* as a visible record of periodic checks, as well as a source for indicating any gradual degradation in a unit's performance.

# 4.2 Trouble Detection Sequence

#### 1. Check front door LEDs

DC Power On: Illuminated if Power Supply is functioning.

TX RF ON: Illuminated when transmitting.

#### 2. Front Display Spinner

Verify "spinning bar" is rotating. If it stops for longer than a few seconds then the software is locked up.

# 3. Front Display (Fig. 4-1) or Home page checks (Fig. 4-2)

Verify no alarms on front display or web pages. See next section.

Verify receiver fade margin of +15 dB +/- 3 dB when far end transmitter is keyed. (assuming default setting of 15 dB was used.)

Verify transmit and receive levels are as expected.

Press "Test" button on front key pad & verify % Reflected Power (or use home page), when transmitting.

#### 4. Module status LEDs

Open front door and verify green status LEDs are illuminated. (One on Power supply, one on Power Amp and two on Display board).

#### 5. Front Panel I/O Test

Use keypad I/O Test in Test menu for checking inputs/outputs & running tests.

#### 6. SOEs

Download SOE Events from each end of the system & look for problems or send to AME-TEK for analysis.

#### 7. Report File

Download settings "report" file from each end of the system & send to AMETEK for analysis. This is a good "as left" document that contains all software/hardware settings as well as TX/RX levels.

## 8. Timing Input

To best coordinate SOE's from different units, we recommend using the IRIG-B synchronized timing input.

# 4.3 Front Display Alarms

Hardware Failure Alarms

GENA - General Alarm

PS1 - Power Supply Main Alarm

PS2 - Power Supply Redundant Alarm

PA1 - Power Amp Main Alarm

PA2 - Power Amp Redundant Alarm

TRBD - Transmitter/Receiver Board Alarm

IOBD - Input/Output Board Alarm

DSPL - Display Board Alarm

Signal Level Alarms

FADL - Fade Alarm

MGAL - Margin Alarm

GSDL - Goose Signal Data Loss



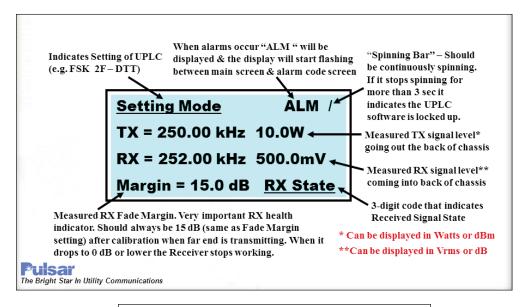


Figure 4–1. Front Panel Display Descriptions

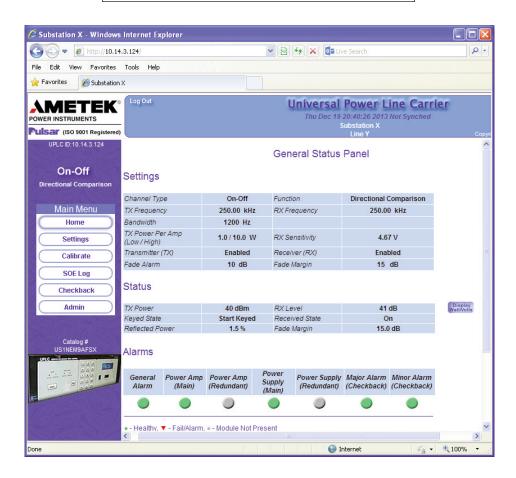


Figure 4–2. Example of the Home Page (ON/OFF Mode)



ON/OFF Checkback Alarms

CBMJ - Checkback Major Alarm

CBMN - Checkback Minor Alarm

RECO - Checkback in Recovery Alarm

FSK Mode Only Alarms

LOLV - Low Level Output

NOIS - Noise

## 4.4 Transceiver NOVRAM Battery

A SOE "Battery Failure" event indicates that the Transceiver board's NOVRAM battery has expired. The battery is a *Dallas Semiconductor DS9034PCX*. Some events may be lost if this battery expires. It supplies power to an event buffer. Typical life is greater than 20 years.

Replacement consists of removing the plastic cover from U30 on the Transceiver board. You will need to gently pry it off with a small flathead screwdriver by inserting the screwdriver into the rectangular slot. Replace the battery (observing the polarity) and snap the plastic cover back onto U30.

#### **NOTE**

It is highly recommended that you do not try to repair or modify individual boards in the field. Call customer service for an RMA number. 800-785-7274 or +1954-344-9822.

# 5. Installation/Commissioning Procedure

## **Quick Installation Guide**

- 1. Physically mount the unit per Chapter 2. (Page 2–8)
- 2. Wire the unit per your engineering documents or typical schemes as shown in Chapter 3.
- 3. Set hardware jumpers on I/O Module, Power Supply Module & Backplane. (Page 5–7)
- 4. Set up your laptop PC for communicating with the unit. (Page 5–10)
  - Ethernet port requires setting static IP address (Direct or LAN connection).
  - RS-232 port requires setting up a modem connection and static IP address.
- 5. Power up the unit.
  - (There is no power switch, simply plug Power Supply module in or out to turn power on or off.)
- 6. Connect to the unit via one of these ports: (Page 5–10)
  - Direct Ethernet (Front or Rear) or LAN Ethernet (Rear only)
  - RS-232 (Front)
- 7. Log in first time as user = administrator, password = pulsar. Enter new user as a "super user" with privileges of "admin" + "user". Log out & back in as the new super user. (Page 5–11)
- 8. Make software settings in the unit via one of the following two methods & submit. (Page 5–14)
  - a. Upload previously made company standard XML software file, on Load/Save Tab of Settings web page. Then modify as needed.
  - b. Use standard configurations on Load/Save Tab of Settings web page. Then modify as needed.
- 9. Calibrate the unit for incoming RX level. TX level is already calibrated to 1W/10W into a  $50\Omega$  load before shipping. (Page 5–31)
- 10.Document, by saving, the XML file and report file on Load/Save Tab of Settings web page. (Page 5–14)
- 11. Verify correct operation by looking at the TX/RX levels, RX Margin, TX reflected power on the front display or Home web page. Check LEDs on front door are correctly illuminated. (Pages 5–35, 5–36)



## **USER NOTES**



### 5.1 Introduction

The Universal Power-Line Carrier (UPLC-II<sup>TM</sup>) equipment has been designed to provide the user with an ease of installation that has never before been attainable in Power-Line Carrier equipment. The UPLC-II<sup>TM</sup> can be fully calibrated without the need for any instruments. It also provides the ease of software programmability for most of its functions, through the use of an internet browser. Thus, there is no need to install special software on the computer to configure the UPLC-II<sup>TM</sup>. This section describes the simple process that is needed to connect, configure and calibrate the Universal Power Line Carrier (UPLC-II<sup>TM</sup>).

## 5.1.1 Safety Precautions

Please review this installation information thoroughly before making any connections to the UPLC-II<sup>TM</sup>. Unless you are thoroughly familiar with the hazards involved in handling high voltage equipment, you should not handle the UPLC-II<sup>TM</sup> or connect any external apparatus.

# 5.2 Mounting/Connecting

## 5.2.1 Mounting

The UPLC-II<sup>TM</sup> unit is 3 RU tall and 13.5" deep and is designed to be mounted in a standard 19" wide panel. It can be flush or projection mounted by moving the mounting brackets to the appropriate location. Refer to Chapter 2 for more details.

#### 5.2.2 Terminal Block Connections

Permanent connections are made from the rear of the chassis on the UPLC-II<sup>TM</sup> backplane. Tables 5–1 & 5–2a/b list all the terminal block connection points. The terminal blocks can accept up to a

14 AWG wire with an AMP #320561, #320619 or #50881 or equivalent, ring lug installed on the end. See the Terminal Block Hardware Specifications table that follows. All power supply, input & output connections are not polarity sensitive except as noted in the tables. Some typical wiring connections to relay systems are shown in Chapter 3.

If there are any UPLC-II<sup>TM</sup> wires coming to or from the switchyard other than the coax, they should be shielded twisted pair to reduce transients to below the Surge Withstand Capability of ANSI C37.90.1.

The UPLC-II<sup>TM</sup> backplane is concealed with a 2-piece metal cover that is divided into a top and bottom section, with an RF foam gasket between the two sections. Remove only the top section for making all necessary connections. All outgoing wire will rest between the RF foam gasket. Do not bundle the wire where it comes through the RF gasket. Spread the wire in one layer across the total width of the gasket.

If maximum isolation is needed to prevent other devices' high level RF signals from affecting the UPLC-II<sup>TM</sup>, then the metal cover must be used.

#### 5.2.3 Equipment Ground

In addition to the UPLC-II<sup>TM</sup> chassis ground connection that is made through the cabinet or rack, a ground connection screw is provided on the backplane and on the lower right corner of the back cover. (See Figure 2–2.) Only one of these two chassis ground screws needs to have a wire connection to earth ground at the UPLC-II<sup>TM</sup> cabinet location. It is best to use a #10 ga. or larger wire, that is short & direct with no sharp bends in the wire, for this connection.

Table 5-1. Terminal Block Hardware Specifications

Terminal Block Designators	Description	Screw Size	Screw Head Type	Max. Torque	Distance Between Barriers	Wire Size Range
TB1, TB2, TB6	Single Row for DC Power & Trip Duty Outputs	#6-32	Philips/Slotted	9 lb-in	0.26" (6.6mm)	#14-22
TB3-TB5	Dual Row for Keying Inputs & Std. Low Level Outpouts	#6-32	Philips/Slotted	12 lb-in	0.26" (6.6mm)	#14-22
ТВ7	Single Row for External CLI Output	#3-48	Philips/Slotted	4 lb-in	0.20" (5.08mm)	#18-30



#### Note:

ALL inputs and outputs are non-polarity sensitive, except for the Power Supply Auxiliary output and the external CLI output.

Table 5–2a. Terminal Block Input Connections \*

Inputs	Terminal Block
Main Power Supply Input	TB1-1 & 2
Redundant Power Supply Input	TB2-1 & 2
Keying Input 1	TB3-5 & 10
Keying Input 2	TB3-4 & 9
Keying Input 3	TB3-3 & 8
Keying Input 4	TB3-2 & 7
Keying Input 5	TB3-1 & 6

Table 5-2b. Terminal Block Output Connections

LL Outputs- 1A Transistor *	Terminal Block
SS Output 1 (LL01)	TB4-5 & 10
SS Output 2 (LL02)	TB4-4 & 9
SS Output 3 (LL03)	TB4-3 & 8
SS Output 4 (LL04)	TB4-2 & 7
SS Output 5 (LL05)	TB4-1 & 6
SS Output 6 (LL06)	TB5-5 & 10
SS Output 7 (LL07)	TB5-4 & 9
LL Outputs- 0.25A Contact *	Terminal Block
EM Output 8 (LL08)	TB5-3 & 8
EM Output 9 (LL09)	TB5-2 & 7
EM Output 10 (LL10)	TB5-1 & 6

Optional Trip Duty Contacts *		
EM Output 1 (TD01)	TB6-7 & 8	
EM Output 2 (TD02)	TB6-5 & 6	
EM Output 3 (TD03)	TB6-3 & 4	
EM Output 4 (TD04)	TB6-1 & 2	
Power Supply Alarms/Outputs	Terminal Block	
Main PS*	TB1-5 & 6	
Redundant PS* (Opt.)	TB2-5 & 6	
Opt. PS Aux.**1	TB1-3(+) & 4(-)	
Opt. Red. PS Aux.**1	TB2-3(+) & 4(-)	
Other Outputs		
External CLI**	TB7-3(+) & 4(-)	

<sup>\*</sup> Non-Polarity Sensitive

<sup>\*\*</sup> Polarity Sensitive

<sup>&</sup>lt;sup>1</sup> For Driving Older EM Relays



#### 5.2.4 RF Coax Connections

The RF connections to the chassis are made using the J1 and J2 female BNC connectors. The cable used to make this connection must be a 50  $\Omega$  or 75  $\Omega$  coax cable, depending on the line tuner input impedance. A knife switch is sometimes placed in the rear of the cabinet housing the UPLC-II<sup>TM</sup> in order to service it.

If the carrier is set for *two-wire* mode: both the TX and RX would go through J1. If the carrier is set for *four-wire* mode: J1 = TX output & J2 = RX input.

#### 5.2.4.1 Coaxial Cable for RF Connections

A coaxial cable is required for a shielded, low-loss, path between the UPLC-II<sup>TM</sup> and the Line Tuner (in the switchyard).

The type of coaxial cable we recommend is RG-213/U (50  $\Omega$ , 29.5 pf/foot):

- #12AWG, (7–strand of #21AWG) copper center conductor
- Polyethylene insulator
- · Copper shield
- Vinyl jacket (nominal O.D. 0.405 inch)

We also recommend changing from RG-213 cable to the smaller diameter RG-58 coax cable at a terminal block once entering the cabinet. Alternately, you can connect directly to a hybrid or some device with a UHF type connector that can accept the RG-213 coax. The inputs of the hybrid would then be connected with RG-58 coax.

If the coaxial cable is to connect to related cabinets enroute to the switchyard, you should connect the RG-58 cable from J1 or J2, of the UPLC-II<sup>TM</sup>, to the related cabinets, and RG-213 from the cabinets to the switchyard. Keep the coaxial cable as short as possible and ground the outer braid of the coax only at the end connected to the UPLC-II<sup>TM</sup> and not at the line tuner end.



# CAUTION

The UPLC-II<sup>™</sup> does not ground the coax shield. It must be externally grounded to prevent surgerelated failure to the UPLC-II<sup>™</sup>.

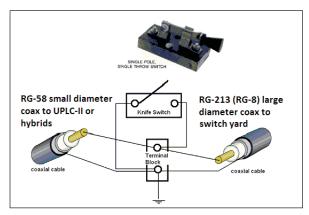


Figure 5–1. Coax Connections (ground at terminal block)

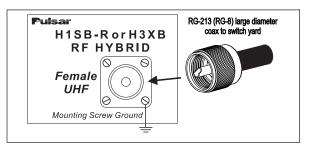


Figure 5–2a. Coax Connections (ground at old style 2RU hybrid)

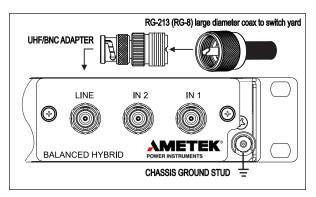


Figure 5–2b. Coax Connections (ground at 1RU hybrid)



# CAUTION

NEVER DISCONNECT THE CARRIER LEAD-IN BETWEEN THE LINE TUNER AND THE COUPLING CAPACITOR UNLESS THE LOW POTENTIAL END OF THE COUPLING CAPACITOR IS GROUNDED. BEFORE DISCONNECTING THE CARRIER LEAD-IN CONDUCTORS, CLOSE THE GROUNDING SWITCH AT THE BASE OF THE COUPLING CAPACITOR. IF THIS GROUND IS NOT PROVIDED, DANGEROUS VOLTAGES CAN BUILD UP BETWEEN THE LINE TUNER AND COUPLING CAPACITOR.



In order to ground the coax braid (shield), you can use an intermediate terminal block (Fig. 5–1), a UHF connector mounting screw on the old style 2RU hybrid (Fig. 5–2a) or ground stud on 1RU hybrid chassis (Fig. 5–2b).

#### 5.2.5 Other Connections

All the other connections to the UPLC-II<sup>TM</sup> are for alarm and information purposes. These inputs and outputs are listed here for reference purposes. Depending on the options ordered, these outputs may or may not be present. These will be listed from left to right looking at the rear of the chassis.

#### 5.2.5.1 Ethernet Connectors

Ethernet Ports: (TX1, RX1 & TX2, RX2)
 Depending on options ordered, these connections may be electrical RJ-45 or fiber ST connectors.

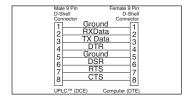
#### 5.2.5.2 Protocols Connector

Please refer to Chapter 7, "Communication Protocols" for more details.

 9-Pin D shell Connector (J4): This connector is for a permanent connection, which provides RS232 or RS485 access to the unit for the DNP3 communication protocol.

RS-232: (see figure below)
RS-485: pins 2 & 8 (TX +/-)
pins 3 & 7 (RX +/-)

 The rear Ethernet ports, listed above, can also be used for DNP3 and/or IEC 61850 communications. The front Ethernet port is not available for protocol communications.



Standard RS-232 Extension Cable

### **5.2.5.3 IRIG-B Input**

BNC Connectors (J13 & J14): These connectors are for the IRIG-B input. J13 is the input for a modulated IRIG-B signal and J14 is the input for a TTL Unmodulated IRIG-B

signal. Only one of these inputs should be used, not both at the same time.

**NOTE:** No setup is required for IRIG-B. Simply connect to the correct coax connector to match your source.

#### 5.2.5.4 CLI (Carrier Level Indicator) Output

• TB7-3(+) & TB7-4(-): These two terminals provide an output that tracks the RX fade margin level. It can be connected to an external voltage transducer which can then connect to SCADA to remotely read the receiver's margin, if desired. It requires an external source of 10–300 Vdc be applied in series with it. (Calibration of this output can be done through the front key pad or the web browser calibration page.)

## 5.2.5.5 Power Supply Outputs

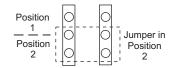
- TB1-3(+) & TB1-4(-): Main power supply Auxiliary output for feeding 20 mA or 200 mA to an electromechanical auxiliary blocking relay such as a KA-4 or SCA carrier auxiliary relay.
- TB1-5 & TB1-6: Main power supply failure alarm dry contact.
- TB2-3(+) & TB2-4(-): Redundant power supply Auxiliary output for feeding 20 mA or 200 mA to an electromechanical auxiliary blocking relay such as a KA-4 or SCA carrier auxiliary relay.
- TB2-5 & TB2-6: Redundant power supply failure alarm dry contact.

# 5.3 Hardware Jumper Settings

Some of the settings on the UPLC-II<sup>TM</sup> require the use of a hardware jumper. These are settings, which involve selections being made on circuits that are in surge sensitive areas. The jumpers are dual jumpers because one side is the actual jumper setting and the other is the sensing side. The microprocessor can then look at the sensing side and report the physical jumper setting on the web pages and in the settings download file, without having to open the unit to view them. Although it looks like two separate jumpers for each selection, it is really a ganged jumper.



Care should be used to make sure the jumper is always connected to the correct 4 pins.



An explanation of jumper positions, on different boards within the UPLC-II<sup>TM</sup>, is provided here. However, for more detailed information such as jumper location on particular boards, please refer to chapter 2.

## 5.3.1 Backplane (Rear Panel)

JMP 1/4 - 50 or  $75\Omega$ : Selects transmitter output impedance

JMP 3/5 - 2 or 4 wire: Sets RF coax connection

If set to 2-wire, then the transmitter and receiver are on a common coax on the rear (J1), as in most ON/OFF applications. If set to 4-wire, then the transmitter outputs on coax connector J1 and the receiver input is on coax connector J2, as in all FSK applications and a few ON/OFF applications (e.g. when using an external amplifier).

JMP 2/6/7: 1 or 2 Power Amplifiers. Set according to the number of power amplifiers present.

#### 5.3.2 I/O Module

INPUT 1	)
INPUT 2	
INPUT 3	
INPUT 4	
INPUT 5	

15V, 48V, 125V or 250V: Inputs are set according to keying voltage for the given input. This jumper establishes the minimum keying threshold voltage which is greater than half station battery voltage to prevent accidental keying.

LL01 LL02 LL03 LL04 LL05 LL06 LL06

1.0A/0.1A: Low level solid state outputs are set according to load level. This jumper sets the solid state output current capability. Microprocessor relay inputs should be set for 0.1A. Greater loads should use the 1.0A setting such as modern lockout relays. As the heavy duty transistors in the solid state outputs leak very small currents, the 0.1A setting totally prevents this phenomenon from accidentally turning on the low current inputs of a microprocessor relay or other low current device.

LL08 LL09 LL10

NO/NC: Low Level contact outputs are set according to desired position when a relay coil is de-energized. When not energized, the contact will be NO (Normally Open) or NC (Normally Closed).

TD01 TD02 TD03 TD04

NO/NC: Trip Duty contact outputs are set according to desired position when a relay coil is de-energized. When not energized the contact will be NO (Normally Open) or NC (Normally Closed).



### 5.3.3 Power Supply Module

JMP1/JMP2: NO/NC Selects the contact position when the relay coil is de-energized. This relay coil is fail-safe and energized when the power supply is functional. Therefore set the contact to NO if you want the contact to open for alarm or NC if you want the contact to close for alarm.

JMP3: PWR ON/PWR OFF allows for de-energizing the module when inserted into the chassis with DC power applied. Normally set to PWR ON.

## 5.3.4 Aux. Power Supply Module (for driving EM protective relays)

JMP1/JMP2: 46V (20mA) / 20V or 8V (200mA) - allows you to select either a 20mA or 200mA capable source for use with carrier auxiliary relays such as KA-4 (ABB relay).

JMP3: 46V/20V - if JMP1/2 is in the (46V/20V) position, this allows selection between the 46V or 20V option. The 46V option is used for 20mA carrier auxiliary relays such as KA-4 (ABB relay). The 20V option is used for solid state relay systems such as ABB's STU or SKAU relay systems. **Note:** This jumper setting doesn't matter when JMP1/JMP2 is set for 8V/200mA.

## 5.3.5 Power Amplifier Module

JMP1/JMP2: (Frequency Select ON/OFF) - Always set for ON in a UPLC-II<sup>TM</sup>. This enables the frequency selectivity capability for the built-in TX reflected power meter, so that this meter reads correctly for its own TX frequency. It is unaffected by other transmit signals coming into it.

For older UPLC units without the supporting hardware, this jumper allows the Power Amp to be used in them without a problem by setting to OFF.



# Hardware Jumper Settings Worksheet (Shipping Defaults shown with a $\sqrt{\ }$ )

Module	Jumper	Selection	Description
Backplane	JMP1/4	<u>√</u> 50Ω75Ω	J1-TX Impedance
	JMP3/5	√ 2-wire4-wire	TX/RX Connect
	JMP2/6/7	<u>√</u> 1-PA <u></u> 2-PA	Single/Dual PA
I/O Module	INPUT 1	15V48V _ <u>√</u> 125V2	250V Keying Voltage
	INPUT 2	15V48V <u>√</u> 125V2	250V
	INPUT 3	15V48V <u>√</u> 125V2	250V
	INPUT 4	15V48V <u>√</u> 125V2	250V
	INPUT 5	15V48V <u>√</u> 125V2	250V ¥
Output	LL01	0.1A <u>√</u> 1.0A	Max. Current
	LL02	0.1A <u>√</u> 1.0A	
	LL03	0.1A <u>√</u> 1.0A	
	LL04	0.1A <u>√</u> 1.0A	
	LL05	0.1A <u>√</u> 1.0A	
	LL06	0.1A <u>√</u> 1.0A	
	LL07	0.1A <u>√</u> 1.0A	
	LL08	<u>√</u> NONC	Contact NO/NC
	LL09	NO <u>√</u> NC	
	LL10	NO <u>√</u> NC	
optional	TD01	<u>√</u> NONC	
optional	TD02	<u>√</u> NONC	
optional	TD03	<u>√</u> NONC	
optional	TD04	<u>√</u> NONC	
Power Supply	JMP1/2	NO _√NC	PS Alarm Contact
	JMP3		PS Enable/Disable
Aux. PS	JMP1/2	46V(20mA)/20V <b>or</b> <u>\lambda</u> 8V(200mA	A) 20mA or 200mA
(Optional for E		,	source, or 20V
Relay Interface	<i>,</i>		
Power Amp	_		
	Freq. Sel.		Freq. Selectivity



# 5.4 PC Setup for Communication with the UPLC-II™

PC to UPLC-II<sup>TM</sup> communication is established;

- 1. Via front or rear Ethernet ports directly through an Ethernet cable. (may use either cross-over or straight-through cable, as it automatically detects the cable)
- 2. Via rear Ethernet ports through a router/switch over private Ethernet network.
- 3. Via front RS-232 port.

All require making some one-time settings on your PC. The Ethernet port connection is the easiest to set up and operates 100X faster than the RS-232 port. So when possible, this is the best port to use. The UPLC-II<sup>TM</sup> Ethernet ports all have one common IP address. Only one port at a time can be accessed for viewing web pages. (Port 80 is the Ethernet internal socket port number used for accessing the units via the web pages.)

#### NOTE

The "PING" command is disabled in the UPLC-II™. And can not be used.

## 5.4.1 Ethernet Port – PC/UPLC-II™ Setup

**Note:** The front Ethernet port, although always mounted on the front door, will only be operational if you ordered the Ethernet option. This option is a small auxiliary board that mounts on the Transceiver board. See the Ethernet board section in Chapter 2 for details.

The default UPLC-II<sup>TM</sup> IP address when shipped is 192.168.0.10 and can only be changed by accessing the unit through its front panel keypad. The IP address will need to be changed when putting the UPLC-II<sup>TM</sup> on a corporate LAN to match up with that system. Otherwise, if just accessing directly with a laptop, without being on a corporate LAN, then you can just use the default IP address.

# 5.4.1.1 Changing the UPLC-II™ Default IP Address (when needed)

**Note:** On the front keypad, the SET button is the same as an "enter" key and must be pressed after

entering a value usually. The ESC (Escape) key is used to back out of menus.



- 1. Using the front keypad, press the SET button. You will be prompted for the password (default is "4050") to enter using the keypad. (Also displayed below the prompt will be the 11-digit UPLC-II<sup>TM</sup> electronic catalog number.)
- 2. Press "2" = menu choice "Configure".
- 3. Press "2" = menu choice "IP Address".
- 4. Press the SET button and then it will allow you to edit the IP address by entering the four 3-digit number groups separated by periods. Use the keypad numbers and forward/back arrow scroll keys to modify as needed. Press the SET button again to enter.
- 5. Scroll down to change the default Gateway to match with the IP address with the last digits of the gateway address usually being "001".
- 6. The Mask default of 255.255.255.0 should normally not need to be changed.
- 7. After entering, press the ESC key to escape out of the menu and to automatically save the settings.

# 5.4.1.2 PC Setup – Direct Ethernet Connection

A static IP address must be set up on your computer to directly connect to the UPLC-II<sup>TM</sup> as all computers are by default set to automatically assign an IP address. The IP address of your computer needs to be manually assigned to be on the same subnet as the UPLC-II<sup>TM</sup>, but with a different IP address. For example, if the UPLC-II<sup>TM</sup> has the IP address of 192.168.0.10 then your computer's IP address can be set for 192.168.0.9 or any other number not ending in 10 with the same subnet. The procedure for changing your computer's IP address is dependent on the type of computer operating system being used. See Appendix B.



# 5.4.1.3 PC Setup – Ethernet Connection via Router/Switch

The IP address of the UPLC-II<sup>TM</sup> must match the subnet of the Ethernet network (LAN) which usually means changing the IP address of the UPLC-II<sup>TM</sup> from its default, as explained previously. Also you must change your computer's IP address which is dependent on the type of computer operating system being used. See Appendix B.

#### 5.4.2 Front RS-232 Port – PC Setup

The UPLC-II<sup>TM</sup> front panel is a DCE serial port. Since most computer serial ports are DTE devices, a standard straight through serial cable may be used to connect the UPLC-II<sup>TM</sup> to a computer via the serial port. If the device you are connecting to is a DCE device, use a null modem cable.

Connecting your computer to the UPLC-IITM

- 1. After initially powering up the unit, wait approx. 1 min. prior to accessing the unit.
- 2. Connect a straight-thru serial cable between your computer serial port and the front serial port on the UPLC-II<sup>TM</sup>.
- 3. Either double click the connection icon you placed on your desktop from the configuration procedure in Appendix A or double click the "My Computer" icon on your desktop.
- 4. Under My Computer double click on "My Network Places" icon and then double click on "view network connections."
- 5. Then double click on the direct connection you set up from the procedure in Appendix A to talk to the UPLC-II<sup>TM</sup>.
- 6. The connection window will pop up. Leave the user name and password blank. Click on the "Connect" button.
- 7. You may see a dialog box pop up that says "dialing..." and this is ok. Then you will see "Verifying username and password....." After that you will see "Registering your computer on the network..." The dialog box will go away and you will get confirmation that you are connected. Should you get a 777 error after "dialing", close the window and restart the direct connection. Do not "redial".

8. Now open Internet Explorer. In the address bar enter http://100.100.100.100 and then hit Return. You will then be asked for a username and password. An example of the login screen is shown below.

# 5.5 Logging In

After your PC is set up, open a web browser window and enter the correct IP address into the address bar. Internet Explorer (IE) is recommended though other browsers will work but might not display all the pages cosmetically correct. If using IE8 or higher then you should put it into compatibility view for best viewing. The following login window should pop up within seconds after entering the IP address.



If this is the first time logging into a UPLC-II<sup>TM</sup>, enter the default user name and password shown below.

- Default user name = *administrator*
- Default password = *pulsar*

#### NOTE:

Only one person (except for Management user) can access the UPLC-II™ at a time. If the keypad is being used and in a menu it will also limit what someone logging in via the web pages can do.

This will take you to the UPLC-II™ Home page.

#### NOTE

Refreshing any web page will automatically return you to the UPLC-II™ home page.



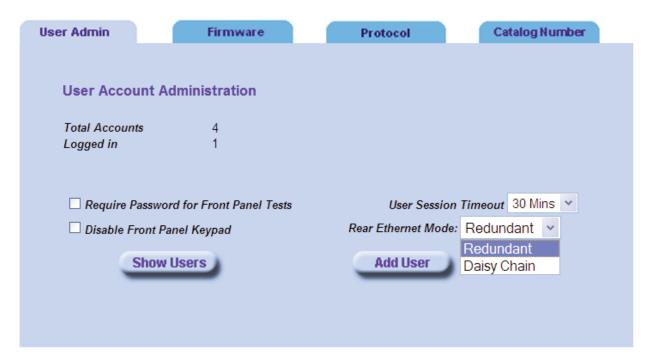


Figure 5–3. Example of the User Admin Tab on the Admin page

#### NOTE:

Any items selected on the User Admin tab are submitted automatically without doing anything else.



# CAUTION

A DEFAULT USER NAME "administrator" AND A DEFAULT PASS-WORD SET TO "pulsar" HAS BEEN PROVIDED WHEN THE UNIT IS SHIPPED. IT IS YOUR RESPONSIBILITY TO CHANGE THE DEFAULT PASSWORD TO SOMETHING DIFFERENT TO ENSURE THE SECURITY OF YOUR UPLC-II™. AMETEK IS NOT RESPONSIBLE FOR THE SECURITY OF THE SYSTEM.

#### Additional items on the User Admin Tab that can be set include:

- Setting a password requirement to enter the front keypad TEST menu (The Settings menu always requires a password, but the TEST menu can be set for either with or without a password requirement.)
- Disabling the front panel keypad if desired for security reasons (The keypad only has a numerical password and if a stronger password is required then it can be disabled and later turned on by logging in to the web pages with a strong password.)
- Web browser session timeout period, 5–30 mins (This is how long it will be before a user will be automatically logged out when on any web page and not interacting with the page. The exception is the Home page as it has no time out. If accidentally disconnecting without logging out first, this timeout is also how long you must wait to be allowed re-entry without power cycling the unit.)
- Dual rear Ethernet ports can be redundant or daisy chain mode. (The redundant mode means that if one rear port fails, it will switch over to the other in a few seconds if you have a second network. The daisy chain mode allows you to connect to a close-by second Ethernet enabled device using the UPLC-II<sup>TM</sup> as a switch rather than running a separate long cable to it. These modes do not apply to the front Ethernet port which is completely isolated from the rear ports.)



Level	Add / Change	Upgrade	Setting	TX / RX	Up / Down	View	Remote
(Priviledge)	User Accts	Firmware	Changes	Calibrate	Load Files	Only	Access*
Guest						Х	
User			Х	Х	Х		
Admin	Х	Х					
Superuser (Admin+ User)	х	Х	Х	Х	Х		
Management	X						Х

Table 5-3. Authority Level Matrix

## 5.5.1 Admin Web Page

Once logged in, initially you will need to set yourself up as a "super user" by clicking on the Admin button in the main menu. Then you can click on the Add User button as shown in Figure 5–3.

Next you add a new user name and enter the password twice and give yourself the privileges of *User* and *Administrator* for your "super user" login. Passwords (case sensitive) can be any combination of up to 8 characters, i.e. upper/lower case letters, numbers and special characters (*no spaces allowed*). User names share the same attributes but can be up to 30 characters. Spaces will be automatically deleted and should not be used.

Then click on the Log Out text in the top left of the screen to exit, so you can log back in as the newly created "super user".

When you log back into the UPLC-II™ as a super user, you will have full access to all its features and can now make settings.

#### NOTE:

If you have other tabs open in IE, it will save your log-in credentials and automatically log into the UPLC-II™ using the last used credentials. To prevent this you need to completely close all open browser windows/tabs and then open a new browser window to log in with your new credentials.

#### 5.5.2 User Accounts

User accounts allow limited access to the maintenance and setting of the UPLC-II<sup>TM</sup>. This is required security to prevent unauthorized access.

There are *five* levels of access allowed through the user account. The UPLC-II<sup>TM</sup> is provided from the

factory with only one administrator level account.

The "administrator" can only assign user accounts and upgrade firmware.

The "guest" level can only view, and cannot make any changes.

The "user" level has the ability to make setting changes, calibrate the unit and download files such as the SOEs and settings.

The fourth level is the "super user", which is the combination of the admin-



Fig. 5-4. Example of Creating a Super User on the User Admin Tab

Via URL Commands



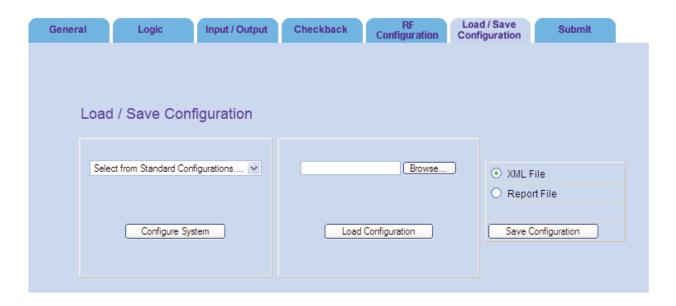


Figure 5-5. Example of Load/Save Confguration Tab on the Settings Page

istrator level and the user level. To Select super user level, check both the user and administrator level boxes.

The fifth level is the "Management" user and is intended for an IT administrator (see Appendix D).

# 5.6 Making/Saving Settings

It is always best *first* to go to the Load/Save Tab of the Settings button web page when making settings, see Figure 5–5. It is recommended to make and save your own company standard settings files for various configurations (ON/OFF DCB, FSK DTT, FSK UB etc.) when connected to a UPLC-II<sup>TM</sup> and then upload these files into a new UPLC-II<sup>TM</sup>.

#### 5.6.1 Loading Settings

 If starting from scratch with entering settings, then choose from the default configurations already in the UPLC-II<sup>TM</sup>.

ON/OFF Directional Comparison

ON/OFF Phase Comparison

FSK 2-Freq. Unblocking, DTT, POTT

FSK 3-Frequency

FSK 4-Frequency

FSK Phase Comparison

Click on the "configure system" button and next click on the Submit Tab and the submit button to save these settings. This loads default settings that are close to what would normally be needed and these can then be modified as needed and resubmitted.

• To Upload a previously stored settings file just click on the "Choose File" button and browse to where it is located and click on Load Configuration. Then usually you only need to modify frequencies, station/line name, checkback test address (if enabled), then submit settings assuming the input/output connections stay the same.

## 5.6.2 Saving Settings

• To Save software settings for re-use later in case something happens to your Transceiver board, click on XML File and Save Configuration. This stores all the software settings in a format that can be loaded into another UPLC-II<sup>TM</sup>. Enter the name you want to call this configuration file, and add an XML extension. It is required that the saved file have an XML extension in order to upload it to a unit. The UPLC-II<sup>TM</sup> does not automatically do this for you.



In addition to the XML file, you may save a report file that is more readable. A sample is provided here:

Software Revision: 4.01	Trip Duty Outputs			
Unit IP: 10.14.3.52	1. Selection: LR Guard NC Contact			
MAC Address: 00:07:5E:00:20:1C	2. Selection: LR Trip NC Contact			
Catalog Number: US1NEM9AFSX	3. Selection: DTT Guard NC Contact			
Date/Time: Fri Sep 19 14:30:30 2014	4. Selection: DTT Trip NC Contact			
System ID (Major): Substation X	Power Supply Alarms Contacts			
System ID (Minor): Line Y	Main Power Supply Normally Closed			
of coom in the first of the fir	Redundant Power Supply: Not Installed			
General Settings				
Channel Type: FSK	Low Level Outputs			
Function: 3-Frequency	1. Selection: LR Guard			
Rear Ethernet Mode: Redundant	De-energized State: NO			
Transmit Frequency: 250.00 kHz Receive Frequency: 252.00 kHz	Action: Normal			
Receive Frequency: 252.00 kHz	Max Load: 1.0A			
TX Shift-Bandwidth: 600 ± 250 RX Shift-Bandwidth: 600 ± 250	2. Selection: LR Trip			
	De-energized State: NO			
RF coax connection: 4 Wire	Action: Normal			
RF Impedance: 50 Ohms	Max Load: 1.0A			
Transmit Power Low: 1.0 W Transmit Power High: 10.0 W	3. Selection: DTT Guard			
Transmit Power High: 10.0 W	De-energized State: NO			
RX Sensitivity: 118.1 mV	Action: Normal			
rade Alalin. 10 db	Max Load: 1.0A			
Fade Margin: 15 dB	4. Selection: DTT Trip			
Reflected Power Alarm: 15 %	De-energized State: NO			
Transmitter: Enabled	Action: Normal			
Receiver: Enabled	Max Load: 1.0A			
Current margin: 15.0 dB	5. Selection: Fade Alarm			
Current receive level: 9 dB	De-energized State: NO			
Current transmit power: 30 dBm	Action: Normal			
Current reflected power: 0.0%	Max Load: 1.0A			
Session Time Out: 30 Min.	6. Selection: Good Channel			
	De-energized State: NO			
Logic Settings	Action: Normal			
CB Trip Test: Enabled	Max Load: 1.0A			
Line Relay Settings	7. Selection: TX Shift Low			
Pre-Trip Delay: 4 ms	De-energized State: NO			
Trip Hold: 0 ms	Action: Normal			
Guard Hold: 0 ms	Max Load: 1.0A			
Unblock Timer: 150 ms	8. Selection: Reflected Power			
Unblock Delay: 10 ms	De-energized State: NO			
Guard Before Trip: Required	Action: Normal			
Direct Transfer Trip Settings	9. Selection: Main RF Output			
Pre-Trip Delay: 30 ms	De-energized State: NO			
Trip Hold: 0 ms	Action: Normal			
Guard Hold: 0 ms	10. Selection: General Alarm			
Guard Before Trip: Required	De-energized State: NC			
Input Output Settings	Action: Normal			
Inputs Sectings	Trip Test Settings			
1. Hold: 0.0 ms	Auto Test: On			
Selection: LR Key	Trip Test Type: CB Trip			
Active State: Application of Voltage	Trip Test Type: Periodic			
Voltage: 125	Trip Test Hours: 6:00			
2. Hold: 0.0 ms	Trip Test Hours: 0.00			
Selection: DTT Key	Trip Test Hours: 18:00			
Active State: Application of Voltage	Trip Test Hours: 0:00			
Voltage: 125	Trip Test Period: 72			
3. Hold: 0.0 ms	111b 1600 161100' 15			
Selection: Power Off	Options			
Active State: Application of Voltage	Configuration: Single Transceiver			
Voltage: 125	Power Supply: 110/125/250 Vdc			
4. Hold: 0.0 ms	Redn. Power Supply: None			
Selection: Trip Test	Outputs: Standard Outputs w/ Trip Duty			
Active State: Application of Voltage	Logic: Standard Standard			
Voltage: 125	Ethernet Ports (Rear): Redundant/Daisy			
5. Hold: 0.0 ms	Chain 2 RJ-			
Selection: SOE Event 1	45(10/100 BaseT)			
Active State: Application of Voltage	Protocols: DNP 3.0			
Voltage: 125	Front Port: Ethernet / RS-232			
120	Testing: ON-OFF CB Test / FSK Trip Test			
	Power Amp Features: Improved Power Amp w/			
	Freq Selectivity for Refl Power			



 To Make an "as-left" document that records all software settings, hardware jumper settings, firmware version, catalog number, current TX and RX signal level, receiver sensitivity setting, etc, then choose Report File and click on Save Configuration. This stores all this information into a simple text file.

If a pop up "save to location" window does not appear this means your browser settings are preventing this. To get around this usually you can first hold down the CTRL key on your computer before clicking on the "Save Configuration" button and keep the CTRL key down until you see a pop-up window asking where you want to save your set-

#### NOTE:

If the Download dialog box doesn't appear, disable all pop-up blockers or add the UPLC-II™'s IP address to the trusted sites and check the following setting. Click on the "Tools" button, which should be in the upper right hand corner of the Explorer window. Then in the drop down menu, click on "Internet Options." In the Internet Options dialog box, click on the "Security" Tab and then click on the "Custom Level..." button at the bottom. Scroll down the list until you find a heading called "Downloads." Make sure the selection "Automatic prompting for file downloads" is enabled. If not enabled, click on the radio button. Likewise, "File download" should be enabled. If you can't enable these buttons, see your system administrator.

tings file. Then you can release the CTRL key and continue as normal. See note below for how to change IE settings to prevent this so you don't have to hold down the CTRL key.

#### 5.6.3 Working vs Temporary Settings

The UPLC- $II^{TM}$  stores its configuration in two sets: *Working* and *Temporary*.

The Working set is nonvolatile, and will be saved even if the unit is turned off. It holds the actual settings the UPLC- II<sup>TM</sup> uses for operation.

The Temporary set is a volatile set that's lost if the unit is turned off. Except when you're editing settings, these two sets are identical.

The Home page shows some of the Working settings, while the Settings pages show the Temporary copy of these settings. All settings are changed from the Settings pages and any changes you make will only affect the Temporary settings. The Working settings won't be changed unless you specifically "submit" your changes on the Submit page. Having two copies of settings allows you to change the UPLC-II<sup>TM</sup>'s settings while it continues to operate as normal on your bench or on-line in the field.

You can also use the UPLC-II<sup>TM</sup> to help you create a configuration file for future use with another UPLC-II<sup>TM</sup>. Edit the Temporary set as usual to create the alternative settings. Then, rather than submitting these settings, "Save" them. If you are just saving the settings, it is a good idea to discard the settings after saving them to a file. You can discard the Temporary settings by going to the submit page and clicking on the discard button. If you don't do this, clicking on the "logout" button will also cause the Temporary settings to be discarded. If you don't logout, the unit will discard all temporary setting changes after an hour of no activity on the serial or Ethernet ports.

Any time you've made at least one settings change either by manually editing or loading a Configuration file, a red bar stating "Changes Pending" will appear at the top of the page. Once you submit or discard these new settings, it will disappear.

# 5.7 Settings Pages

Once you have loaded either a previously made company standard settings file or a UPLC-II<sup>TM</sup> standard configuration file on the Load/Save Configuration Tab to get you in the correct general area, then you can modify particular settings to satisfy your specific installation needs. When you click on the "Settings" button on the left menu bar you will be presented with the settings tabs for the UPLC-II<sup>TM</sup>. These settings pages change depending on the mode you are in (e.g. ON/OFF DCB, FSK 2F DTT etc.). Note the tabs at the top of the white area, General, Logic, Input/Output, etc.. These tabs are where all the settings are made to the UPLC-II<sup>TM</sup>. Some tabs have multiple pages underneath them



that are revealed when you click on buttons on that particular tab. The tab that is seen first is the General Settings for the connected unit. The bold items are the set items which can be changed. The settings shown in blue are actual hardware jumper settings, which are sensed and can not be changed in the software.

#### NOTE:

Once any settings on a web page are made you must always click on the "Continue" button, if not, you will lose these settings changes. You will then automatically be directed to the next successive screen for the settings. And if you had made any changes on the last page you will see a narrow red bar appear at the top of the window that has the words "Changes Pending" in it. This indicates that settings changes have been made and have not been sent to the UPLC-II<sup>TM</sup> yet. If you shut down your computer at this point you will lose these settings.

If the user account you have used to log into the UPLC-II<sup>TM</sup> is set to "User" rights then you will see a "Change Settings" button below the Current Settings table on the web page. If you do not see this button then your user account does not have rights to make changes to the settings and you can only view the settings. You must then logon with a user name that has rights to make changes if you desire to change the settings.

## 5.7.1 General Tab

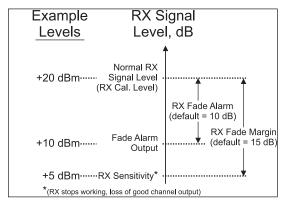
When you click on the change settings button on the General settings page (Fig. 5–6 & 5–7), you will see the first items that need to be selected. At the top, is the System ID1 and System ID2 Setting. These two boxes allow you put an identification you want the unit to show in the Title bar of the web pages. One suggestion here might be to identify the substation name with the line name and breaker number that the carrier set's associated relaying is connected to.

The last item to select is the most important. That is, do you want this unit to be a Frequency Shift Keyed (FSK) or ON/OFF type? This setting will affect all the other settings you are presented on the next pages.

On the second screen of the General Settings Tab you will see more items to set. These items depend on whether ON/OFF or FSK is selected. See Table

5–4 and Table 5–5 for the setting options that appear.

The RX sensitivity setting is not input directly but is a level automatically calculated when the receiver is calibrated. It is the minimum level at which the receiver will work. It is equal to the fade margin dB amount below the RX level at which the last calibration was done. The RX fade alarm setting gives an early warning alarm output when the RX signal drops by the dB level to which it was set. But the RX fade margin is the dB drop level at which the receiver stops working. Therefore the RX fade alarm is always set for a lower dB amount than the RX fade margin. See the following figure.



RX Fade Alarm & Fade Margin

If the unit is a Transceiver, it can also be set to TX only or RX only if desired. Changing this setting does erase all the I/O selections requiring them to be selected.

The TX Reflected Power Alarm setting is the only setting that can't be accurately set before communicating with the UPLC-IITM. The reason being is that the TX reflected power level is dependent on the line tuner in the substation yard being adjusted first so you know at what value to set the alarm threshold. Once the line tuner has been adjusted for minimum TX reflected power then the TX Reflected Power Alarm should be set to approx. 15% higher than this measured value shown on the Home page in the Status section. This is to prevent nuisance alarms and SOEs. There is no way to turn these SOEs off.

This concludes the General settings on the unit. When complete, click on the "Continue" button and you will be taken to the Logic Tab.





Figure 5–6. Example of The General (Settings 1) Tab on the Settings Page (ON/OFF Mode)



Figure 5–7. Example of The General (Settings 2) Tab on the Settings Page (FSK Mode)



# Table 5–4. General Settings (ON/OFF Mode)

	Selection	Steps
Function	Directional or Phase Comparison	N/A
TX Frequency	30 to 535 kHz	10 Hz
RX Frequency	30 to 535 kHz	10 Hz
Bandwidth	600, 1200 or 4,000 Hz	N/A
TX Power*	Low Power / High Power (0.3 to 10 W)	0.1 W
(RX) Fade Alarm	1 to 25 dB	1 dB
(RX) Fade Margin	1 to 25 dB	1 dB

Table 5–5. General Settings (FSK Mode)

	Selection	Steps
Function	Phase Comparison, Unblocking-2F POTT/DTT-2, 3 or 4 Frequency	N/A
TX Frequency	30 to 535 kHz	10 Hz
RX Frequency	30 to 535 kHz	10 Hz
Frequency	300 Hz ± 100 Hz	N/A
Bandwidth/Shift	600 Hz ± 100 Hz	
	600 Hz ± 250 Hz <sup>2</sup>	
	1200 Hz ± 250 Hz	
	1200 Hz ± 500 Hz <sup>2</sup>	
TX Power <sup>1</sup>	Low Power (Guard Freq.) / High Power (Trip Freq.) - (0.3 to 10 W)	0.1 W
(RX) Fade Alarm	1 to 25 dB	1 dB
(RX) Fade Margin	1 to 25 dB	1 dB
TX Reflected <sup>3</sup> Power Alarm	0 – 100%	1%

<sup>&</sup>lt;sup>1</sup> For units with a redundant Power Amp module, the TX power is for only one Power Amp. So for a 1W/10W setting the total TX power is twice this setting or 2W/20W.

<sup>&</sup>lt;sup>2</sup> These are the only 2 frequency bandwidth & shifts available for 3-frequency mode. Also 4-frequency mode uses special shifts (refer to page 2-1).

<sup>&</sup>lt;sup>3</sup> Normally this should be set to about 15% higher than the actual measured valued on the Home page to avoid nuisance alarms & SOEs.



## 5.7.2 Logic Tab

See Fig. 5–8 (ON/OFF Mode) & 5–9 (FSK Mode). In the logic settings all the time selections are changed in increments of 1 ms. The others are similar. See Chapter 2 for definitions of the various logic settings.

ON/OFF Directional Comparison & Phase Comparison Logic settings are shown in Table 5–6.

Caution should be taken when considering setting receiver dropout delay to anything other than 0 ms. Applying a setting of 1-15 ms can adversely affect relaying logic such as transient blocking logic.

FSK Logic settings for the different functions are shown in Tables 5–7 through 5–11. Note that GBT=Guard Before Trip.

When you have completed the logic settings click the "Continue" button.

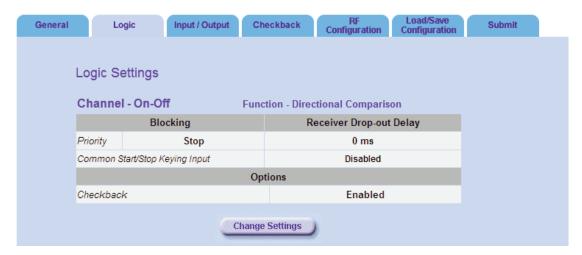


Figure 5-8. Example of The Logic Tab on the Settings Page (ON/OFF Mode)

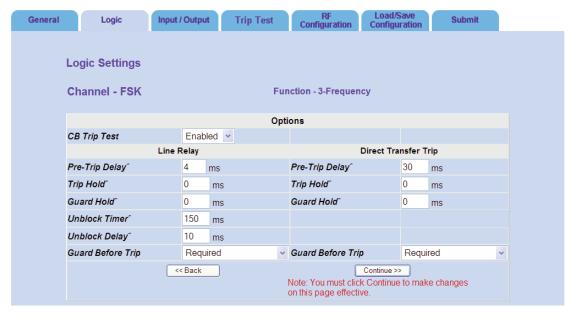


Figure 5-9. Example of The Logic Tab on the Settings Page (FSK Mode)



Table 5–6. Logic Settings for ON/OFF (Directional Comparison & Phase Comparison)

Blocking		Rec	ceiver Drop-out Delay		
Priority	Start or Sto	op 0 to 15 ms			
Commo	Common Start/Stop (KA-4) Enabled or Disabled				
	Options				
Chec	kback	Enabled or Disabled			

Table 5–7. Logic Settings for Phase Comparison (FSK Mode)

Receiver Logic						
Channel Trouble	TP & TN Clamps to "1"	Polarity	HF = TP & LF = TN			
	TP & TN Clamps to "0"		LF = TP & HF = TN			

Table 5-8. Logic Settings for 2F Unblock (FSK Mode)

Options					
Trip Test	Enabled or Disabled				
Receiver Logic					
Pre-Trip Delay*	0 to 30 ms	Guard Hold	0 to 100 ms		
Trip Hold	0 to 100 ms	Guard Before Trip	None, GBT or GBT with Override		
Unblock Timer	0 to 500 ms	Unblock Delay	0 to 100 ms		

Table 5–9. Logic Settings for 2F POTT/DTT (FSK Mode)

Options						
Trip Test	Enabled or Disabled					
Receiver Logic						
Pre-Trip Delay*	Pre-Trip Delay* 0 to 30 ms Guard Hold 0 to 100 ms					
Trip Hold	0 to 100 ms	Guard Before Trip	None, GBT or GBT with Override			

<sup>\*</sup> For every msec of pre-trip delay you add, the security, against noise causing a false trip, increases exponentially.

• UB & POTT: A min of 2-4 msec is recommended.

<sup>•</sup> DTT: The time delay should be as long as the critical stability of your system can tolerate, at least 10 msec min.



Table 5–10. Logic Settings for 3-Frequency (FSK Mode)

Options					
Trip Test	st Enabled or Disabled				
	Recei	ver Logic			
LR Pre-Trip Delay*	0 to 30 ms	DTT Pre-Trip Delay*	0 to 30 ms		
LR Trip Hold	0 to 100 ms	DTT Trip Hold	0 to 100 ms		
LR Guard Hold	0 to 100 ms	DTT Guard Hold	0 to 100 ms		
LR Unblock Timer	0 to 500 ms				
LR Unblock Delay	0 to 100 ms				
LR Guard Before Trip	None, GBT or GBT w/Override	DTT Guard Before Trip	None, GBT or GBT w/Override		

LR = Line Relaying

Table 5–11. Logic Settings for 4-Frequency (FSK Mode)

Receiver Logic						
Cmd A Pre-Trip Delay*	0 - 30 ms	Cmd B Pre-Trip Delay*	0 - 30 ms			
Cmd A Trip Hold	0 - 100 ms	Cmd B Trip Hold	0 - 100 ms			
Cmd A Guard Hold	0 - 100 ms	Cmd B Guard Hold	0 - 100 ms			
Cmd A Unblock Timer	0 - 500 ms	Cmd B Unblock Time	0 - 500ms			
Cmd A Unblock Delay	0 - 100 ms	Cmd B Unblock Delay	0 - 100ms			
Cmd A Guard Before Trip	None, GBT or GBT w/Override	Cmd B Guard Before Trip	None, GBT or GBT w/Override			

<sup>\*</sup> For every msec of pre-trip delay you add, the security, against noise causing a false trip, increases exponentially.

<sup>•</sup> UB & POTT: A min of 2-4 msec is recommended.

<sup>•</sup> DTT: The time delay should be as long as the critical stability of your system can tolerate, at least 10 msec min.



## 5.7.3 Input/Output Tab

### 5.7.3.1 Inputs (Fig. 5-10)

There are five inputs on the UPLC-II<sup>TM</sup>. Each input can be set with a contact bounce time of 0–8 ms, any of several selection choices, and if the input is active for voltage applied or removed.



# CAUTION

If you are considering setting any contact bounce time please keep in mind that any time other than 0ms will affect the security of your system. If any time is set and you get a very short input of 100µs or less, the input will be held for the total contact bounce time. It may be wiser to let the input follow whatever is coming in and let the receiver respond accordingly.

The input selection choice varies depending on the channel type and function setting. Table 5–12 shows the various input selection choices for different channel type and function selections. Of course, there is always the choice of "Not Used." You do not have to program all inputs just the ones you need.

Tables 5–13 & 5–14 show the definitions of the inputs depending on whether the unit is in ON/OFF or FSK mode.

There are 3 inputs that allow an external event to be recorded as an SOE and time tagged by the UPLC-II<sup>TM</sup>. The inputs' names are SOE Event 1, 2, & 3 and they have the same SOE name in the sequence of events file.

In FSK mode the (TX) Power Off input turns off the transmitter so neither guard nor trip can be sent. It is typically used for testing purposes.

After you have programmed all the inputs needed click on the "Continue" button and you will be taken to the Trip Duty Contact output programming functions, if your UPLC-II<sup>TM</sup> has this option. If not you will be taken to the Low Level output settings page. First let's take a look at the Trip Duty Outputs.



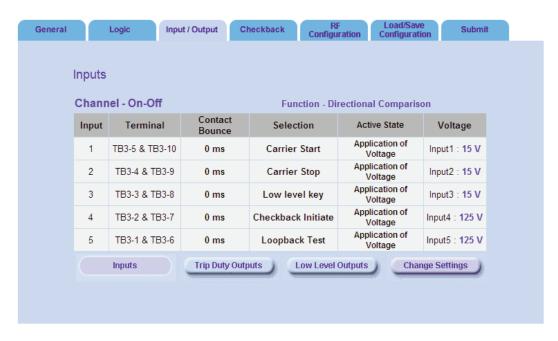


Figure 5–10. Example of the Inputs on the I/O Tab on the Settings Page (ON/OFF Mode)

Table 5-12. Input Selection Choices

ON/OFF		FSK				
Directional Comparison	Phase Comparison	Unblocking-2F	Phase Comparison	POTT/DTT-2F	3-Freq.	4-Freq.
Carrier Start	Carrier Start	UB Key	PC Key	Trip Key	LR Key	A Key
Carrier Stop	Carrier Stop	(TX) Power Off	Boost (52B)	(TX) Power Off	DTT Key	B Key
Low Level Key	Low Level Key	Trip Test	SOE Event 1	Trip Test	(TX) Power Off	(TX) Power Off
Checkback Alarm Reset	Checkback Alm Reset	Disable Trip Test	SOE Event 2	Disable Trip Test	Trip Test	Boost (52B)
Checkback Initiate	Checkback Initiate	Boost (52B)	SOE Event 3	Boost (52B)	Disable Trip Test	SOE Event 1
SOE Event 1	SOE Event 1	SOE Event 1		SOE Event 1	Boost (52B)	SOE Event 2
SOE Event 2	SOE Event 2	SOE Event 2		SOE Event 2	SOE Event 1	SOE Event 3
SOE Event 3	SOE Event 3	SOE Event 3		SOE Event 3	SOE Event 2	
Loopback Test Initiate	Loopback Test Initiate				SOE Event 3	

 $LR = Line \ Relaying \ (POTT \ or \ UB) \ UB = Unblock \ PC = Phase \ Comparison$ 



Table 5–13. (ON/OFF Mode) Input/Output Descriptions

Input Name	TX or RX	Action When Input Applied	
Carrier Start	TX	TX carrier keyed on to high level setting (10W) default)	
Carrier Stop	TX	TX carrier keyed off	
Low Level Key	TX	TX carrier keyed on to low level setting (1W default)	
SOE Event 1/2/3	Both	Causes Event 1/2/3 to be recorded in SOE log	
Output Name	TX or RX	Active State	
General Alarm	Both	Any major hardware failure occurs	
Reflected Power	TX	TX % reflected power above threshold setting	
Main RF Output	TX	TX level above 0.3W on Main Power Amp	
Redundant RF Output	TX	TX level above 0.3W on Redundant Power Amp	
Fade Alarm <sup>1</sup>	RX	RX level below alarm threshold setting since last RX calibration	
Blocking Output <sup>2</sup>	RX	Carrier received and blocking command issued	
Carrier Received <sup>2</sup>	RX	Carrier received and blocking command issued	
CB (Checkback) Outputs	Both	"See Chapter 6, table 6-2."	

<sup>&</sup>lt;sup>1</sup> Fade alarm is actually a RX level **monitor** instead of an alarm in the ON/OFF mode. It should activate when no carrier is transmitted and deactivate when carrier is started.

<sup>&</sup>lt;sup>2</sup> These 2 outputs are the same, even though they have different names.



Table 5-14. (FSK Mode) Input/Output Descriptions

Input Name	TX or RX	Action When Input Applied	
Trip Key	TX	TX keyed to Trip Frequency	
UB Key	TX	TX keyed to Unblock Trip Frequency	
DTT Key	TX	TX keyed to Direct Transfer Trip Frequency	
LR Key	TX	TX keyed to Line Relay (POTT/UB) Trip Freq.	
A Key	TX	TX keyed to Channel "A" Trip Frequency	
B Key	TX	TX keyed to Channel "B" Trip Frequency	
PC Key	TX	TX keyed for Phase Comparison	
Power Off	TX	TX output level shut off, no frequencies transmitted	
Boost TX	TX	TX output level increased to high level setting in Phase Comparison mode	
Trip Test Inputs	TX	See Chapter 6	
SOE Event 1/2/3	Both	Causes "Event 1/2/3" to be recorded in SOE log	
Output Name	TX or RX	Active State	
General Alarm	Both	Any major hardware failure occurs	
Reflected Power	TX	TX % reflected power above threshold setting	
Main RF Output	TX	TX level above 0.3W on Main Power Amp	
Redundant RF Output	TX	TX level above 0.3W on Redundant Power Amp	
TX Shift High	TX	TX keyed to shift high frequency	
TX Shift Low	TX	TX keyed to shift low frequency	
Fade Alarm	RX	RX level below fade alarm threshold setting since last RX calibration	
Good Channel	RX	RX level below fade margin threshold setting since last RX calibration	
Noise	RX	RX freq. not recognized, unstable in freq. or high noise relative to valid signal	
Guard	RX	Receive Guard Freq. with adequate level & RX logic satisfied	
Trip	RX	Receive Trip Frequency with adequate level & RX logic satisfied	
Checkback Trip	RX	Receive Trip Frequency with adequate level only (Do not have to receive Guard before Trip)	
DTT Guard	RX	Receive DTT Guard Frequency with adequate level & RX logic satisfied	
DTT Trip	RX	Receive DTT Trip Frequency with adequate level & RX logic satisfied	
DTT Checkback Trip	RX	Receive DTT Trip Frequency with adequate level only (Guard before Trip not required)	
LR Guard	RX	3-Freq Receive Line Relay (POTT/UB) Guard Frequency & RX logic satisfied	
LR Trip	RX	3-Freq Receive Line Relay (POTT/UB) Trip Freq. & RX logic satisfied	
LR Checkback	RX	3-Freq Receive Line Relay (POTT/UB)Trip Freq. with adequate level only (Do not have to receive Guard before Trip)	
Trip Negative	RX	Phase comparison negative half cycle frequency received	
Trip Positive	RX	Phase comparison positive half cycle frequency received	
A or B Guard	RX	4-Freq Receive A or B Guard Freq. with adequate level & RX logic satisfied	
A or B Trip	RX	4-Freq Receive A or B Trip Freq. with adequate level & RX logic satisfied	
A or B Checkback Trip	RX	4-Freq Receive A or B Trip Freq. with adequate level only (Do not have to receive Guard before Trip)	
Trip Test Outputs	Both	See Chapter 6	



### **5.7.3.2 Trip Duty Outputs (Fig. 5–11)**

There are four trip duty relay outputs enabled on the UPLC-II<sup>TM</sup>, if this option is ordered. The trip duty relay programmable selections are shown in Table 5–15. There are hardware jumpers to select for either a normally open or normally closed contact. Although these output contacts can trip a breaker directly (30 A for 200 msec), they can only interrupt 0.5 A at 125 Vdc.

### 5.7.3.3 Low Level Outputs (Fig. 5-12)

There are ten Low Level outputs available to be programmed to various output functions. Seven of these outputs are isolated transistor outputs that can be set for either 0.1 A or 1.0 A output. It is recommended to use the 0.1 A selection if your load is less than 0.1 A, such as, for microprocessor based relay inputs. The reason for this is to prevent any possibility of leakage current especially at 250 V station battery. (In the 0.1 A setting the high power transistors that leak very small currents are jumpered out.) Three of these low level outputs are electromechanical relays. There are hardware jumpers to select for either a normally open or normally closed contact. These contacts have a 0.5 A interrupt rating at 125 Vdc. All ten of these outputs may be programmed to one of several functions or to a not used state. The available output functions are shown in Table

If you want a UPLC-II™ alarm output to be fail-safe, you have to use one of the 3 low level EM contact outputs (Outputs LL08–LL10). By fail-safe, that means the output will alarm for the set condition and also for loss of dc power to the UPLC-II™.

#### NOTE:

LL01 – LL07 outputs are transistor switches and if normally closed is selected, the transistor is energized when that output is inactive. Because of this, the transistor will deenergize if the power is turned off to the set. If it is desired to have a normally closed state during power off then select a normally closed contact of one of the low-level relay outputs LL08 – LL10.

Tables 5–13 & 5–14 show the definitions of all the outputs depending on whether the unit is set in ON/OFF or FSK mode.

For monitoring the overall hardware health of the UPLC-II<sup>TM</sup>, it is recommended the General Alarm output be used. This alarm output is a fail-safe alarm. That is, the General Alarm is normally energized and drops out when any major hardware failure occurs on any board. See Chapter 3 alarm tables for available TX/RX level alarms not covered by the General Alarm. These tables show what causes the alarms and whether the output is closed or open when the alarm is active.

#### NOTE:

The Power Supply alarm output is separate & not shown on the web page as it is a direct hardware fail alarm to the Power Supply terminal blocks (TB1 & TB2). A Power Supply alarm will also cause a General Alarm output.

Two RX alarm outputs, which are illustrated in section 5.7.1 earlier, deserve special mention for clarity. They are the RX Fade Alarm and RX Good Channel outputs available in the FSK mode. The Good Channel Alarm is dependent on the RX fade margin setting to which the receiver is calibrated. When calibrating a receiver, you establish how much signal degradation (signal fade margin) is tolerable, usually either 15 or 20 dB. This allows the unit to keep working when a condition causes extra loss such as bad weather or aging/minor failure of components in the overall system. When the RX level degrades past the RX fade margin threshold then the Good Channel output drops out for the loss of channel condition.

The RX Fade Alarm is set to activate before the Good Channel output drops out and to be an early warning that the signal level is dropping before a complete loss of channel occurs.

The RX Fade Alarm output is also available in the ON/OFF mode. However, because this alarm output picks up only when the receiver is receiving an RF signal, it is really not an "alarm" in this mode but rather only an indication of receipt of signal when the far end TX is turned on.



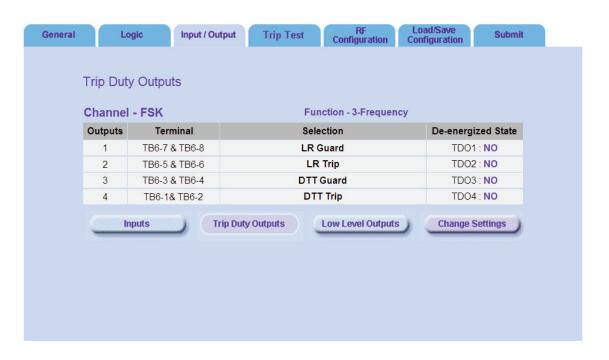


Figure 5–11. Example of the Trip Duty Outputs on the I/O Tab on the Settings Page (FSK Mode)

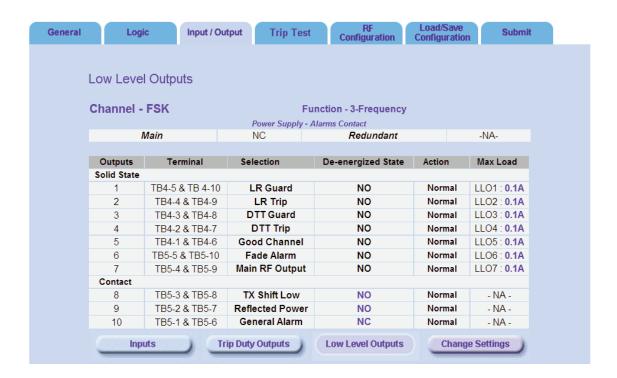


Figure 5–12. Example of the Low Level Outputs on the I/O Tab on the Settings Page (FSK Mode)



Table 5-15. Trip Duty Output Programmable Selections

ON/OFF	FSK					
Directional Comparison	Unblocking-2F	POTT/DTT-2F	3-Frequency	4-Frequency		
Blocking	Guard	Guard	LR Guard	A Guard		
Fade Alarm	Trip	Trip	LR Trip	A Trip		
			DTT Guard	B Guard		
			DTT Trip	B Trip		

Table 5–16. Low Level Output Programmable Selections

ON/OFF		FSK			
Directional Comparison	Phase Comparison	Phase Comparison	2F-UB, POTT or DTT 3-Frequency		4-Frequency
General Alarm <sup>1</sup>	General Alarm <sup>1</sup>	General Alarm <sup>1</sup>	General Alarm <sup>1</sup>	General Alarm <sup>1</sup>	General Alarm <sup>1</sup>
(TX) Reflected Power	(TX) Reflected Power	(TX) Reflected Pwr	(TX) Reflected Pwr	(TX) Reflected Pwr	(TX)Reflected Pwr
(TX) Main RF Output	(TX) Main RF Output	(TX) Main RF Output	(TX) Main RF Output	(TX) Main RF Output	(TX) Main RF Output
(TX) Red. RF Output	(TX) Red. RF Output	(TX) Red. RF Output	(TX) Red. RF Output	(TX) Red. RF Output	(TX) Red. RF Output
Fade Alarm (RX)	Fade Alarm (RX)	TX Shift High	TX Shift High	TX Shift High	TX Shift to A
Blocking Output (RX)	Blocking Output (RX)	TX Shift Low	TX Shift Low	TX Shift Low	TX Shift to B
Carrier Rec. Block (RX)	Carrier Rec. Block (RX)	Fade Alarm (RX)	Fade Alarm (RX)	Fade Alarm (RX)	Fade Alarm (RX)
CB Off <sup>2</sup>	CB Off <sup>2</sup>	Good Chan. (RX)	Good Chan. (RX)	Good Chan. (RX)	Good Chan. (RX)
CB Passed <sup>2</sup>	CB Passed <sup>2</sup>	Noise (RX)	Noise (RX)	Noise (RX)	Noise (RX)
CB Major Alarm <sup>2</sup>	CB Major Alarm <sup>2</sup>	Trip Neg. (RX)	Guard (RX)	DTT Guard (RX)	A Guard (RX)
CB Minor Alarm <sup>2</sup>	CB Minor Alarm <sup>2</sup>	Trip Pos. (RX)	Trip (RX)	DTT Trip (RX)	A Trip (RX)
CB Delayed Alarm <sup>2</sup>	CB Delayed Alarm <sup>2</sup>		CB Trip (RX)	DTT CB Trip (RX)	A CB Trip (RX)
CB Carrier Recovered <sup>2</sup>	CB Carrier Recovered <sup>2</sup>		Trip Test Failed	LR Guard (RX)	B Guard (RX)
CB In Recovery Mode <sup>2</sup>	CB In Recovery Mode <sup>2</sup>		Trip Testing	LR Trip (RX)	B Trip (RX)
CB Test in Progress <sup>2</sup>	CB Test in Progress <sup>2</sup>			LR CB Trip (RX)	B CB Trip (RX)
CB Auto Tests Disabled <sup>2</sup>	CB Auto Tests Disabled <sup>2</sup>			Trip Test Failed	
				Trip Testing	

(TX) = Transmit – end output type (RX) = Receive – end output type

<sup>&</sup>lt;sup>1</sup> Only Available on LL Outputs 8-10

<sup>&</sup>lt;sup>2</sup> Checkback (CB) Testing Option Only



# 5.7.4 Checkback (ON/OFF Mode) or Trip Test (FSK Mode) Tab

This is the testing facilities tab that only shows up if you have a UPLC-II<sup>TM</sup> catalog # ending in "AFSX", where the "A" enables testing. The details for this optional settings tab are shown in Chapter 6.

## 5.7.5 RF Configuration Tab

This is just a graphical representation of how the TX and RX are connected together based on the backplane 2W/4W jumper setting. It also shows current jumper settings of the 3 backplane jumpers. There are no settings to make on this tab.

#### 5.7.6 Submit Tab

On the Submit Tab (Fig. 5–13), you can either choose to submit the settings to the UPLC-II<sup>TM</sup> or you can discard the settings. Select the "Submit Changes" button to send the new settings to the UPLC-II<sup>TM</sup>.

The Submit Tab is also where you can set the system time and date. This will be the time used to time tag the Sequence of Events. Therefore, use the time that is common practice in your company for time tagging events, such as standard local time or GMT. If IRIG-B is connected to the unit the month, day, hour, minute and second will be set to GMT by the IRIG-B signal. The user must set the year, even with IRIG-B connected. The time and date are submitted separately from all the other settings.

At this point you have completed the settings on the UPLC-II<sup>TM</sup>. As described here we progressed through the settings from beginning to end as if we were dealing with a new installation. However, you may go into the settings and map another input or output or change an existing one without going through the whole procedure. All you do is make the settings change you want then click on the Submit Tab and then click the "Submit Changes" button. Thus after a UPLC-II<sup>TM</sup> is configured, it is easy to make a couple of needed changes.

The only time your settings will be cleared and you will have to go through all the settings tabs, is when you change the channel type or the function.

We have covered the entire setup of the UPLC-II<sup>TM</sup> Power-Line Carrier set. By using the web pages in a standard browser and providing a controlled workflow, the set up of the unit has been greatly simplified. That is, by only presenting the user with the menu selections needed based on previous menu selections, this eliminates confusion and lessens the chance for an error in setup. Since many protection-system security and dependability problems relate to system setup issues, we feel this controlled workflow process will have the overall affect of improving the protection-system reliability where UPLC-II<sup>TM</sup> is applied.



Figure 5-13. Example of the Submit Tab on the Settings Page





Figure 5–14. Example of the Calibrate Page (ON/OFF Mode)

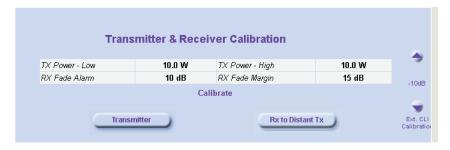


Figure 5-15. Example of the Calibrate Page (FSK Mode)

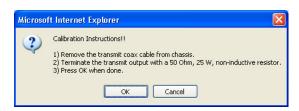
## 5.8 Calibration

**NOTE:** If you change the TX level setting, then the UPLC-II<sup>TM</sup> will not change to the new TX level until *after* TX calibration. TX calibration actually stores the new TX level into memory. See Figs. 5–14 & 15. Now that the settings have been submitted to the UPLC-II<sup>TM</sup>, the transmitter and receiver levels must be calibrated.

The table in the middle of this web page shows the values that will be used to calibrate the transmitter and receiver. In the case shown in the Figures above, the transmitter will be calibrated to 1 W low power and 10 W high power. The receiver will be calibrated for a 10 dB fade alarm and the fade margin will be set to 15 dB.

You must start by calibrating the transmitters at all line terminals first. If you have not changed the default TX power levels of 1W (low) / 10W (high), then you do not need to calibrate the transmitter because the factory always calibrates at these levels before shipping. If you need to calibrate the transmitter, you will need a  $50/75\Omega$  non-inductive resistor, depending on the TX output impedance setting. This resistor must be able to handle at least 10 W of power for a brief period of time. It is suggested to

use a 25 W,  $50/75\Omega$  non-inductive resistor. First turn off the power and then remove the transmitter coax from the rear of the chassis. Then connect the 25 W,  $50/75\Omega$  non-inductive resistor to the transmitter output coax connector J1. Now turn the UPLC-II<sup>TM</sup> power back on. The transmitter may be calibrated by selecting the "Transmitter" button on the calibration web page. When you select the transmitter button the following dialog box will pop up.



Calibration Instructions Dialog Box

Click the OK button in the dialog box. The transmitter will now be calibrated to the low and high power settings. The web page and the display on the front panel will show the calibration progress.

After the transmitter is calibrated, turn off the unit and remove the load. Then reconnect the coaxial cable that goes to the line tuner and turn the transmitter power on. The transmitters at all line termi-



nals must be calibrated in the same manner before continuing. Also, the line tuners and line traps at all line terminals must be tuned. The line tuner must be tuned for minimum TX reflected power at the appropriate TX frequency.

**NOTE:** If the TX reflected power is  $\geq 5\%$  or so when connected to the line tuner, then the TX level will appear higher if the line tuner's impedance is higher than  $50\Omega$  and it will appear lower if the line tuner's impedance is  $< 50\Omega$ . Do not recalibrate because of this.

After the above steps are completed at all terminals, the receivers may be calibrated. The transmitter at the remote end of the line must be transmitting guard in the case of an FSK channel type or keyed on to the normal blocking level in the case of an ON/OFF channel type. Now select the "RX to Remote TX" button on the calibrate web page. When this button is selected the following dialog box will appear.



Calibration Instructions Dialog Box

If things are set up as instructed then click on the OK button. The web page and the display on the front panel will show the calibration progress. If the channel type is FSK then this will complete the calibration of the UPLC-IITM. If the channel type is ON/OFF then one more step is needed to complete the process. Figure 5–14 shows the calibration web page for the ON/OFF channel type. Note that there is one extra button on the calibration web page for an ON/OFF channel type. This is the "RX to Local TX" button. In an ON/OFF channel type, the receiver must be calibrated to the signal it receives from the remote transmitter and also the signal it sees from the local transmitter, since both are on the same frequency. To complete the calibration click the "RX to Local TX" button. The remote transmitter must be off. The following dialog box will pop up.



Calibration Instructions Dialog Box

Click the OK button and the local TX will automatically be keyed on. The web page and the display on the front panel will show the RX calibration progress.

This completes the calibration process for the UPLC-II<sup>TM</sup>. With the settings made and the unit calibrated you are now ready to go through your normal end-to-end testing of the system to ready it for service.

# 5.9 SOE Log

See Fig. 5–16. The Sequence of Events (SOE) logs will show the history of the events that have occurred to the unit. Many different events are time-tagged and listed in the SOE Log. Appendix E lists the events per the configuration. All the events in the log, except for one, are time tagged to the nearest 1ms. The "Power off" event is time tagged to the nearest 1 second. The unit can store as many as 4096 events. After 4096 events are stored then the oldest ones will be erased as new ones are added. When the web page is first opened you will see the 15 most current events. You can obtain older events by clicking on the "Next" button. When you click the Next button you will be presented with the next oldest 15 events. If you click the "Back" button you will be presented with the next 15 later (in time) events. Thus, by using the Next and Back buttons you can scroll through the events 15 events at a time. A quick way to get to the oldest set of 15 events is to click the "Bottom" button, and in the same fashion you can go to the latest set of 15 events by clicking on the "Top" button.

You may also filter the events if you wish. By placing your cursor over the filter events at the top of the web page, you will get a pull down menu as shown in Figure 5–16. You may filter by Event Number Date/Time or Types (of events). There is also a "Clear All Filters" command on this drop down list. When you set up a filter it will be remembered when you display events until it is cleared. So



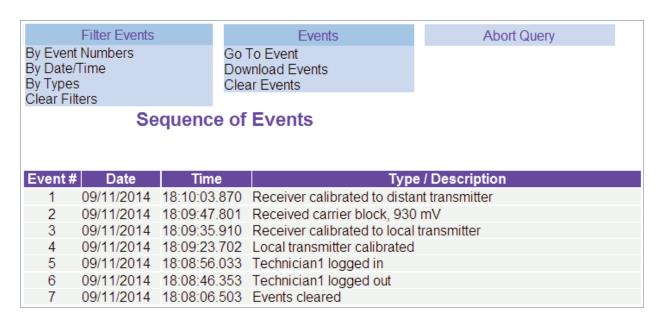


Figure 5-16. Example of the SOE Page

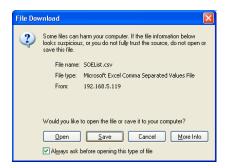
it is important to remember to clear event filters when you are done. That way the next person accessing the unit will be able to see all events.

The quickest way to view all SOEs is to download the list of events to a comma-delimited file (.csv) that can be used in most any spreadsheet application. If a filter is in place at the time of the download then that filter is used to download only those events. Events can be downloaded by moving the cursor to the area at the top of the screen labeled Events. A pull down menu will appear. Then select download events and the following dialog box appears.



**Download Dialog Box** 

This is just warning you that there may be a large number of events in the unit and it may take a few minutes to download. However, for most modern computers this will take less than 1 minute. Click OK and the download will start. After the download is complete the following Dialog box appears.



File Download Dialog Box

Now click the Save button and you will be presented with the opportunity to change the name of the file and the storage location on your local computer. After the file is saved click on Continue.

You may also clear all the events in the unit by moving your cursor over the events pull down menu and clicking Clear Events. You will be presented with a dialog box giving you a chance to cancel. Click OK to clear events.



ONCE YOU CLICK "CLEARING SOE LOG OK", ALL EVENTS WILL BE CLEARED FROM THE UNIT AND IT'S IRREVERSIBLE. AMETEK RECOMMENDS NOT CLEARING EVENTS AFTER THE UNIT IS IN SERVICE.



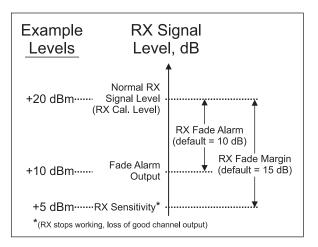
Remember that when you are viewing the SOE web page, it is not being refreshed on an automatic basis. If you want to see if any new events have occurred since you last pulled up the web page click on the little refresh oval to the right of the web page screen. Do not click on the normal browser refresh button in the top menu line. If you do you will be sent to the UPLC-II<sup>TM</sup> Home page.

# 5.10 Home Page

The home page (Fig. 5–17) shows the general status and settings of the unit at the time the home page was requested by your browser, as well as other information. In the main blue bar at the top of the page is the date and time when the web page was requested as well as the status of whether or not the unit is time synched to an IRIG-B signal. In addition, two title lines which identify the unit to which you are connected are shown, provided this text string has been set. The main blue bar on the left of the screen shows the IP address of the unit connected, the current configuration it is set for and the catalog number of the unit at the bottom. Also it shows all the menu buttons from which you can choose based on the user log-in & configuration setting. Following are the 3 main sections to the home page.

#### 1. Settings Table

- Shows the fixed basic settings (complete settings are viewed on settings pages) which only change if you change the settings
- Shows RX sensitivity which changes only after each calibration of the receiver to the remote transmitter. This is the minimum level at which the RX will work. (See the following table for RX sensitivity levels corresponding to certain RX levels at which calibration was performed. The following figure provides an explanation of RX Sensitivity, Fade Alarm, and Fade Margin.)



RX Fade Alarm & Fade Margin

- 2. Status Table \*
  - Shows actual measured TX / RX levels (Note: The RX level is only accurate after calibration of the receiver.)
  - Shows Keyed State of TX and RX Signal State
  - Shows actual measured TX Reflected Power percentage and RX fade margin, which should always be equal to the Fade Margin setting above in the Settings Table after RX calibration.
  - "Display Watt/Volts" (or dBm/db) button to the right allows for changing the units displayed for these measured val-
- 3. Alarm LEDs \* (Green circle = Healthy, Red triangle = Fail/Alarm, Grey circle = Option not present)
  - Shows General Alarm indicating overall hardware health for the entire unit.
  - Shows specific alarms for Power Amp & Power Supply modules.
  - Shows 2 other configuration specific alarms

<sup>\*</sup>This information is updated about every 15 sec or when the browser window is manually refreshed.



Table 5-17. RX Level vs RX Sensitivity

RX Level (dBm) When Calibrated	RX Level (V) When Calibrated	RX Sensitivity with 15 dB Fade Margin (V)	RX Sensitivity with 20 dB Fade Margin (V)
+40	22.36 V	3.84 V	2.24 V
+35	13.24 V	2.34 V	1.32 V
+30	7.05 V	1.27 V	705 mV
+26	4.46 V	798 mV	446 mV
+20	2.24 V	397 mV	224 mV
+15	1.26 V	205 mV	126 mV
+10	707 mV	113 mV	70.7 mV
+5	398 mV	65 mV	39.8 mV
0	224 mV	37 mV	22.4 mV
-5	126 mV	21 mV	12.6 mV
-10	70.7 mV	12 mV	7.1 mV
<b>–15</b>	39.7 mV	6.7 mV	4.0 mV

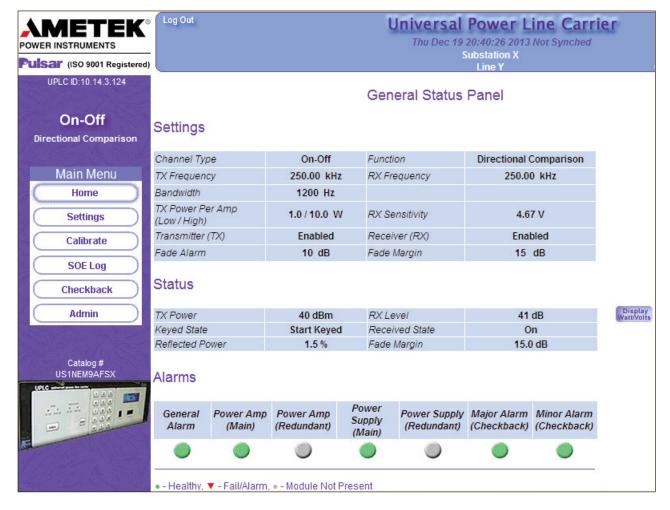


Figure 5-17. Example of the Home Page



### 5.11 Front Panel

Limited access is available through the front panel interface of the UPLC-II<sup>TM</sup>. There are 2 menus available using the "SET" or "TEST" button.

Besides these 2 menus, you may view alarms, acknowledge alarms and turn on the display after it has self-extinguished.

- To turn on the display, press any key.
- To view Alarms, press the "RIGHT" arrow.
- To acknowledge alarms, press the "DOWN" arrow.

#### 5.11.1 Password Access

A password is required to make any changes to settings via the SET button menu but by default it is not required for the TEST button menu unless set to "required" on the Admin web page. The default password is 4050. Front panel passwords can be four to nine numeric characters. The front panel password may be changed. However, it can only be changed using the front panel. To disable all front panel access, see Admin page (Fig. 5–3).

### 5.11.2 Front Panel Display

The display (Fig. 5–18) goes into sleep mode after a few minutes of inaction. Press any key to wake it up. In the upper right corner an alarm state indication can occur. If it does, the display will alternate

between the main screen and the alarm code screen. See Troubleshooting in Chapter 4 for a list of the 3 or 4-letter alarm codes. Also in the lower right corner are 3-letter RX state codes shown below.

#### **ON/OFF Mode**

BLK Blocking signal received OFF No signal received

#### **FSK Mode**

LOC Loss of Channel
NOI Noise detected
GRD Guard
CRT Charleback Trip

CBT Checkback Trip

TRP Trip

CB1 Checkback Line Relay trip

CB2 Checkback DTT trip

LRT Line Relay Trip

(same as UB or POTT trip)

DTT DTT Trip

#### 5.11.3 Set Button Menu

The "Set" button menu (Fig. 5–19) changes depending on the configuration mode setting (ON/OFF, FSK-2F, etc.). Pressing "SET" also displays the 11-digit catalog number of the UPLC-II<sup>TM</sup> and prompts for the password. Once entering the password, limited functionality is available as shown in the following menu tree. This menu must be accessed to view or change the IP address.

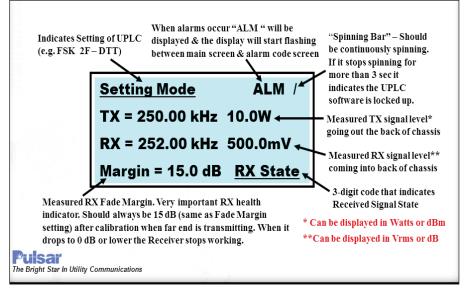


Figure 5–18. UPLC-II™ Front Panel Display



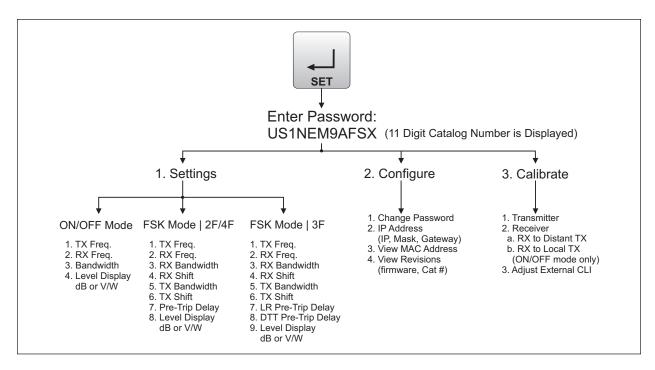


Figure 5–19. UPLC-II™ SET Button Menu (ON/OFF & FSK)

#### 5.11.4 Test Button Menu

See Figs. 5–20, 21, 22. Pressing the TEST or Left arrow allows you to test the functionality of the unit. It also shows the TX reflected power percentage on the top line above the TEST menu. This TEST menu can be password-protected if desired (see Figure 5–3).

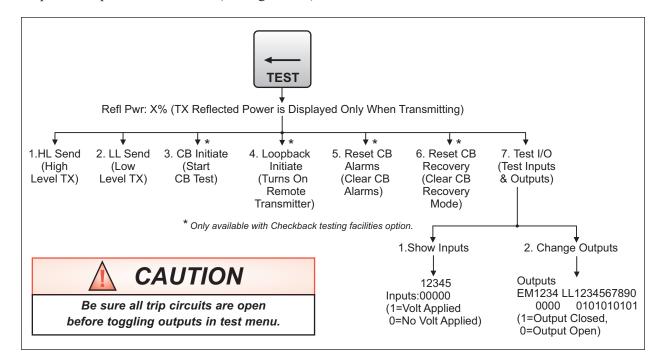


Figure 5–20. UPLC-II™ TEST Button Menu (ON/OFF Mode Only)



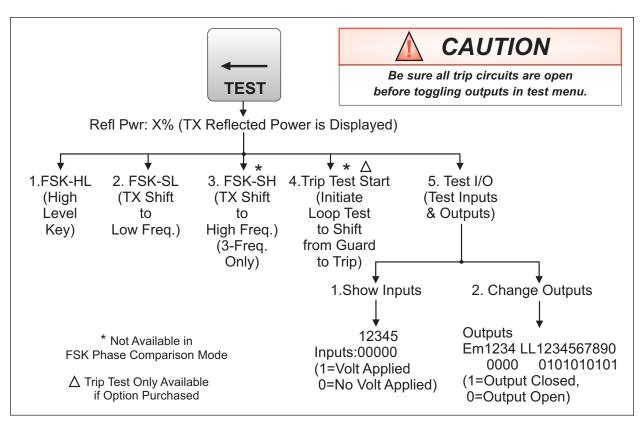


Figure 5–21. UPLC-II™ TEST Button Menu (FSK: 2-Freq, 3-Freq & Phase Comparison)

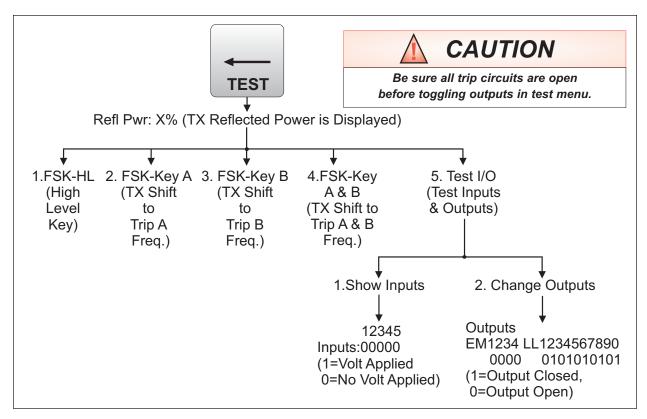


Figure 5–22. UPLC-II™ TEST Button Menu (FSK 4-Frequency Only)

# 6. Testing Facilities

An optional test capability for the UPLC-II<sup>TM</sup>, if purchased, is available to perform manual or automatic testing. The same capability does two different functions depending on whether the UPLC-II<sup>TM</sup> is in ON/OFF or FSK mode.

For ON/OFF mode, because the system is not transmitting most of the time, there is a need to periodically verify that the Transmitter and Receiver are functional. This is accomplished in the UPLC-II<sup>TM</sup> with a Checkback (CB) Tester that does a periodic test to each Transmitter and Receiver in the system.

For FSK mode the system is always transmitting and receiving a Guard frequency, but very rarely is the frequency shifted to Trip. For customers that want to verify their system will shift to trip when called upon to do so, the UPLC-II<sup>TM</sup> has an FSK Trip Test feature. It uses the guard-before-trip logic and sends a trip frequency loop test without causing a real Trip output.

Testing is always over ridden by protective relaying operation.

# ON/OFF Mode Automatic Checkback (CB) Feature

# 6.1 General Description

The Checkback Tester is an AMETEK proprietary test because there is no industry standard for checkback tests. This means that all Power-Line Carriers communicating with the UPLC-II<sup>TM</sup> Checkback Tester must be able to run an AMETEK type of checkback test. The following AMETEK products are compatible with the UPLC-II<sup>TM</sup> Checkback Tester:

- Another UPLC-II<sup>TM</sup> with checkback test option
- UPLC with Checkback test option
- TC-10B with a Universal Checkback module
- Any other Power-Line Carrier with a Universal Checkback Standalone UCBS Tester connected to it

# Checkback Test Facility (Quick Checklist, if not working)

1. Verify that you calibrated all Receivers properly. RX margin measured value (bottom line on display) should be the default of 15dB, or whatever RX margin setting was chosen, when keying either distant or local transmitter.

Each Receiver stores 2 settings – for Distant Transmitter and Local Transmitter.

- 2. Check UPLC-II<sup>TM</sup> settings:
  - "Logic" Tab Settings

CHECKBACK	Set to ENABLED
COMMON START/STOP KEYING INPUT	Set to DISABLED (Unless Interfacing with
	EM Relay, KA-4 or Equivalent)

- "Checkback" Tab Settings:
  - > Last Remote = number of remotes in your system (for a 2-terminal line = 1)
  - > Verify that the Checkback settings are the same in all UPLC<sup>TM</sup> units, (also TC-10B or UCBS–Standalone Checkbacks), except for the address (Master, Remote 1, Remote 2 etc.)
- 3. Verify that no STOP or START carrier is applied to the UPLC-II™ inputs.



A normal checkback test consists of one unit addressed as the master sending a test to 1 or more units addressed as remotes and those units responding back to the master. To accomplish this, a unique time period carrier ON pulse or multiple pulses are sent which the other units recognize as a test. These pulses are sent in the same way as when a blocking carrier signal is sent but it is their precise time period and/or pulse pattern that identifies them as a test. All checkback testing is immediately shut down if there is a carrier start or stop input to the UPLC-II<sup>TM</sup> coming from a protective relay due to the way the UPLC-II<sup>TM</sup> keying logic is designed.

# 6.2 Checkback (CB) Settings

#### 6.2.1 General Information

The general rule for Checkback settings is to set all units in a system with the same settings except each unit will have a different module address (master, remote # 1, remote #2, etc.). This should be followed for optimum results. Which unit is master or remote is really not critical, except that it is recommended to make the UPLC-II<sup>TM</sup> the master with mixed systems that have other non-UPLC<sup>TM</sup> units. Also if IRIG-B is only being used at one UPLC<sup>TM</sup> for time stamping, then make that location the master and the other non-IRIG-B units can be synchronized to it if desired.

#### 6.2.2 Primary Communications Mode

The primary communication mode of the checkback relates to the speed and capability of the checkback test.

In the coded mode the test operates at approximately 60 bits per second with the carrier being pulsed on and off as fast as 1/60th of a second depending on the data stream. This has been found to be a very reliable communication speed.

In the timed mode, however, it operates much slower with the carrier being pulsed on for a 5, 10, or 15 sec time period depending on whether the master, remote #1 or remote #2 are being talked to, respectively. The timed mode is very reliable and in general this extra reliability is not needed. We only recommend setting the "Primary

Communication" to the timed mode for systems that are very noisy or where blocking output SOEs filling a protective relay's buffer is an issue.

The recommended setting is to use the ""Primary Communication" set to "Coded" and the "Fallback Timed Mode" set to "Enabled" so if the coded mode fails to have a successful test it first tries a timed mode test before giving any alarms.

Even with the "Primary Communication" set to the timed mode, the checkback will still be operating in coded mode for sending commands (i.e. getting settings, checking events, etc.) other than doing the actual checkback tests, because if these commands were sent in the timed mode it would take several hours to process a command. Also two features are not available in the timed mode due to the reduction in data that can be sent. First, you do not get a successful checkback test output at the opposite end of where you initiated the test, only at the local end. And secondly the remote checkback only responds with high level tests regardless of whether high level or low level tests were sent to it.

## 6.2.3 Checkback Test Sequence

The normal sequence of events for a successful checkback test is that the master end sends out coded signal pulses from the local Transmitter to the remote end Receiver first. At the remote end, the signal is received by its Receiver and the checkback software tells the Transmitter to respond with a different set of coded signal pulses. The local Receiver at the master end then receives this checkback signal and indicates a successful test at the master end. If set in the "coded" primary communication mode, it then sends an acknowledgement to the remote end and the remote end indicates a successful test also. If you have a 3-terminal line and initiate a test at the Master, then the Master will communicate to Remote #1 and then to Remote #2. If you initiate a test at either Remote, then the Remote will first communicate to the Master and then to the other Remote.

With an unsuccessful test, the master end will send the initial test, then "X" number of retry tests, then (if "fallback to timed mode" is enabled) run a much slower pulse "timed" mode test before final-



ly giving a checkback major or minor alarm. So there would normally be at least 4 attempts to have a successful test, when the number of retries is set to 2, before getting any alarms. These tests would be run at both low level and high level if "Low Power Tests" are enabled with low power tests being run first. All this gives security against noise on the line or some temporary condition causing a false alarm. Major alarms occur for high power test failures and minor alarms occur for low power test failures.

#### 6.2.4 Last Remote

Your network may contain more than two check-back terminals (i.e., one master and one remote). Among other things, this setting lets the unit know the final address to which it needs to send a check-back test request. If the primary communication mode is set to "timed", you can have up to four (4) remotes. If it is set to "coded", you can have up to 10 remotes.

#### 6.2.5 Auto tests

Automatic checkback tests can be enabled or disabled. Normally, you would probably want them to be enabled. But if, for example, you are installing a new checkback system, you might want to disable automatic checkback tests until all units are in place. When auto tests are disabled at a unit, it does not issue checkback tests unless manually commanded by you, the user. In addition, the master unit does not issue the automatic clock update at around 12:30 AM. In other words, no unit sends any command, unless you specifically command it.

### 6.2.6 Low Power Tests

Here, you can enable or disable the low power setting during checkback tests. When enabled, all checkback tests initiated by this unit are first performed on low power, then high power. When disabled, only the high-power test is performed, except when in recovery mode during which time only low power tests are run.

#### 6.2.7 Retries

During noisy line conditions, remote messages may contain errors that cannot be fixed at the destination module. With this setting, you can specify the maximum number of times you want the module to automatically resend a message (retries). The valid range is zero (0) to 5 (times).

## 6.2.8 Automatic Tests – Time Settings

The time setting specifies how you want automatic checkback tests to be performed. You have two options:

- 1. Checkback Hours of the Day
- 2. Checkback Period

Option 1 – Automatic checkback tests are performed at your four user-specified times. These might be, say, 6:00, 12:00, 17:00, and 23:00.

Option 2 – Automatic tests are performed every so many hours, for example, every eight (8) hours.

When you set the time setting to "Hours of the Day" the master initiates a checkback test at each of these times. You can set these times only to the nearest hour, using a 24-hour format. The master actually executes a test five minutes after the hour (e.g. 4:05). This delay provides some "wiggle" room to compensate for unsynchronized checkback clocks. Remotes that have their Interval Types set to "Hours of the Day" also use these times to initiate their own checkback tests, if they do not hear from the master within a grace period. The grace period is ten minutes after the hour for remote #1, fifteen minutes for remote #2, and so on.

If you do not want to use all four times, say you are only interested in one test per day, you can simply set all of the times equal to one another. For example, you could set time #1 - #4 to 08 to perform a test at 8am every day.

When the Time Setting is set to "Checkback Period" and three tests per day are desired without caring about the time of day when they occurred, you could set this time to 8 hours. The Master attempts periodic checkback tests at exactly this time, in this case eight hours since the last test. Remotes have a grace period before they, too, attempt a checkback test, if they have not heard from the master. For example, remote #1 would do a checkback test after eight hours and five minutes, if it did not receive a checkback test from another unit.



If the current time setting is Checkback Period, this means that the "Hours of the Day" times are disabled and checkback tests occur according to the periodic interval (e.g., in the above example, every 8 hours).

When you set "Hours of the Day", these times become active and the Periodic time is inactive.

## 6.2.9 Optional Carrier Recovery

In general, if settings are set for at least 2 retries & fall back to timed mode, there is very good security against a noise burst causing a false checkback alarm. However "Carrier Recovery mode" is an ultra reliable way to verify that any checkback test failures were legitimate hardware failures and were not caused by an extended noise burst. It works together with the "delayed alarm output" when enabled. The unit starts "carrier recovery mode"

after a failed checkback test. In carrier recovery mode, the "master" initiates a checkback test using a more frequent user interval, for example, every 15 minutes. After three consecutive successful checkback tests, the "master" reverts to normal operation and sets the "successful carrier recovery" output. If three successful consecutive checkback tests fail, the "delayed alarm" output is set. Remotes in carrier recovery mode suspend all checkback tests and wait until they receive three good checkback tests from the "master". At that time they also resume normal operation. When in recovery mode, the unit shows a "reco" alarm on the front display to indicate this state. Also note that while in recovery mode only low power checkback tests are sent, regardless of whether you have low power tests disabled or not. This ensures line conditions are good before resuming normal operation.

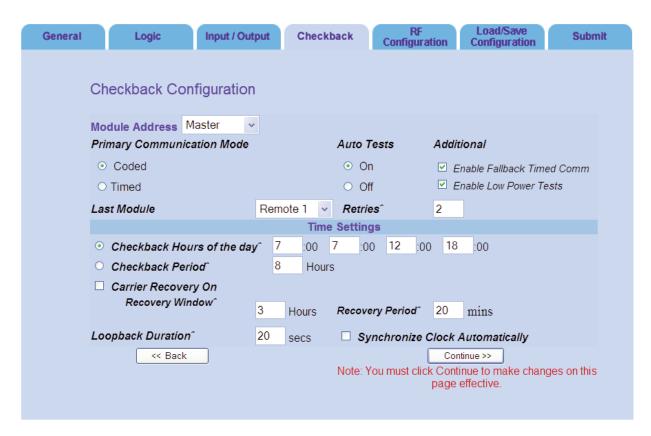


Figure 6–1. Example of the Checkback Tab on the Settings Page (ON/OFF Mode)



Table 6-1. Checkback (CB) Settings

Checkback Setting Name	Selections	Description	Typical Setting
Module Address	Master, Remote 1–10	Set each unit's address that controls which unit will initiate the tests in automatic mode. (Master = addr 0).	As appropriate
Primary Communication Mode	Coded or Timed	How fast and how many pulses will be sent during the test (coded = pulses at up to 60 bps, timed = 1 pulse with minimum pulse width of 5 sec).	Coded
Last Module	Remote 1–10 (coded mode) Remote 1–4 (timed mode)	Specify how many total remotes are in your system.	For 2-terminal system = Remote 1, for 3-terminal system = Remote 2
Auto Tests	On or Off	Set ON if you want tests to run automatically w/o user intervention.	On
Retries	0–5	If the initial test fails, number of additional tests to perform before allowing alarms.	2
Enable Fallback Timed Comm	Enabled or Disabled	If Primary Communication Mode is set to coded, then when enabled this will run an additional "timed" long pulse test before giving any alarm outputs.	Enabled
Enable Low Power Tests	Enabled or Disabled	When enabled, run tests not only at high power but also at low power to check for RX margin.	Enabled
Checkback Hours of the day *	From 1 to 4 times per day at a specific hour (military 24 hour time)	Run automatic tests at up to 4 specific times during the day.	Enabled and all 4 times set to a particular hour of the day for once/day test
Checkback Period*	1–99 hours	Run automatic tests at this time interval.	Disabled
Carrier Recovery On **	Yes or No	After a checkback test failure, this is an ultra secure mode to verify the system is really bad, which works with the Checkback Delayed Alarm output. Multiple tests are run in a sped-up mode to verify system is bad.	Disabled
Recovery Window **	1–24 hours	After a checkback test failure, this is the time window in which 3 consecutive good tests have to be received to recover and have no Checkback Delayed Alarm output.	When used, set to 3 hrs
Recovery Period **	5–60 minutes	Time between the recovery mode sped up tests.	When used, set to 20 min
Loopback Duration	4–60 seconds	When a ""Loopback"" test is run it turns on the remote Transmitter for this amount of time to allow measurement of receive signal.	
Synchronize Clock Automatically	Enabled or Disabled	Synchronizes the remotes' clocks with the master's clock once per day at 12:30AM.	Enabled, if IRIG-B not used

<sup>\*</sup> Choose between these 2 checkback timing modes for either a specific hour of the day or a particular time interval.
\*\* Blue Cells: These settings all work together when using the carrier recovery mode option.

Page 6–5 February 2018



# 6.3 Checkback Tester Inputs/Outputs

Table 6–2 lists all the inputs and outputs available for the checkback test option. All 3 inputs are meant to be momentarily pulsed on and should not have a continuous input applied. You can program the alarm outputs to seal or just momentarily toggle when an alarm occurs. When you select sealed operation, the alarm outputs stay in their active, or energized, states as long as the alarm exists. If you select momentary, the outputs go to their active states for only five seconds, then return to their previous states. For example, assume alarms are set to momentary action and the major alarm active state is closed. Normally this output is open. When a major alarm occurs, the MAJOR ALARM output closes for five seconds then opens again. The MAJOR ALARM output does not change (again) when the major alarm is cleared.

Table 6-2. Checkback (CB) Inputs/Outputs

Inputs		
Menu Selection	Description	
Checkback Initiate <sup>1</sup>	Pulsing this input initiates a checkback test & resets Major/Minor Alarms.	
Checkback Reset <sup>2</sup>	Pulsing this input resets all checkback alarms & recovery mode.	
Loopback Test <sup>1</sup>	Pulsing this input initiates a loopback test to turn on the remote transmitter for "X" seconds per setting.	
	Outputs	
Menu Selection	Description	
CB Off	Activates when all checkback tests are completely disabled in settings.	
CB Passed	Activates & latches after successful checkback test.	
CB Major Alarm	Activates & latches when failing a high-power test.	
CB Minor Alarm	Activates & latches when failing a low-power test.	
CB Delayed Alarm	Activates & latches when failing to recover from the auto recovery mode before the recovery windows expires.	
CB Carrier Recovered	Momentarily activates for 1 second after a successful recovery before the recovery window expires.	
CB In Recovery Mode	Activates while in recovery mode.	
CB Test In Progress	Activates at end that initiates checkback test during the whole checkback test, but activates after a few seconds during checkback test at remote end.	
CB Auto Tests Disabled	Activates when automatic checkback tests are disabled in settings.	

<sup>&</sup>lt;sup>1</sup> Input must be applied for  $\geq$  15 msec.

<sup>&</sup>lt;sup>2</sup> Input must be applied for  $\geq$  2.0 sec.



# 6.4 Performing Checkback Tests/Functions

The Checkback system's primary function is to perform checkback tests, verifying that your carrier communication path is operating. You can perform checkback tests in several ways:

- Manual request from the front panel test menu
- Manual request from the checkback page
- Manual request from an external source via an input set for "Checkback Initiate"
- · Automatic test
- Automatic carrier recovery test
- · Automatic remote-initiated tests

The Checkback system also does other secondary functions such as turning on remote transmitters and getting data from distant UPLC-II<sup>TM</sup> units.

# 6.4.1 Manual Requests from Web Pages

By clicking on the left-hand navigator "Checkback" button and using the 3 pull-down menus, you can do the following:

#### A. Tests

1. Run manual checkback test

- 2. Run loopback test to turn on remote transmitter only
- B. Clear Module
  - 1. Clear recovery mode (also clears all alarms)
  - 2. Clear alarms
  - 3. Clear checkback events counts
- C. Checkback (Communications)
  - 1. Update status of web page
  - 2. Connect to distant UPLC-II<sup>TM</sup> to view;
    - · Home page
    - Settings
    - Partial SOE Log

# 6.4.2 Loopback Test Capability (Turn On Remote Transmitter via the power line)

You can command a distant Automatic checkback system to key its carrier for a specified duration (e.g., 30 seconds), giving you time to measure your local receiver's level. This is called loopback tests in the UPLC-II<sup>TM</sup> and they are always performed at both high and low power. If loopback duration is set to 30 seconds, the carrier is first keyed on high power for 30 seconds, then low power for 30 seconds.

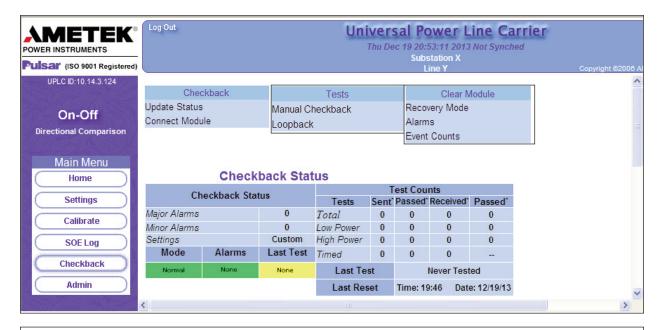


Figure 6–2. Example of the Checkback Page (ON/OFF Mode)



If you have a 3-terminal line or more terminals, a pop-up box will appear after clicking on loopback test so you can choose to which unit you want to do a loopback. (Note: The front panel TEST button menu only allows a loopback test between Master & Remote1)

### 6.4.3 Remote-Initiated Periodic Tests

If the master fails to send a test or is late, then a remote initiates its own checkback test. You can always manually request a test via the Web page or Front Panel test menu on the remote UPLC-II<sup>TM</sup>. But the remote automatically does a checkback test if it detects the master is late. When a remote is set to do automatic periodic tests, it determines the master is late if it does not receive a checkback request within the user period plus some delay, or grace period. For remote #1, this grace period is five minutes.

For example, let's say your remote is set for automatic periodic testing, with a period of eight hours. If it does not receive a checkback test within eight hours and five minutes, it executes a checkback test. If this test is successful, both the master and the remote's periodic timers are restarted at roughly the same time, and the master takes over for subsequent checkback tests, if both units are set for the same periodic interval. The periodic timer starts as soon as the unit is powered, so that one will have a head start on the others. After the first successful checkback test, all the periodic timers in the network are synchronized, and the master initiates any future tests.

If you have more than one remote in your system, each has its own unique grace period. Remote #1 waits five (5) minutes, remote #2 waits 10 minutes, remote #3 waits 15 minutes, and so on.

For example, if neither remote #1 nor the master has initiated a checkback test for the interval plus 10 minutes, remote #2 executes a test.

For this scheme to work properly, it is important to keep all the settings similar. If the master is set for automatic periodic testing, all remotes should also be set this way. If not, you may have more checkback tests occurring than you would expect at equally unexpected times.

# 6.4.4 Remote-Initiated "Hours of the Day" Tests

Just as with remote-initiated periodic testing, remotes set to "Hours of the Day" testing initiate their own checkback tests if the master does not do a test in time. The "grace" period is longer for this mode: user time + 10 minutes for remote #1, user time + 15 minutes for remote #2, etc. That allows this scheme to work even when there is up to five minutes difference between the checkback units' clocks.

For automatic timed testing, the clocks in the master and the remotes should be fairly close.

You can enable the automatic clock synchronization feature to keep your clocks synchronized. When enabled, the master synchronizes all remote clocks to its own time starting at 12:30 a.m. In practice, the synchronization is rough, within about +/- 2 seconds, but that is sufficiently accurate for timed checkback testing.



# 6.5 System Troubleshooting with Checkback

You can identify and solve many checkback network problems by examining the major and minor alarms. If low power checkback tests are enabled in addition to high power tests, the major and minor alarms work like this:

- If a unit fails only the low power test, it sets the minor alarm
- If a unit fails the high power test, it sets the major alarm
- If a unit fails the high power test and can not receive its own messages, it sets both major and minor alarms

Armed with this information, you can usually identify a failed unit or line problem. The System

Troubleshooting table lists all combinations for a two-unit system and the probable situation.

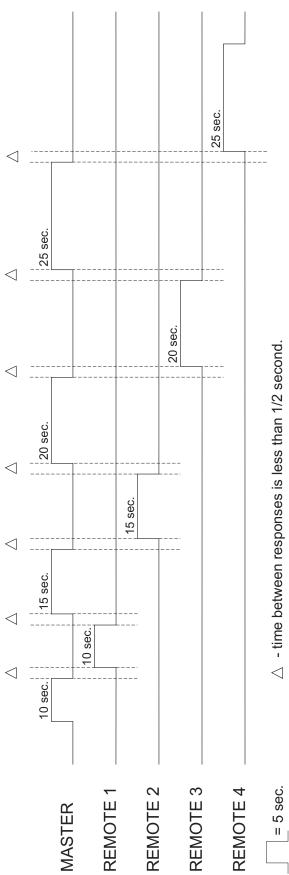
To get the complete picture, you must wait long enough for all remotes to initiate their own checkback tests. For example, if the master has a major alarm, but the remote has no alarms, you can not determine if it failed to receive the command due to a bad line or because its receiver failed. By waiting for the remote to initiate a checkback, you can tell if it is the line (major alarm) or the unit (both alarms). Some customers use a N.O. Major alarm and a N.O. Minor alarm output in series to give a "local" alarm so they can know which end of the line has a problem. Both Major & Minor alarms occurring on one UPLC-II<sup>TM</sup> means that this particular UPLC-II<sup>TM</sup> in the system is bad.

Table 6-3. System Troubleshooting

	ALAF				
Master N	Master Module		Module	Probable Situation	
Major	Minor	Major	Minor		
clear	clear	clear	clear	All OK	
clear	clear	clear	set	Weak/noisy line	
clear	clear	set	clear	Master or line failed	
clear	clear	set	set	Remote failed	
clear	set	clear	clear	Weak/noisy line	
clear	set	clear	set	Weak/noisy line	
clear	set	set	clear	Weak/noisy line or master failed	
clear	set	set	set	Remote failed	
set	clear	clear	clear	Remote or line failed	
set	clear	clear	set	Remote or line failed	
set	clear	set	clear	Line failed	
set	clear	set	set	Remote failed	
set	set	clear	clear	Master failed	
set	set	clear	set	Master failed	
set	set	set	clear	Master failed	
set	set	set	set	Master and remote failed	



Figure 6-3. Timed Checkback Sequence (Master Initiation)



 $\triangle\,$  - time between responses is less than 1/2 second.

6



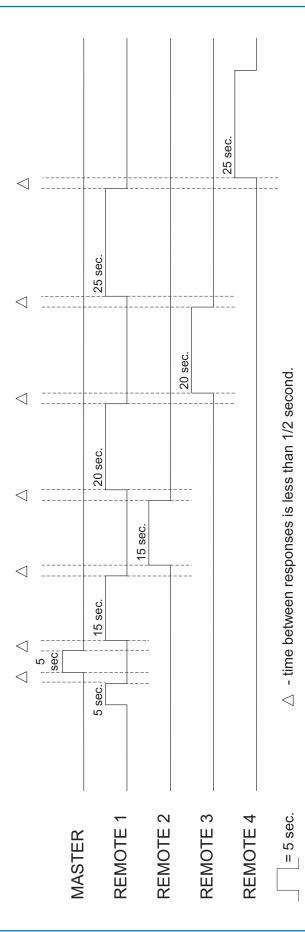
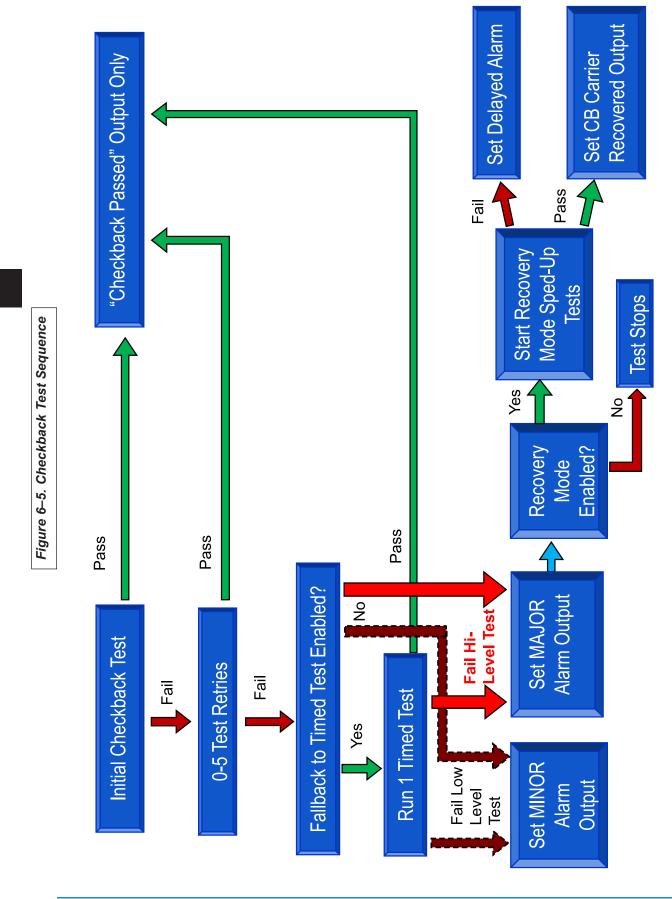


Figure 6-4. Timed Checkback Sequence (Remote 1 Initiation)







# FSK Mode Trip Test Feature

Trip Test Inputs/Outputs, Web pages and timing diagrams are at the end of the chapter.

# 6.6 General Description

The optional Trip Test is designed to test FSK two-frequency or three-frequency mode and is compatible with the TCF-10B's Trip Test option. Two transmitters with trip test, one at each end of the line, are needed to perform this testing function.

Trip testing will only work on 2-terminal lines and is not functional on 3-terminal lines or more.

The Trip Test can be used to functionally test the transmitters and receivers at both ends of a two terminal line with having only a person at one end.

The Trip Test on the UPLC-II<sup>TM</sup> works in conjunction with the local receiver as well as the remote receiver and transmitter to test the ability of the system to shift the transmitter to the trip frequency and receive the trip frequency at the opposite end.

For 2-frequency FSK systems, the trip test can be set for a "real" trip or a "checkback" trip. The "real" trip will produce an output of the receiver logic TRIP. A "Checkback" Trip setting will provide only a checkback trip output from the receiver logic, which can be used to pick up an auxiliary relay or indicating light. Only the "checkback" trip setting can be used for 3-frequency systems.

# 6.6.1 Two Frequency Applications Real Trip Scenario

Please refer to the timing diagrams at the end of the chapter.

In this application, the local end, at which you initiate a Trip Test, will receive a <u>real TRIP</u> as well as a CHECKBACK TRIP, but the remote end will only produce a CHECKBACK TRIP. When using this application the end that initiates the trip would have to be disconnected from the trip relays.

When a trip test is initiated, the local transmitter shuts down for 2 seconds. The remote end receiver will see this as a loss of channel. After 2 seconds, the local transmitter then keys to the trip fre-



# **CAUTION**

- If the unit is set for a real trip, then caution should be taken to open the trip circuit path so as not to mistakenly trip out a breaker or lockout relay on a Direct Transfer Trip system.
- The required logic must be set for "GUARD BEFORE TRIP".

quency for 2 seconds. The remote end recognizes this as a Trip Test command and the remote receiver will then produce a CHECKBACK TRIP and key the remote transmitter to the trip frequency for 2 seconds. The local end receiver sees that as a REAL TRIP and produces a TRIP and CHECKBACK TRIP output.

# 6.6.2 Two Frequency Application Checkback Trip Scenario

In this application, both the local and remote ends shift to "checkback" trip. No trip outputs have to be disconnected.

When a trip test is initiated, the local transmitter shuts down for 1.5 seconds. The remote end receiver will see this as a loss of channel. After 1.5 seconds, the local transmitter then keys to the trip frequency for 0.5 second. The remote end recognizes this as a Trip Test command and the remote receiver will then produce a CHECKBACK TRIP and shut down the remote transmitter for 2 seconds. The remote transmitter is then keyed to the trip frequency for 0.5 second. This in turn produces a loss of channel and CHECKBACK TRIP (without a real TRIP) at the local end.

# 6.6.3 Three Frequency Applications Checkback Trip Scenario

In this application, both the local and remote ends shift to "checkback" trip. No trip outputs have to be disconnected. Both trips, DTT & LR (unblock/POTT) are tested. DTT is low frequency and LR (unblock/POTT) trip is high frequency.

When a trip test is initiated, the local transmitter shuts down for 1.5 seconds. The remote end receiver will see this as a loss of channel. After 1.5 seconds, the local transmitter then keys to the lower trip frequency for 0.5 second. The remote end recognizes this as a Trip test command and the remote receiver will then produce a CHECK-



BACK TRIP1 and shuts down the remote transmitter for 2 seconds. The remote transmitter is then keyed to the lower trip frequency for 0.5 second. This in turn produces a loss of channel and DTT CHECKBACK TRIP (without a TRIP) at the local end's receiver. Then the system needs to check for the LR TRIP function. In a similar way, the local end will send a LR CHECKBACK TRIP to the remote and the remote receives and then returns a LR CHECKBACK TRIP to the local receiver.

## 6.6.4 Trip Test Initiation

You initiate a trip test sequence by front panel testing, web page request or asserting the trip test initiate input (if programmed).

## 6.6.5 Trip Test Pulse

This optional feature is used to verify that the actual Trip Key input is operating by applying a 0.1 sec pulse to it at the beginning of the Trip Test. This pulse is prevented from causing an actual Trip Key during the test and is used only to verify the input is good. This feature is only enabled when an output is set to "Trip Test Pulse".

Table 6-4. Trip Test Inputs / Outputs

Inputs				
Menu Selection	Description			
Trip Test	Pulsing this input initiates a Trip Test.			
Disable Trip Test	When activated the Trip Test is shut down.			
Outputs				
Menu Selection	Description			
Trip Test Failed	Activates and latches when the Trip Test fails.			
Trip Testing	Trip Test in progress. Activates at end that initiates Trip Test during the whole test, but activates after a few seconds at remote end.			
Trip Test Pulse	When selected, this activates a special Trip Test mode requiring this output to be externally wired to the input which is set for keying Trip. If the pulse is not received at the beginning of the test then the Trip Test fails.  Used to verify Trip Key input circuit is good.			



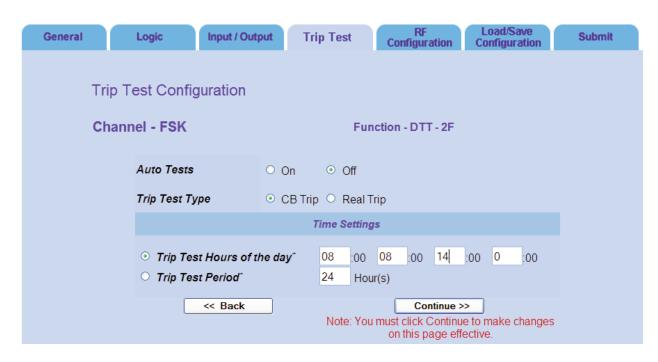


Figure 6–6. Example of Trip Test Tab on the Settings Page (FSK Mode)

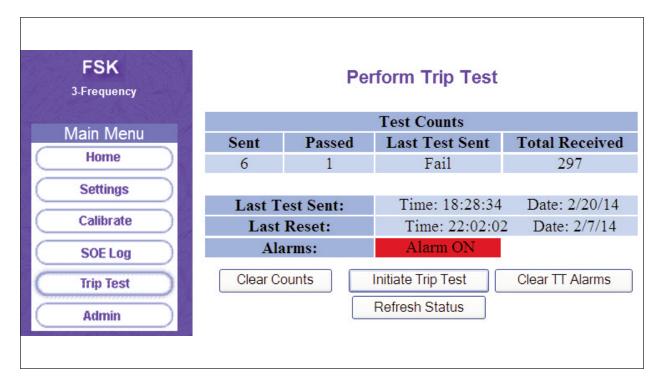


Figure 6–7. Example of Trip Test Page (FSK Mode)

February 2018 Page 6–15



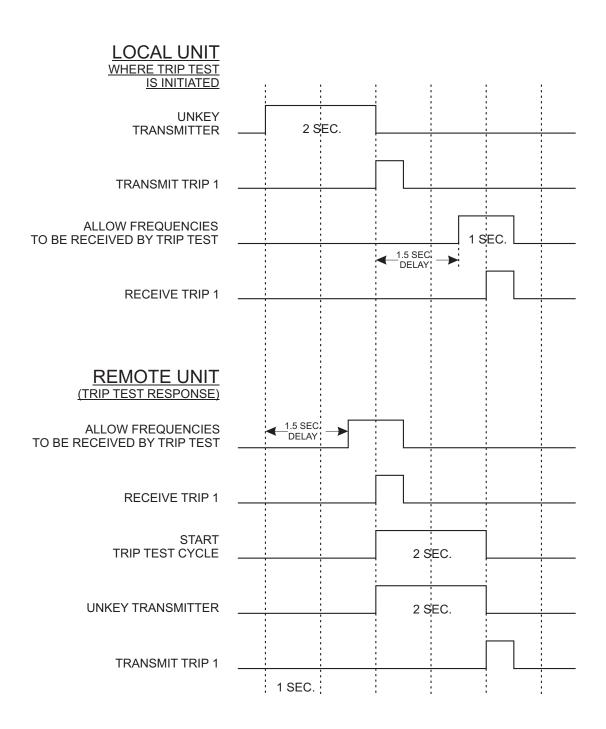


Figure 6-8. Trip Test 2-Frequency Checkback Trip Timing Diagram



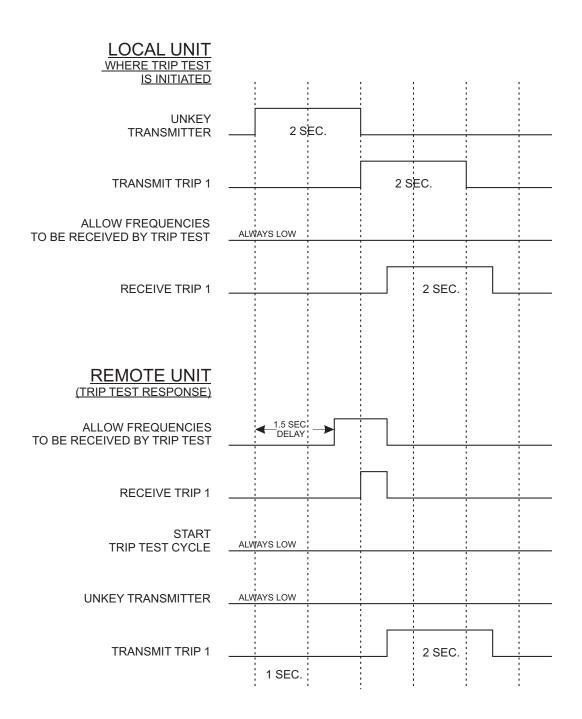


Figure 6-9. Trip Test 2-Frequency Real Trip Timing Diagram

February 2018 Page 6–17



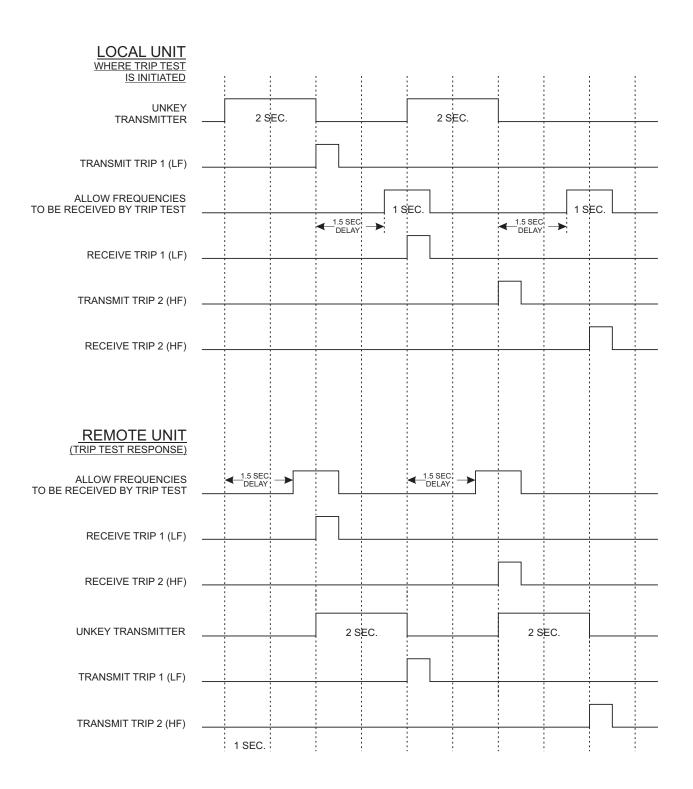


Figure 6–10. Trip Test 3-Frequency Checkback Trip Timing Diagram

# 7. Communication Protocols

The UPLC-II™ is available with separate protocols. The Distributed Network Protocol, DNP 3; and the IEC61850 object oriented standard.

#### 7.1 DNP 3

The UPLC-II<sup>TM</sup> can communicate via DNP 3 using one of the following ports/standards.

- Std. rear 9-pin D-sub connector (J4) via RS-232\* (Use Std. Straight-through 9-pin Serial Cable, Male to Female)
- Standard rear 9-pin D-sub connector (J4) via RS-485 (TX- = pin#2, TX+ = pin#8, RX- = pin#3, RX+ = pin#7)
- Optional rear Ethernet connector (TX1/RX1 or TX2/RX2) via TCP/IP–UDP

The account holder must have "User" privileges to set the DNP communications.

The UPLC-II<sup>TM</sup> DNP communications works in a slave mode as an outstation device and supports level 1 & 2 of the DNP 3 protocol. A DNP device profile can be generated by downloading the UplcDnpCfg.xml file into a folder with the appro-

priate DNP device profile xsd, xsx & xslt files (2009) and then opening the UplcDnpCfg.xml file.

## 7.1.1 DNP 3 Settings

# 7.1.1.1 Main DNP Web Page Settings

The following settings must be made on the main DNP page.

- 1) Click on the Admin button in the left task bar.
- 2) Next, click on the Protocol Tab.

3) Finally, click on the DNP Tab.

If the physical layer is set to RS-232 or RS-485 mode, a Baud rate must be chosen. For the TCP/IP—UDP mode, an IP port must be chosen.

### Physical Layer = RS-232 or RS-485

• Baud = 2400, 4800, 9600, 19200, 38400 or 115200

#### Physical layer = TCP/IP-UDP

- IP Port = 20000 (default) or 49152-65535
- UPLC-II<sup>TM</sup> DNP address = 1–65519
- Link Layer Confirm = Never, Multi or Always
- Unsolicited Responses = Disabled or Enabled

If "Unsolicited Responses" is enabled, the following additional settings must be made.

- Master DNP Address = 1–65519
- Confirmation Timeout (secs) = 1-60
- Number of Retries = 1-5 or indefinite

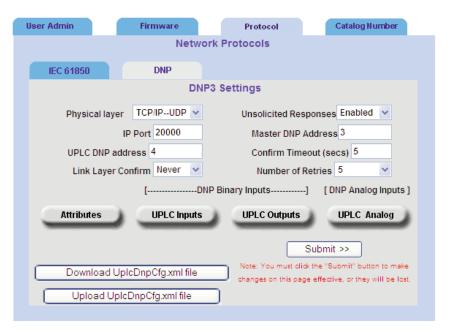


Figure 7–1. DNP Page (Admin > Protocol > DNP)

<sup>\*</sup> Terminal Emulator Program Settings: Data Bits/Per Word = 8 Stop Bits = 1 Parity = None Flow Control/Handshake = None



# 7.1.1.2 Secondary DNP Web Page Settings (Setting Up Data Points)

The UPLC-II<sup>TM</sup> sends only Binary Inputs and Analog Inputs to an RTU or SCADA master station. There are no DNP Outputs accepted by the UPLC-II<sup>TM</sup> from an RTU or SCADA master station. All points are programmable as to whether they will be included in a particular class poll and also to what variation (type of value) will be returned in the poll. All points can be set to a Class of "off" if the point is not valid for the selected UPLC-II<sup>TM</sup> function. All binary points in the UPLC-II<sup>TM</sup> report a value of 0 when "off" and a value of 1 when "on".

A separate pop-up window/page appears when you click on each of the 4 buttons at the bottom of the main DNP page. Only one pop-up page can be displayed at a time. Pop-up pages should be closed after viewing or changing. To close the page, you must either click "Submit", to send the changes to the UPLC-II<sup>TM</sup>, or click the "X" in the upper right corner of the page if there are no changes.

Basic information regarding the UPLC-II<sup>TM</sup> is located on the Attributes page. The following attributes, in green cells, can be edited.

- User-Assigned Location Name
- User-Assigned ID Code Number
- User-Assigned Name for Outstation

For the 3 DNP Input Web pages,

- 1) "UPLC-IITM Inputs" (Binary)
- 2) "UPLC-IITM Outputs" (Binary)
- 3) "UPLC-IITM Analog" (Analog)

the following settings must be made in the pop-up Web pages.

- Event/Static Data Class = Off, 0–3
- Description = Long Character String that User Can Enter Describing the DNP Input
- Default Variation for Static Data = 1–3 (1-5 for Analog Inputs only)
- Default Variation for Event Data = 1–3 (1-5 for Analog Inputs only)

Please refer to the following figures.

#### NOTE

You Can Double Click in Green Cells to Edit.

Variation	Dnp Type	Value
242	Device manufacturer's software version string	3.06.09
243	Device manufacturer's hardware version string	Rev 9
245	User-assigned location name or code string	Substation XX
246	User-assigned ID code/number string	Panel XX
247	User-assigned name string for the outstation	UPLC XX
248	Device serial number string	00075E000F17
249	DNP subset level and conformance	DNP3 Level 2
250	Device manufacturer's product name and model	UPLC Model US1NSC5ANSX
252	Device manufacturer's name string	Ametek Power Instruments, Inc.

Figure 7–2.

UPLC-II™ DNP Attributes Page

(Admin > Protocol > DNP > Attributes)



# 7.2 DNP Binary Inputs (UPLC-II™ Inputs)

The UPLC-II<sup>TM</sup> has five physical binary inputs that can be assigned numerous functions chosen from a selection menu. The following tables include all possible input selections for the UPLC-II<sup>TM</sup> ON/OFF and FSK modes. Since there are only five

inputs and many possible selections, at any given time some of these selections will be unassigned or not used. The on-line bits of these unassigned selections will be set to zero.

Table 7–1. UPLC-II™ Inputs – DNP Points (ON/OFF Mode)

Point	Name	Setting Mode	Definition
0	Carrier Start Key	All ON/OFF Modes	Carrier Start Input has been Keyed
1	Carrier Stop Key	All ON/OFF Modes	Carrier Stop Input has been Keyed
2	Low Level Key	All ON/OFF Modes	Low Level Keying Input has been Keyed
3	CB Alarm Reset	Checkback Option Only	Checkback Alarms have been Reset
4	CB Test Initiate	Checkback Option Only	Checkback Test has been Initiated
5	Loop Test Initiate	Checkback Option Only	Loop Back Test has been Initiated
6	User SOE 1 Key	All ON/OFF Modes	SOE Event 1 Input has been Keyed
7	User SOE 2 Key	All ON/OFF Modes	SOE Event 2 Input has been Keyed
8	User SOE 3 Key	All ON/OFF Modes	SOE Event 3 Input has been Keyed
9	High Power Key	All ON/OFF Modes	High Power Level has been Keyed
10	Low Power Key	All ON/OFF Modes	Low Power Level has been Keyed

Point Index	Name	Event/Static Data Class	UPLC function for which point is valid	Description	Default Variation for Static Data	Default Variation for Event Data
0	Carrier Start Key	1	All On-Off Modes	Example: Carrier started by Relay XX	1	1
1	Carrier Stop Key	1	All On-Off Modes		1	1
2	Low Level Key	2	All On-Off Modes		1	1
3	CB Alarm Reset	Off	Checkback option only		2	2
4	CB Test Initiate	Off	Checkback option only		3	3
5	Loop Test Initiate	Off	Checkback option only		1	1
6	User SOE 1 Key	3	All On-Off Modes		1	1
7	User SOE 2 Key	3	All On-Off Modes		1	1
8	User SOE 3 Key	3	All On-Off Modes		1	1
9	High Power Key	1	All On-Off Modes		1	1
10	Low Power Key	1	All On-Off Modes		1	1

Figure 7–3. DNP Binary Inputs / UPLC-II™ Inputs Settings Page (Admin > Protocol > DNP > UPLC-II™ Inputs)

February 2018 Page 7–3



### Table 7–2. UPLC-II™ Inputs – DNP Points (FSK Mode)

Point	Name	Setting Mode	Definition
0	3F DTT Trip Key	3-Freq. Only	DTT Trip Input Keyed (for 3–Freq. Mode)
1	LR Trip Key	2 or 3-Freq.	Line Relaying Trip Input Keyed (Unblock/2F, UB/POTT/3F)
2	TX Power Off Key	All FSK Modes	TX RF Power Off Input Keyed (Turns TX Off for Test)
3	TX Pwr Boost Key	All FSK Modes	Power Boost Input has been Keyed
4	User SOE 1 Key	All FSK Modes	SOE Event 1 Input has been Keyed
5	User SOE 2 Key	All FSK Modes	SOE Event 2 Input has been Keyed
6	User SOE 3 Key	All FSK Modes	SOE Event 3 Input has been Keyed
7	PC Key	Phase Comp.	Phase Comparison Input has been Keyed
8	Trip A Key	4-Freq. Only	Trip Channel A Input has been Keyed
9	Trip B Key	4-Freq. Only	Trip Channel B Input has been Keyed
10	Initiate Trip Test	Testing Only	Trip Test Input has been Keyed
		Option Enabled	(for Testing Purposes Only)
11	2F DTT/POTT	2-Freq. Only	DTT Trip of POTT Trip Input has been Keyed
	Trip Key		
12	TX Keyed Off	All FSK Modes	Transmit Keyed Off

# 7.3 DNP Binary Inputs (UPLC-II™ Outputs)

The UPLC-II<sup>TM</sup> has 10 or 14 binary outputs, depending on the model. Like UPLC-II<sup>TM</sup> inputs, you can assign these outputs in numerous ways. The following tables include all possible output selections for the UPLC-II<sup>TM</sup> ON/OFF and FSK modes. Since there are more selections than outputs, at any given time some of these selections will be unassigned and their on-line bits will be set to zero.



Table 7–3. UPLC-II™ Outputs – DNP Points (FSK Mode)

Point	Name	Setting Mode	Definition
13	General Failure	All FSK	Hardware Failure in the UPLC <sup>TM</sup>
14	RX Fade Alarm	All FSK	Rec. Level has Dropped Below Fade Alarm Setting
15	RX Noise Alarm	All FSK	Noise Alarm has Occurred
16	RX Good Chanel	All FSK	Channel Good (Rec. Signal Level & Freq. OK)
17	TX Refl Pwr Alarm	All FSK	% Refl Power Exceeded Alarm Threshold Setting
18	TX Main RF On	All FSK	TX Level on Main Power Amp Above 0.5W
19	TX Red. RF On	All FSK	TX Level on Redundant Power Amp Above 0.5W
20	Main PA Alarm	All FSK	Main Power Amp has Failed
21	Red. PA Alarm	All FSK	Redundant Power Amp has Failed
22	Main PS Alarm	All FSK	Main Power Supply has Failed
23	Red. PS Alarm	All FSK	Redundant Power Supply has Failed
24	Trip 1 Out	Non-PC FSK	Trip 1 Output Present (LF Trip for 2F,
			Line Relay Trip for 3F, Trip A for 4F)
25	Trip 2 Out	3F/4F Only	Trip 2 Output Present (DTT Trip for 3F, Trip B for 4F)
26	Guard 1 Out	Non-PC FSK	Guard 1 Output Present (HF Guard for 2F
			LR Guard for 3F, Guard A for 4F)
27	Guard 2 Out	3F/4F Only	Guard 2 Output Pres. (DTT Guard/3F, Guard B/4F)
28	CB Trip 1 Out	Non-PC FSK	Checkback Trip 1 Output Present (Rec. Trip 1 Freq.)
29	CB Trip 2 Out	3F/4F Only	Checkback Trip 2 Output Present (Rec. Trip 2 Freq.)
30	Trip Pos. Out	Phase Comp.	Trip Positive Output Present
31	Trip Neg. Out	Phase Comp.	Trip Negative Output Present
32	TX Shift High Freq	All FSK	Transmit Freq. Commanded to Shift High in Freq.
33	TX Shift Low Freq	All FSK	Transmit Freq. Commanded to Shift Low in Freq.
34	TX Shift Ch A Trip	4 Freq. Only	TX Freq. Keyed to Chan A Trip Freq. (F4)
35	TX Shift Ch B Trip	4 Freq. Only	TX Freq. Keyed to Chan B Trip Freq. (F2)
36	TX Shift ChAB Trip	4 Freq. Only	TX Freq. Keyed to Chan A/B Trip Freq. (F1)

Point Index	Name	Event/Static Data Class	UPLC function for which point is valid	Description	Default Variation for Static Data	Default Variation for Event Data
11	General Failure	1	All On-Off Modes	Example: UPLC XX in Panel XX has failed.	1	1
12	RX Signal Off	Off	All On-Off Modes		2	2
13	TX Refl Pwr Alarm	2	All On-Off Modes		3	3
14	RX Block Out	2	All On-Off Modes		1	1
15	RX Carrier Out	2	All On-Off Modes		1	1
16	TX Main RF On	2	All On-Off Modes		1	1
17	TX Redundant RF On	2	All On-Off Modes - If Present		1	1
18	Main PA Alarm	2	All On-Off Modes		1	1
19	Redundant PA Alarm	2	All On-Off Modes - If Present		1	1
20	Main PS Alarm	2	All On-Off Modes		1	1

Figure 7–4. DNP Binary Inputs / UPLC<sup>TM</sup> Outputs Settings Page (Admin > Protocol > DNP > UPLC-II™ Outputs)

February 2018 Page 7–5



# Table 7–4. DNP Binary Outputs – UPLC-II™ Outputs (ON/OFF Mode)

Point	Name	Setting Mode	Definition
11	General Failure	All ON/OFF	A Hardware Failure in the UPLC-II <sup>TM</sup>
12	RX Signal Off	All ON/OFF	Received Level Dropped Below Fade Alarm
			Setting (Active Unless Block Signal Received)
13	TX Refl Pwr Alarm	All ON/OFF	% Reflected Power has Exceeded
			Alarm Threshold Setting
14	RX Block Out	All ON/OFF	Carrier Block Output has Occurred
			from the UPLC™
15	RX Carrier Out	All ON/OFF	Carrier Receive Output has Occurred
			from the UPLC <sup>TM</sup>
16	TX Main RF On	All ON/OFF	TX Level on Main Power Amp
			Above 0.5W
17	TX Redundant RF On	All ON/OFF	TX Level on Redundant Power Amp
		If Present	Above 0.5W
18	Main PA Alarm	All ON/OFF	Main Power Amp has Failed
19	Redundant PA Alarm	All ON/OFF	Redundant Power Amp has Failed
		If Present	
20	Main PS Alarm	All ON/OFF	Main Power Supply has Failed
21	Redundant PS Alarm	All ON/OFF	Redundant Power Supply has Failed
		If Present	
22	CB Major Alarm	If CB Option	Checkback Major Alarm Occurred due to
		Present	Failure of High Level Checkback Test
23	CB Minor Alarm	If CB Option	Checkback Minor Alarm Occurred due to
		Present	Failure of Low Level Checkback Test
24	CB Delayed Alarm	If CB Option	Checkback Delayed Alarm Occurred due to
		Present	Failure to Exit Recovery Mode
25	CB Test Passed	If CB Option	Successful Checkback Test
		Present	
26	CB Test in Progress	If CB Option	Checkback Test in Progress
		Present	
27	CB in Recovery	If CB Option	UPLC-II™ Failed Checkback Test
		Present	and is In Recovery Mode
28	CB Recovered	If CB Option	UPLC-II™ Successfully Recovered from a CB
		Present	Test Failure, No Delayed Alarm
29	Auto CB Tests Off	If CB Option	Automatic Checkback Tests
		Present	Have Been Turned Off



## 7.4 DNP Analog Inputs (UPLC-II™ Analog Values)

The UPLC-II<sup>TM</sup> has 4 analog UPLC<sup>TM</sup> measured values that can be set to be read via DNP.

### Table 7–5. UPLC-II™ Analog Values (All Modes)

Point	Name	Definition
0	TX Signal Level	Measured Transmit Signal Level to Coax
1	RX Signal Level	Measured Receive Signal Level from Coax
2	RX Fade Margin	Measured dB RX Margin – Amount Signal can Fade & Still Work
3	Percent Reflected Power	Measured % Reflected Power for TX

Point Index	Name	Event/Static Data Class	UPLC function for which point is valid	Description	Default Variation for Static Data	Default Variation for Event Data
0	TX Signal Level	2	All	Example: UPLC XX 's transmit level	2	2
1	RX Signal Level	0	All		5	1
2	RX Fade Margin	Off	All		2	2
3	Percent Reflected Power	3	All		2	5

Figure 7–5.

DNP Analog Inputs / UPLC-II™ Analog Values Settings Page
(Admin > Protocol > DNP > UPLC-II™ Analog)

February 2018 Page 7–7



#### 7.5 IEC 61850 Protocol

### 7.5.1 UPLC-II™ with IEC 61850

IEC 61850 is the industry's standard for peer to peer communications within a substation. Data is transmitted over an Ethernet network in the substation, eliminating much of the wiring between devices that has historically been used to interconnect them. The UPLC-II<sup>TM</sup> is used as a pilot channel with transmission line relaying and major equipment breaker protection. Since IEC 61850 protocol allows for interconnecting the devices within the substation without the usual wiring, this eliminates the labor and cost associated with physical wiring. Since a template may be created for all the different devices, and copied for each project, this also eliminates the human factor in wiring errors from panel to panel.

It is not a point-to-point system but a multicast system whereby a message is generated by the UPLC-II<sup>TM</sup> to which the other devices in the substation subscribe. A new message is sent when there is a change to one of the data items and is repetitiously sent at increasing intervals until another data change occurs. Likewise, the devices and elements the UPLC-II<sup>TM</sup> has been programmed to subscribe to will produce these messages and the UPLC-II<sup>TM</sup> will respond accordingly. These messages can be a variety of functions, such as:

Permission to trip or a block input for pilot relaying

Request to initiate a checkback test function

Alarm output

Measured value such as transmitted power out or received level.

Some specifics to be aware of:

- 1. The LNodeType id is "ZPLC" and the InClass is "ZPLC".
- 2. The user will need to assign:
  - UPLC-IITM IEC name (the generic name the subscribing unit may use to identify the subscribed device)
  - Choose to enable the digital and/or analog GOOSE:

- MAC address (the destination address for the UPLC<sup>TM</sup> GOOSE message) Required to be of the form 01-0C-CDxx-xx-xx, with the first 3 fields always 01-0C-CD-
- APPID
- VLAN Priority
- GSE Control appID

These will need to be correct for the UPLC-II<sup>TM</sup> to subscribe to other devices to properly detect and process the information.

Figure 7–6 shows the GOOSE definitions page.

The .cid file will need to be uploaded to the UPLC-II<sup>TM</sup>. This is temporarily created manually. It must be named "api\_uplc.cid". AMETEK will assist any customer with their configuration.

The UPLC-II<sup>TM</sup> uses the "private subscription" section of the standard, since there are not standard object definitions at this time. A sample file is available from your local AMETEK sales representative.

What's available?

#### **Settings:**

ChannelType

RelayingFunction

TransmitterFrequency

ReceiverFrequency

ONOFFBandwidth

FSKTransmitterBandwidth

FSKReceiver Bandwidth

FSKTransmitterShift

**FSKReceiverShift** 

TransmitterHighPower

TransmitterLowPower

#### **GOOSE Outputs and Alarms:**

The outputs are divided into "high speed" and "slow speed" GOOSE messaging. The outputs that are direct protective functions are interpreted and



transmitted immediately (less than 1 ms) while those that are not direct protective functions are transmitted after a time period of approximately 5 ms to see if a high speed output change occurs prior to the time period. Should a high speed element change, then the message is transmitted immediately. These are outputted via the same "GOOSE" message. The only difference is the processing time. The high speed GOOSE outputs are bolded in the "Output" list below. The other outputs (as listed in Alarms) are slow speed GOOSE elements.

#### **Alarms**

These are the data items available from the UPLC-II<sup>TM</sup> to indicate functionality/health of the device. These are non-protection based functions.

GeneralFail

ReflectedPowerAlarm

TransmitterKeyedState

ReceivedState

PowerAmpOneAlarm

PowerAmpTwoAlarm

**FSKLowLevel** 

ONOFFCheckbackMajorAlarm

ONOFFCheckbackMinorAlarm

ONOFFCheckbackInRecovery

ONOFFCheckbackAutoOff

ONOFFCheckbackRecovered

ONOFF Checkback Delayed Alarm

ONOFFCheckbackPassed

ONOFFCheckbackOff

ONOFFCheckbackInProgress

ONOFFFadeAlarm

PowerSupplyOneAlarm

PowerSupplyTwoAlarm

FSKFadeMarginAlarm

**FSKFadeAlarm** 

**FSKShiftLowFrequency** 

#### NOTE

For loss of goose signal data, a general alarm output will occur and there will be a GSDL alarm code on the front display.

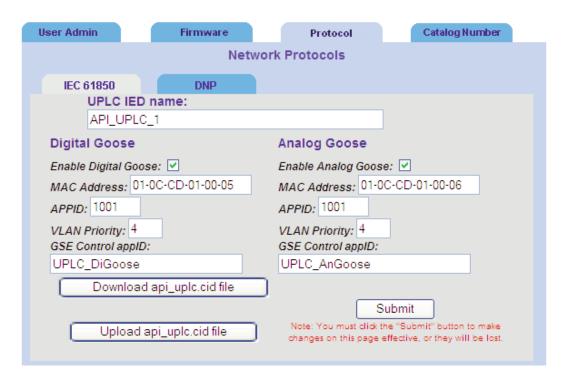


Figure 7–6. GOOSE Definitions Page (Admin > Protocol > IEC 61850)

February 2018 Page 7–9



FSKShiftHighFrequency

RF Output

### **Outputs**

These are the protection based outputs and therefore the "high" speed GOOSE data items.

**FSKTripOne** 

FSKGuardOne

FSKTripTwo

**FSKGuardTwo** 

FSKGoodChannel

**FSKNoise** 

FSKCheckBackTripOne

FSKCheckBackTripTwo

**FSKTripPositive** 

**FSKTripNegative** 

ONOFFBlockingOutput

#### **Control**

These data items allow the user to program functions for testing in the UPLC<sup>TM</sup>.

ONOFFCheckbackInitiate

**ONOFFLoopback** 

FSKTripTestInitiate

**FSKTripTestDisable** 

FSKTripTestReset

#### Subscribed data:

These are the data items that the UPLC-II<sup>TM</sup> will subscribe (listen) to. The data items must be identified in the CID file just as shown below. The remote device labeling can be anything the user desires. The position of the data item in the list is what determines the function, not the label.

**ONOFFCarrierStart** 

ONOFFCarrierStop

ONOFFLowLevelKey

ONOFFCheckbackReset

ONOFFCheckbackInitiate

ONOFFLoopBack

FSK52BKey

**FSKTripKey** 

**FSKLRKey** 

**FSKDTTKey** 

**FSKAkey** 

**FSKBKey** 

**FSKPowerOff** 

**FSKTripTestInitiate** 

FSKTripTestDisable

FSKTripTestReset

#### **Measured Values:**

These are analog values continuously sent via the analog GOOSE. These values can be used for reporting functions as needed by the user.

TransmitPowerLevel

TransmitPowerdB

ReceiveLevel

ReceiveLeveldB

Margin

MarginPercent

ReflectedPower

# 7.5.2 Private GOOSE Subscription Details

This section outlines the method by which the UPLC-II<sup>TM</sup> subscribes to and assigns functions to IEC 61850 GOOSE messages. The method of defining the GOOSE message that the UPLC-II<sup>TM</sup> uses is the IEC 61850 Private Data type. This section also describes the functions that can be assigned to incoming data.

Please note that the definition of "GOOSE" message within this section follows the definition of GOOSE messaging in IEC 61850 part 8, and should not be confused with UCA GOOSE messages (known as GSSE in IEC61850). You are encouraged to obtain a copy of the standard.

It is assumed that you are somewhat familiar with GOOSE messaging and the IEC 61850 standards. It is also assumed that you are familiar with the idea of configuration files using the Substation



Configuration Language (SCL), and the definitions of .ICD and .CID as device description files.

#### 7.5.3 Overview

The UPLC-II<sup>TM</sup> is capable of using the Configured IED Description file as a means of defining the communications parameters and the data of GOOSE Messages that the user needs the UPLC-II<sup>TM</sup> to "listen" to and perform functions based upon the data received. This definition of the Goose message is accomplished by using an IEC private data block containing the information in a structured manner. The private data block is contained within the UPLC-II<sup>TM</sup>'s .cid file, and can be edited to produce the desired data to function mapping.

When editing the .cid file, you should use a non-formatting editor such as Windows® Notepad, or if a formatting editor is used then be sure to save the file as a plain ASCII text file. The SCL interpreter is sensitive to embedded formatting characters, or ANSI escape sequences. If the .CID file contains these characters the file will not load.

Figure 7–7 shows an example of the UPLC-II<sup>TM</sup> <Private /> GOOSE subscription block.

The color coding is as follows:

Green – The <Private> </Private> block as described in the IEC61850 section "Private parts"

Blue – The UPLC-II<sup>TM</sup> private definition of a "GooseSubscription".

Proper XML and IEC formatting require the use of a "Private namespace" denoted by the eapi: prefix, and an opening item paired with a closing item. i.e. <eapi:GooseSubscription>.....................</eapi:GooseSubscription>. Note that all IEC definitions ARE case sensitive. The GooseSubscription contains the communication parameters, and the IEC data that uniquely identify the incoming GOOSE. Due to publication formatting, this line has been split into multiple lines, but in the actual .cid file, it is one long line.

Orange – order sensitive multiple definitions that correspond with the data order of the incoming GOOSE message.

These definitions allow the UPLC-II<sup>TM</sup> to call functions based upon the incoming data value. Note that the number of definitions MUST correspond to the number of data items contained in the received GOOSE message, *EXACTLY*. For example, if the GOOSE message contains 6 items, then there MUST be 6 definitions. This is true regardless if the

Figure 7–7.
Example GOOSE Subscription Block

February 2018 Page 7–11



data is to be used by the UPLC-II<sup>TM</sup> as an input to the function or if the UPLC-II<sup>TM</sup> is to ignore the data. The null function "UPLCNoFunction" is provided for the purpose of ignoring the value from the perspective of the UPLC-II<sup>TM</sup>.

The GOOSE subscription private data MUST be defined within the <IED>...</IED> section of the .cid file.

Below are the detailed descriptions and definitions for each of the above sections.

#### **IEC Private Parts**

The IEC allows for the use of extensions within the .CID file. These extensions are for manufacturers' use, and are not standardized as to the content. The unique identification of the private data objects is accomplished by using XML namespaces. A full description of this is beyond the scope of this manual. For further education you are referred to the XML standards available at www.w3.org and the IEC 61850 standards.

# The UPLC-II<sup>TM</sup> GooseSubscription Definition

The UPLC-II™ GooseSubscription contains attributes that define the IEEE 802.1Q vlan information and the IEC 61850 information that uniquely identify the incoming GOOSE message. The need for the identification is to allow the UPLC-II™ to reject GOOSE messages at the various layers of the protocol.

From the example above:

<eapi:GooseSubscription iedName="SEL\_421\_1"
ldInst="CFG" cbName="Conf" datSet="PLC"
confRev="1" mAddr="01-0C-CD-01-00-02"
maxTime="500" vlanPriority="4"
a p p I d = " S E L \_ 4 2 1 \_ 1 "
goCbRef="SEL\_421\_1CFG/LLN0\$GO\$PLC"
datSetRef="SEL\_421\_1CFG/LLN0\$PLC">

#### **GooseSubscription Attributes:**

iedName

This is the name of the sending IED.

ldInst

The identifier of the <GSE/> protocol communication definition. Also contained in the data definition per data item within the <FCDA/> for each.

cbName

The control block name of the issuing GOOSE messages' control block.

datSet

The data set name of the data contained within the issuing GOOSE message.

confRev

The configuration revision contained within the control block of the issuing message.

mAddr

The GOOSE messages' destination address.

maxTime

Maximum time to live in milliseconds.

vlanPriority

The 802.1Q vlan priority level.

appId

The appId assigned to the GOOSE message by the <GSEControl /> block.

goCbRef

The IEC61850 address of the GOOSE control.

datSetRef

The IEC61850 address of the data set.

#### The UPLC-II™ GooseRXEntry Definitions

When GOOSE messages are defined in an IEDsí .cid file they consist of three separate "parts". In the <Communication/> block there is the <GSE /> definition, which defines the destination address ("MAC address"), the APPID and the VLAN-PRI-ORITY. In the <IED> <AccessPoint> <Server><LDevice><LN0> block, there are two definitions that contribute to the GOOSE message:

The <DataSet> and the <GSEControl>.

The <GSEControl> creates an instance in the server that allows for control of the GOOSE messaging from the IEC 61850 client-server access.



The <DataSet> contains a list of data entries each known as <FCDA>. These entries form the content of the GOOSE message. The number of entries and the order of the data are defined by the IEC 61850 variables contained within the <FCDA>s.

You are encouraged to seek the relevant sections of the standards for further information regarding GOOSE message definitions.

For the purposes of this section, it is necessary to determine the number of entries in the GOOSE message subscription, what type they are, and the order the entries are in.

For each entry in the GOOSE message there MUST be a corresponding entry in the UPLC-IITM GooseSubcription block. Both the order and the number of entries must be exact.

Note: The UPLC-II<sup>TM</sup> at this time is only capable of receiving BOOLEAN entries from a GOOSE message.

As an example, suppose that IED "OaklandPark" is issuing a GOOSE message containing the following:

```
<Communication>
 < SubNetwork name="W01" type="8-MMS">
 <ConnectedAP iedName="OaklandPark" apName="S1">
   <GSE ldInst="C1" cbName="TripControl" >
    <Address>
         <P type="MAC-Address">01-0C-CD-01-00-01</P>
         <P type="APPID">1001</P>
         <P type="VLAN-PRIORITY">4</P>
    </Address>
    <MaxTime unit="s" multiplier="m">500</MaxTime>
   </GSE>
 </ConnectedAP>
 </SubNetwork>
<Communications>
```

(The above example is edited to show only the items that are needed to define the UPLC-IITM GOOSE subscription. In an actual .cid file, there will be more blocks between <ConnectedAP> and </ConnectedAP> defining the systems' OSI addressing, and optionally other interfaces, such as serial, and possibly other GOOSE messages.)

Further, suppose that IED "OaklandPark" has the following located in the <IED> section:

(For clarity, there are line breaks between the <FCDA> entries. Normally this is not done within the file. Also, the <FCDA> entries are contained in one line, however due to the limitations of the width of this section, the entry wraps around. The same wrap around occurs in the <GSEControl>)

<LN0 desc="description" lnType="LN0" lnClass="LLN0" inst="">

<IED name="OaklandPark">

...(Services are defined here)

<AccessPoint name="S1">

<LDevice desc="description" inst="C1">

<Server>

```
<DataSet name=" TripControlData" desc="Goose Trip Control
Data">
<FCDA ldInst="C1" lnClass="LLN1" lnInst="1" doName="TripOne"
daName="stVal" fc="ST" />
<FCDA ldInst="C1" lnClass=" LLN1" lnInst="1" doName="TripTwo"
daName="stVal" fc="ST" />
<FCDA ldInst="C1" lnClass=" LLN1" lnInst="1" doName="52B"
daName="stVal" fc="ST" />
<FCDA
            ldInst="C1"
                           InClass="
                                         LLN1"
                                                    lnInst="1"
doName="DisableTx" daName="stVal" fc="ST" />
           ldInst="C1"
                           InClass="
                                                    InInst="1"
<FCDA
                                         LLN1"
doName="TripTestStart" daName="stVal" fc="ST" />
</DataSet>
                  name="
<GSEControl
                               TripControl"
                                                  confRev="1"
appID="TripControlappID" datSet="TripControlData"
Trip Control"/>
  </LLN0>
</LDevice>
</Server>
</AccessPoint>
</IED>
Using the data above, the UPLC-II<sup>TM</sup> Goose sub-
```

scription can be constructed:

<Private type="Ametek GooseSubscription">

```
<eapi:GooseSubscription iedName=" OaklandPark " ldInst="CFG"</p>
cbName="TripControl " datSet=" TripControlData " confRev ="1"
mAddr="01-0C-CD-01-00-01" maxTime="500" vlanPriority="4"
appId="
                        TripControlappID
goCbRef="OaklandParkC1/LLN0$GO$TripControl"
datSetRef="OaklandParkC1/LLN0$TripControlData"">
```

```
<eapi:GooseRxEntry gooseData="FSKTripKey" type="Bool"/>
<eapi:GooseRxEntry gooseData="FSKTripKey" type="Bool"/>
<eapi:GooseRxEntry gooseData="FSK52BKey" type="Bool"/>
```

Page 7-13 February 2018



.....<eapi:GooseRxEntry gooseData="FSKTripTestInitiate" type="Bool"/>

<eapi:GooseRxEntry gooseData="FSKPowerOff" type="Bool"/>
<eapi:GooseSubscription/>

</Private>

(The gooseData="xxxxx" map the incoming GOOSE bits to UPLC-II™ input functions. These keywords and definitions are in the next section.)

Note that there are 5 GOOSE entries in the example. The number of GOOSE entries MUST agree with the GOOSE message and the GOOSE subscription, otherwise the GOOSE message will be rejected by the UPLC-II<sup>TM</sup>.

# **UPLC-II™ GOOSE subscription input** functions

The UPLC-II<sup>TM</sup> provides the following input functions for mapping to incoming GOOSE data. Note that these functions are positive logic (1 = TRUE).

**ONOFFCarrierStart** 

Turn on the transmitter in AM mode only.

ONOFFCarrierStop

Turn off the transmitter in AM mode only. The priority of these items is set in the UPLC-II™ logic settings.

ONOFFLowLevelKey

Turn on transmitter at the low power setting.

ONOFFCheckbackReset

Clear all checkback alarms.

ONOFFCheckbackInitiate

Start a checkback test. Progress and results can be monitored via the UPLC-II<sup>TM</sup> output GOOSE.

ONOFFLoopBack

Start a loopback test.

FSK52BKey

Boost the transmitter to high power in FSK mode.

**FSKTripKey** 

Key the transmitter to Trip in FSK.

**FSKLRKey** 

Key the transmitter to LRTrip in FSK 3F and 4F function only.

#### **FSKDTTKey**

Key the transmitter to DTT Trip in FSK 3F and 4F function only.

**FSKAKey** 

Key the transmitter to A in FSK 4F mode only.

**FSKBKey** 

Key the transmitter to B in FSK 4F mode only.

**FSKPowerOff** 

Turn off the transmitter.

FSKTripTestInitiate

Start a trip test.

FSKTripTestDisable

Disable trip tests system wide.

FSKTripTestReset

Reset trip test alarms.

**UPLCNoFunction** 

Do nothing.

Notes:

- The ONOFF prefix means the function will operate in ON/OFF mode only. FSK prefix means that the function will operate in FSK mode only.
- Some functions are used in specific relaying functions only. For example, FSKAKey and FSKBkey will operate in FSK 4 Frequency mode only.
- 3. These functions may be overridden by local settings. For example, if the UPLC-II<sup>TM</sup> logic setting checkback is disabled, then the OFFCheckbackInitiate will have no effect. All inputs and logic settings must allow for the function to operate.
- 4. ONOFFCheckbackInitiate, ONOFFLoopback, FSKTripTestInitiate all operate on a transition from a logic FALSE (Input value '0') to a logic TRUE (Input value '1'). The tests will operate then finish. For the test to be initiated again, the input MUST return to FALSE, then TRUE. If a test is in progress and the input changes state from TRUE, to FALSE, then TRUE again,



there will be no effect. i.e. the test inputs are not "queued" in the time dimension.

- 5. The function UPLCNoFunction is provided as a place holder so that the UPLC<sup>TM</sup> can ignore bits in the incoming GOOSE message at the user's discretion.
- 6. All of these inputs are type="Bool" which is short for BOOLEAN as defined by IEC 61850.

# Downloading, modifying, and uploading the api\_uplc.cid data file

(It is assumed that you are familiar with the UPLC-II<sup>TM</sup> web page interface. If not, please refer to Chapter 5 for details.)

The UPLC-II<sup>TM</sup>, when enabled for IEC 61850 protocol, has the ability to generate an api\_uplc.cid file on the tab located under Admin->Protocol>IEC 61850 (See Figure 7–6).

The settings on this page (Fig. 7–8) allow you to change the parameters of the UPLC-II<sup>TM</sup> 61850

operation regarding the GOOSE messages produced by the UPLC-II<sup>TM</sup>. To obtain a copy of the UPLC-II<sup>TM</sup> api\_uplc.cid file, click the button "Download UPLC .CID file". The browser interface will prompt you to save the api\_uplc.cid file to your local hard drive.

You then may edit the api\_uplc.cid file to construct a GOOSE Subscription.

The default api\_uplc.cid file contains a sample GOOSE Subscription block that may be edited. Be sure to use a non-formatting text editor such as Windows® Notepad, or a programming editor.

Figure 8–8 shows the api\_uplc.cid file with the yellow line indicating the start of the GOOSE Subscription block. Due to rapid development, the actual api\_uplc.cid file may be slightly different than shown. Also note that in this editor lines do not wrap, so the attributes of the GOOSE subscription are not all shown.

You can now make changes to the GOOSE subscription data.

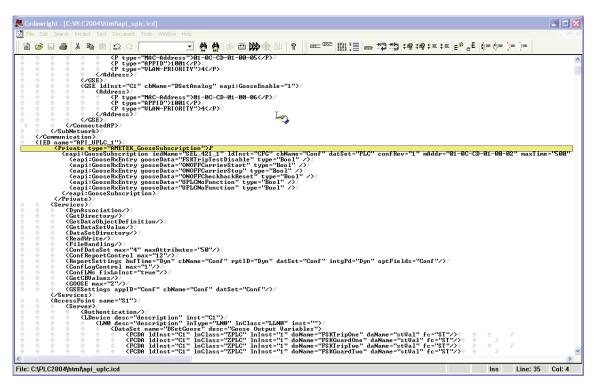


Figure 7–8. UPLC-II™ .cid File

February 2018 Page 7–15



## **USER NOTES**



# Appendix A: UPLC-II™ Serial Connection Configuration

#### Windows XP

Setup of a computer running Windows XP to connect to the front serial port

- 1. Click the "Start" button in the lower left hand corner of the screen.
- 2. Then click on the "Control Panel" button to open the Control Panel.
- 3. Select the "Phone & Modem Options" button in the Control Panel.
- 4. Select the "Modems" Tab in the Phone & Modem Options window.
- 5. Then click the "Add" button and this will open the Add Hardware Wizard.
- 6. Click on the check box that says "Don't detect my modem; I will select it from a list." Then click on the "Next" button.
- 7. In the box labeled Manufacturer select "(Standard Modem Types)" and under models on the right select "Communications" cable between two computers" then click on the "Next" button.
- 8. Now select the serial port number that you will use to communicate to the UPLC-II<sup>TM</sup>. Then click the "Next" button.
- 9. You should now see a box that says, "your modem has been set up successfully" Then click on the "Finish" button. After a short delay you should then see the connection appear in the Modem tab of the "Phones and Modem Options" window.
- 10. Now click on the new modem connection to highlight it. A "Properties" button should appear at the bottom of the window. Click on this "Properties" button, and wait for the properties window to open.
- 11. When the properties window opens click on the "Modem" tab and select the Maximum Port Speed pull down menu. Select a port

#### NOTE

In order for your settings to take effect, you must click the "Continue" button on each page.

- speed of 115200. Then click on the "OK" button.
- 12. Now click the "OK" button to close the Phone & Modem Options window.
- 13. Now you have to set up the network connection. This is done by opening the Control Panel again and clicking on the Network Connection Icon.
- 14. When the Network Connections window opens click on "Create a new connection" on the left side of the window under the heading Network Tasks.
- 15. When the New Connection Wizard window opens just click on the "Next" button and the "What do you want to do?" window will open.
- 16. Click on "Set up an advanced connection" and then click the "Next" button.
- 17. The "Which type of connection do you want to set up" appears. In this window you want to select "Connect directly to another computer" and then click the "Next" button.
- 18. In the "Host or Guest?" window select "Guest" and then click the "Next" button.
- 19. Now you are asked for a Computer Name. This is the name you want for the connection. A suggestion might be UPLC-II<sup>TM</sup> Connection. Then click the "Next" button.
- 20. Now you are asked to select the communications device. Select the "Communication cable between two computers (COMX)" device. Where COMX is the COM port you had set up before. For most computers this will be COM1. Click the "Next" button.
- 21. You are asked to select who will use this connection. Select which one will apply to your computer and then click the "Next" button.
- 22. The Completing the New Connection Wizard window will pop up. At this time

February 2018 Page A–1



- you may choose to add an icon to your desktop or not. Then choose "Finish."
- 23. At this point the connect window will pop up. It will have a space to put in a User Name and Password. At this time these are left blank. Click on the "Properties" button. The General Tab should now be showing and you should see a pull down menu titled Select a device.
- 24. Pull down the menu, by selecting the down arrow on the right. Select the device that was set up for UPLC-II<sup>TM</sup> communications. Then click on the "Configure" button and this will bring up a Modem Configuration window. If it isn't already set select the Maximum speed to 115200. Also make sure the "Enable hardware flow control" box is checked. Nothing else should be checked. Now click "OK."
- 25. Click on the Networking Tab of the Properties window. Then highlight the Internet Protocol (TCP/IP), and then click on the "Properties" button.
- 26. Select the radio button titled "Use the following IP address:" and then enter 100.100.100.101 in the IP address location. Then click on the "OK" button.
- 27. The area titled "Type of dial-up server I am calling:" should have "PPP: Windows 95/98/NT 4/2000, Internet" selected. If that isn't selected then select it.
- 28. Click the "OK" button
- 29. You are now ready to connect to the UPLC-II<sup>TM</sup> Front Panel.

This completes the Windows XP setup process.

#### Windows 7

- 1. If you are using an RS-232 to USB converter, make sure the drivers for the converter are installed and that they use a comport that does not change each time your computer is rebooted.
- 2. Click the "Start" button in the lower left hand corner of the screen.
- 3. Then click on the "Control Panel" button in the right hand panel to open the Control Panel.
- 4. **Note:** This write-up assumes your are using the control panel in the classic view.
- 5. Select the "Phone & Modem" button in the Control Panel.
- 6. Select the "Modems" Tab in the Phone & Modem window.
- 7. Then click the "Add" button and this will open the Add Hardware Wizard.
- 8. Click on the check box that says "Don't detect my modem; I will select it from a list." Then click on the "Next" button.
- 9. In the box labeled Manufacturer, select "(Standard Modem Types)" and under models on the right, select "Communications cable between two computers" then click on the "Next" button.
- 10. Now select the serial port number that you will use to communicate to the UPLC-II<sup>TM</sup>. Then click the "Next" button.
- 11. After a brief period of time, you should now see a box that says, "your modem has been set up successfully". Then click on the "Finish" button. After a short delay you should then see the connection appear in the Modem Tab of the "Phones and Modem" window.
- 12. Now click on the new modem connection to highlight it. A "Properties" button should appear at the bottom of the window. Click



- on this "Properties" button, and wait for the properties window to open.
- 13. When the properties window opens, click on "Change Settings" at the bottom of the window.
- 14. Wait for a new properties window to open. Then click on the "Modem" Tab and select the Maximum Port Speed pull down menu. Select a port speed of 115200. Then click on the "OK" button.
- 15. Now click the "OK" button to close the Phone & Modem window.
- 16. Now you have to set up the network connection. This is done by opening the Control Panel again and clicking on the Network and Sharing Center Icon.
- 17. When the Network and Sharing Center window opens, click on "Set up a new connection or network" of the window under the heading, Change your networking settings.
- 18. When the Choose a connection option window opens, just click on "Setup a dial-up connection". And then click the "Next" button
- 19. If you have more than one modem connected, you will get a popup box that asks "Which modem do you want to use?" Choose the one that says "Communications cable between two computers." If you only have one connection, you may not see this popup box and will go directly to step 20.
- 20. In the Dial-up phone number box, type any number. A suggestion might be to type a 1.
- 21. In the box labeled, Connection Name, enter a name for the connection, that you will recognize. A suggestion might be UPLC-II Serial Connection. Then click the "Connect" button. It will attempt to dial the connection. Wait until it times out and you get a box that says, Connection failed with error 777. In this box you will have two choices. Select the "Set up the connection anyway" choice.
- 22. You will now get a box that says "The connection to the Internet is ready to use." Click the "Close" button in this box. The

- computer will take you back to the Network and Sharing center window. At this point click on the choice, "Connect to a network". A new box will pop up which lists the connections available. You should see the new connection with the name you selected. Move the mouse to that connection and right click, then select Properties.
- 23. In the Connect using: you should see the words "Communication cable between two computers (COMX)" device. Where COMX is the COM port you had set up before. For most computers this will be COM1. Click on it to select it. At this point select the move down to the dummy phone number you put in and remove it.
- 24. Now click on the "Configure" button below the box in the previous step. The "Modem Configuration" window pops up. Be sure the Maximum speed is set to 115200 bps. Also make sure the "Enable hardware flow control" box is checked. Now click the "OK" button.
- 25. Now click on the "Options" Tab. Uncheck the "Prompt for name and password, certificate, etc." box. Also uncheck the "Prompt for phone number" box.
- 26. Click on the box labeled "PPP Settings." The only box that should be checked is "Enable LCP extensions." Uncheck all others.
- 27. Click the Networking Tab of the Properties window. Then highlight Internet Protocol Version 4 (TCP/IPv4), and then click on the "Properties" button.
- 28. Select the radio button titled "Use the following IP address:" and then enter 100.100.100.101 in the IP address location. Then click on the "OK" button.
- 29. Click the "OK" button
- 30. You are now ready to connect to the UPLC-II<sup>TM</sup> Front Panel.

This completes the Windows 7 setup process.

February 2018 Page A–3



# Connecting to the UPLC-II with this Serial Port

- Connect your serial cable to the serial port selected as COMX or if using a USB to serial converter connect the USB end to a USB port on your computer.
- 2. Then connect the other end of the cable to the UPLC-II<sup>TM</sup>.
- 3. Either select the connections icon on the system tray if you have one, or open the Network and Sharing Center.
- 4. If you selected the network connections icon from the system tray, the "Connections are available" dialog box will appear. Skip to step 6.
- 5. If you opened the Network and Sharing Center, click on "Connect to a network" under the Change your networking settings. This will pop up the same "Connections are available" dialog box as in step 4.
- 6. Click on the connection that has the name you used for the UPLC-II<sup>TM</sup>. Then click on the "Connect" button.
- 7. Several Dialog boxes will pop up and disappear. Some will be slow and some will be very fast. The last one will say "Connected."
- 8. If you want, you may select the network connection icon in the system tray and under the UPLC connection, the word *connected* will appear.
- 9. Now open internet explorer and in the URL box, type "http://100.100.100.100/" and press return. At this point, the UPLC II<sup>TM</sup> password box will pop up. Type in the UPLC II<sup>TM</sup> username and password that has been setup for your use.

- 10. The home screen for the UPLC II™ should now appear after a short delay.
- 11. Do the work you need to do.
- 12. When you have completed your work, do not disconnect the serial cable from your computer. At this point, instead, click on the Log out in the upper left hand corner of the home screen.
- 13. Click "OK" to the dialog box that appears. Then click "yes" to the Question, "Do you want to close internet explorer." *Do not unplug the serial cable from your computer or the UPLC-II*<sup>TM</sup> *until you complete step 14.*
- 14. Next, click the network icon in the system tray and click on the UPLC II<sup>TM</sup> connection, then click on the Disconnect box.

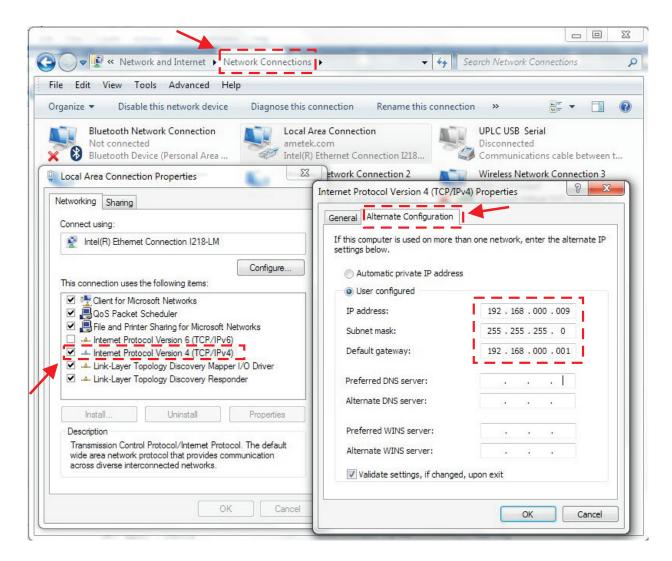
This completes your connection session with the UPLC-II<sup>TM</sup>.

Warning: If you do not perform steps 12, 13 and 14 before disconnecting your computer, on UPLC II<sup>TM</sup> versions 2.05 and less, you will have to reboot the UPLC-II<sup>TM</sup> before you will be able to connect again. On versions greater than 2.05, you will not have to reboot but you will have to wait before you can reconnect again by the amount set in the timeout setting on the administration page (30 minutes by default).



# **Appendix B: PC Setting for Static IP Address**

- 1. Locate Network Connections on your PC. (See Figure below)
- 2. Right click and choose Properties.
- 3. Click on "Internet Protocol Version 4 (TCP/IPv4).
- 4. Click the Properties button.
- 5. In either the "Alternate" or "General" tab select "User Configured".
- 6. Enter a static IP address with last group of 3 digits different from the UPLC-IITM IP address.
- 7. If on a LAN also set default gateway.



Network and Internet Connections

February 2018 Page B–1



## **USER NOTES**



# Appendix C: UPLC-II™ XML File Format

Here is an example of a configuration file down-loaded from the UPLC-II<sup>TM</sup>. This is an XML file. The file can be checked with any common XML tools to see if it conforms to XML format rules. It can be edited in any standard text-editing program, however you must be certain not to change any of the XML required format. If you are going to edit the file in a text editor it is important that you understand the format requirements of an XML file.

The file has a main section <UPLC-II<sup>TM</sup>>, also called the 'root node'. The main section encompasses three major sub-sections;

```
<genset> - General Settings
<logset> - Logic Settings
<ioset> - Input/Output Settings
```

The Inputs/Outputs settings also has a three minor sub-sections;

```
<inputs> - Inputs
<tdoutputs> - Trip Duty Outputs
<lloutputs> - Low Level Outputs
```

These sections encompass the entire configuration for the UPLC-II<sup>TM</sup>. Typically this file should be system generated to avoid any typographic and syntax errors. Rather than starting from scratch, it's easier to download from the UPLC-IITM and create a configuration file first, then edit that before uploading it back to the UPLC-IITM. After uploading you should review the changes on the settings pages to ensure they're correct before locking them in by submitting. The XML configuration file can be loaded into any text editor and the data can be changed. We recommend you familiarize yourself with the nuances of the eXtensible Markup Language (XML Files), prior to attempting any changes to the data in the file. Be careful not to change any file formatting or the file will not load properly.

Following, is an example of the downloaded XML file. The data in the example file is shown in bold for instructional purposes only.

NOTE: It will not and should not be in bold in the downloaded or uploaded file.

```
<?xml version="1.0" encoding="ISO-8859-1"?>
<!--UPLC-II Configuration for 10.14.3.127 as of
Mon Sep 10 11:17:50 2007-->
<UPLC-II>
   <system>
      <ppc version>2.00</ppc version>
   </system>
   <genset>
      <id line0>System
                           ID
                                 text
                                         string
      1</id line0>
      <id line1>System
                           ID
                                 text
                                         string
      2</id line1>
      <chan type>1</chan type>
                                   // AM - 0 FSK
      <functn>1</functn>
      <tx freq>250.00</tx freq>
      <rx freq>252.00</rx freq>
      <txbwshift mode="FSK">2</txbwshift>
      <rxbwshift mode="FSK">2</rxbwshift>
      <tx low>1.0</tx low>
      <tx hi>10.0</tx hi>
      <fade alarm>10</fade alarm>
      <fade margin>15</fade margin>
      <reflpwr>15</reflpwr>
      <shift up to trip tx>0</shift up to trip
      <shift_up_to_trip_rx>0</shift_up_to_trip_</pre>
      <tr_rx_enable>3</tx_rx_enable>
   </genset>
   <logset>
      <voice>1</voice>
      <ptt delay1>2</ptt delay>
      <trip hold1>0</trip hold1>
      <quard hold1>0
      <ptt delay2>30</ptt delay2>
      <trip hold2>35</trip hold2>
      <guard hold2>40</guard hold2>
      <unblock time1>0</unblock time1>
      <unblock delay1>0</unblock delay1>
      <ttu0>2</ttu0>
      <guard t0>2</guard t0>
```

February 2018 Page C–1



```
</loaset>
<ioset>
<inputs>
 <in1 hold>0</in1 hold>
 <in1 selection>1</in1 selection>
 <in1 active state>0</in1 active state>
 <in2 hold>0</in2 hold>
 <in2 selection>2</in2 selection>
 <in2 active state>0</in2 active state>
 <in3 hold>0</in3 hold>
 <in3 selection>0</in3 selection>
 <in3 active state>0</in3 active state>
 <in4 hold>0</in4 hold>
 <in4 selection>0</in4 selection>
 <in4 active state>0</in4 active state>
 <in5 hold>0</in5 hold>
 <in5 selection>0</in5 selection>
 <in5 active state>0</in5_active_state>
 </inputs>
 <tdoutputs>
 <em1 selection>0</em1 selection>
 <em2 selection>0</em2 selection>
 <em3 selection>0</em3 selection>
 <em4 selection>0</em4 selection>
 </tdoutputs>
 <lloutputs>
 cprog1 selection>1
 og1 active>0 active>
 cprog1_action>0
 cprog2_selection>2
 cprog2_active>
 cprog2_action>0
 og3 selection>6
 g3 active>
 og3 action>0
 cprog4 selection>7/prog4 selection>
 cprog4_active>
 cprog4_action>0
 cprog5_selection>
 og5 active>0
 cprog5 action>0
 og6 selection>10
 og6 active>
 og6 action>0
 og7 selection>4
 og7 active>
 og7 action>0
 og8 selection>0
```

# Configuration File Modification(Firmware Ver. 3.00 and later)

System identifies the firmware version and can not be changed.

```
<system>
```

<ppc version>3.02</ppc version</pre>

#### **General Settings**

#### **System Identification**

```
<id_line0>System Identification Line
1</id_line0>
```

```
<id_line1>System Identification Line II </id_line1>
```

These two lines are 40 characters free form text. You are free to enter any text here to identify the system.

#### Channel

```
<chan type>1</chan type>
```

This indicates the channel type and is a single digit value.

- 0 Configures the system to operate in AM or otherwise called ON/OFF mode
- 1 Configures the system for operation in FSK Mode

#### **Function**

```
<functn>1</functn>
```

Function allows you to choose the function type. This is a number between 0 & 3 depending on the choice of mode.

If the Channel is configured for AM Mode, you can choose from the following types:

- 0 Phase Comparison
- 1 Directional Comparison



If the Channel is configured for FSK Mode, you can choose from the following types:

- 0 Phase Comparison
- 1 Unblocking-2Frequency
- 2 DTT-2Frequency
- 3 POTT 2-Frequency
- 4 3-Frequency
- 5 4-Frequency

#### TX & RX Frequency

<tx freq>250.35</tx freq>

<rx freq>252.55</rx freq>

These are the transmit and the receive frequencies within the range of 30 to 530 kHz in steps of 0.01 kHz, e.g. 250.55 is 250.55 kHz.

#### Bandwidth and Shift

Bandwidth & shift is specified as a single digit number:

#### ON/OFF Mode

- <br/>
  <br/>
  bandwidth>1</br/>
  /bandwidth>
- 1 Sets the bandwidth to 600 Hz.
- 2 Sets the bandwidth to 1200 Hz.
- 3 Sets the bandwidth to 4000 Hz.

#### FSK Mode

<txbwshift mode="FSK">2</txbwshift>

<rxbwshift mode="FSK">2</rxbwshift>

This is called the TX Bandwidth-Shift & RX Bandwidth-Shift

- 0 Sets the bandwidth-shift to 300±100 Hz.
- 1 − Sets the bandwidth-shift to 600±100 Hz.
- 2 Sets the bandwidth-shift to  $600\pm250 \text{ Hz}$ .
- 3 Sets the bandwidth-shift to 1200±250 Hz.
- 4 Sets the bandwidth-shift to 1200±500 Hz.

#### FSK - 3 & 4-Frequency has only

- 0 Sets the bandwidth-shift to 600±250 Hz.
- 1 − Sets the bandwidth-shift to 1200±500 Hz.

#### Tx Power

<tx low>1.5</tx low>

<tx hi>9.5</tx hi>

The tx\_hi and tx\_low values must be between 1 & 10 W in steps of 0.1 W, with tx\_low smaller than tx hi, e.g. 1.5 specifies 1.5 W.

#### Fade Alarm

<fade alarm>10</fade alarm>

Fade Alarm is between 1 & 25 dB

#### Fade Margin

<fade\_margin>15</fade\_margin>

Fade Margin is between 1 & 25 dB

#### Reflected Power

<reflpwr>15</reflpwr>

Reflected power is 1 to 100% in 1% increments

### Shift Up to Trip

<shift\_up\_to\_trip\_tx>0</shift\_up\_to\_trip\_tx>
0-sets the transmitter to see a shift down to trip signal

1-sets the transmitter to see a shift up to trip signal

<shift up to trip rx>0</shift up to trip rx>

0-sets the receiver to see a shift down to trip signal

1-sets the receiver to see a shift up to trip signal

#### Transmit/Receive Enable

<tx rx enable>3</tx rx enable

- 3-Both transmitter and receiver enabled
- 2–Receive only (transmitter is disabled)
- 1-Transmit only (receiver is disabled)

#### **Logic Settings**

Pre-trip Delay (Valid for FSK Mode Only)

<ptt delay>30</ptt delay>

Pre-trip Delay is 0 - 30 ms in 1 ms steps.

Trip Hold (Valid for FSK Mode Only)

<trip hold>10</trip hold>

Trip Hold is 0 - 100 ms in 1 ms steps.

Guard Hold (Valid for FSK Mode Only)

<guard hold>15/guard hold>

Guard Hold is 0 - 100 ms in 1 ms steps.

February 2018 Page C-3



Pre-trip Delay (Valid for FSK Mode Only)

<ptt3\_delay>30</ptt3\_delay>

Pre-trip Delay is 0 - 30 ms in 1 ms steps.

Trip Hold (Valid for FSK Mode Only)

<trip3\_hold>35</trip3\_hold>

Trip Hold is 0 - 100 ms in 1 ms steps.

Guard Hold (Valid for FSK Mode Only)

<guard3 hold>40/guard3 hold>

Guard Hold is 0 - 100 ms in 1 ms steps.

<u>Unblock Time</u> (Valid for FSK Mode Only)

<unblock time>20</unblock time>

Unblock Time is 0 - 500 ms in 1 ms steps.

Unblock Delay (Valid for FSK Mode Only)

<unblock delay>25</unblock delay>

Unblock Delay is a number between the range of 0 - 100 ms.

RCVR Drop Delay (Valid for AM Mode Only)

<fade drop delay>0</fade drop delay>

RCVR Drop Delay is 0 - 15 ms in 1 ms steps

<u>Trip Test</u> (Valid for FSK Mode Only)

<ttu0>1</ttu0>

Trip Test is a single digit value. Only 1 or 2 is valid:

- 1 Disabled
- 2 Enabled

Guard Before Trip (Valid for FSK Mode Only)

<guard t0>2</guard t0>

Guard Before Trip is a single digit value between 1 & 3:

- 1 Not Required
- 2 Required
- 3 Required But With Override

Blocking Priority (Valid for AM Mode Only)

<br/>blk pri0>1</blk pri0>

Blocking Priority is a single digit value:

- 1 Stop
- 2 Start

Checkback (Valid for AM Mode Only)

<checkback0>0</checkback0>

Checkback is a single digit value. Only 0 or 1 is valid:

- 0 Checkback Disabled
- 1 Checkback Enabled

#### Input/Outputs

<u>Inputs</u>

Contact Bounce

<in1 hold>1</in1 hold>

Contact Bounce is between 0 to 15. Each unit denotes 0.5 ms. As an example, 8 would be equal to 4ms.

Selection

<in1 selection>1</in1 selection>

Selection is a number between 0 & 8 or 9 depending on the mode:

**FSK** 

FSK-UB, FSK-DTT, FSK-POTT

- 0 Not Used
- 1 UB Key
- 2 Power Off
- 3 Trip Test
- 4 Disable Trip Test
- 5-52B
- 6 SOE Event 1
- 7 SOE Event 2
- 8 SOE Event 3

FSK-3 Freq

- 0 Not Used
- 1 LR Key
- 2 DTT Key
- 3 Power Off
- 4 Trip Test
- 5 Disable Trip Test
- 6 52B
- 7 SOE Event 1



8 – SOE Event 2	Trip Duty Outputs is a single digit value between 0
9 – SOE Event 3	& 2
FSK-4 Freq	FSK
0 – Not Used	0 – Not Used
1 – UB Key	1 – Guard
2 – Power Off	2 – Trip
3 – Trip Test	AM
4 - 52B	0 – Not Used
5 – SOE Event 1	1 – Blocking Output
6 – SOE Event 2	2 – Fade Alarm
7 – SOE Event 3	Low Level Outputs
AM	Selection
0 – Not Used	<pre><pre><pre><pre>prog1 selection&gt;</pre></pre></pre></pre>
1 – Carrier Start	Low Level Outputs is a single or double-digit value
2 – Carrier Stop	between 0 & 11 or 16 depending on the mode:
3 – Low Level Key	FSK
4 – Checkback Reset	Phase Comparison
5 – Checkback Initiate	0 – Not used
6 – SOE Event 1	1 – Trip Negative
7 – SOE Event 2	2 – Trip positive
8 – SOE Event 3	3 – Reflected Power
9 – Loopback Test	4 – Main RF Output
AM RX Only	5 – Redundant RF Output
0 – Not Used	6 – Good Channel
1 – SOE Event 1	7 – Noise
2 – SOE Event 2	8 – Fade Alarm
3 – SOE Event 3	9 – TX Shift High
Active State	10 – TX Shift Low
<in1_active_state>0</in1_active_state>	11 – General Failure
Active State is a single digit value. Only 0 or 1 is	2F-Unblocking & 2F-POTT/DTT
valid:	0 – Not used
0 – Application of Voltage	1 – Guard
1 – Removal of Voltage	2 – Trip
Trip Duty Outputs	3 – Reflected Power
Selection	4 – Main RF Output
<em1_selection>1</em1_selection>	5 – Redundant RF Output
	6 G 1 G 1

February 2018 Page C-5

6 – Good Channel



- 7 Noise
- 8 Fade Alarm
- 9 TX Shift High
- 10 TX Shift Low
- 11 Checkback Trip
- 12 Trip Test Failed
- 13 Trip Test in Progress
- 14 General Failure

### 3-Frequency

- 0 Not used
- 1 LR Guard
- 2 LR Trip
- 3 Reflected Power
- 4 Main RF Output
- 5 Redundant RF Output
- 6 Good Channel
- 7 Noise
- 8 Fade Alarm
- 9 TX Shift High
- 10 TX Shift Low
- 11 LR Checkback Trip
- 12 DTT Guard
- 13 DTT Trip
- 14 DTT Checkback Trip
- 15 Trip Test Failed
- 16 Trip Test in Progress
- 17 General Failure

#### 4-Frequency

- 0 Not used
- 1 A Guard
- 2 A Trip
- 3 Reflected Power
- 4 Main RF Output
- 5 Redundant RF Output
- 6 Good Channel
- 7 Noise
- 8 Fade Alarm

- 9 TX Shift to A
- 10 TX Shift to B
- 11 A Checkback Trip
- 12 B Guard
- 13 B Trip
- 14 B Checkback Trip
- 15 General Failure

#### AM

- 0 Not used
- 1 Blocking Output
- 2 Fade Alarm
- 3 Reverse Power
- 4 Main RF Output
- 5 Redundant RF Output
- 6 CB Off
- 7 CB Passed
- 8 Carrier Received
- 9 CB Major Alarm
- 10 CB Minor Alarm
- 11 CB Delayed Alarm
- 12 CB Carrier Recovered
- 13 CB In Recovery Mode
- 14 CB Test In Progress
- 15 CB Auto Test Disabled
- 16 General Alarm
- prog1 active>0/prog1 active>

Low level active state is a single digit value, only a 1 or 0 is valid.

- 0 Normally Open
- 1 Normally Closed
- prog1 action>0/prog1 action>

Low level action state is a single digit value, only a 1 or 0 is valid.

- 0 Normal
- 1 PULSED (on for 5 sec.)

NOTE: General Alarm is a valid option only for the EM Outputs.

De-Energized State



<em1 selection>1</em1 selection>

De-energized State is a single digit value:

- 0 Normally Open
- 1 Normally Closed

### **Checkback Configuration**

#### Module Address

<address>0</address>

Module Address is a number between 0 and 10. 0 being the Master and 1-10 are Remote Modules

#### Primary Communication Mode

<prim\_comm>1</prim\_comm>

Primary Communication mode is a single digit value. Only 0 or 1 is valid:

- 1 Coded Communication Mode
- 0 Timed Communication Mode

#### **Auto Tests**

<auto test>1</auto test>

Auto tests is a single digit value. Only 0 or 1 is valid:

- 1 Auto Tests On
- 0 Auto Tests Off

#### Fallback Communication Mode

<fallback>0</fallback>

Fallback Communication Mode is a single digit value. Only 0 or 1 is valid:

- 1 Enable Fall back Communication
- 0 Disable Fall back Communication

### Low Power Tests

low pwr>0</low pwr>

Low Power Tests is a single digit value. Only 0 or 1 is valid:

- 1 Enable Low Power Tests
- 0 Disable Low Power Tests

#### Last Module

<last rem>1</last rem>

Last Module is between 1 and 10; up to ten Remote Modules can be assigned.

#### Retries

<retries>4</retries>

Retries is 0 - 15, indicating, up to 15 retries are allowed.

#### Interval Type

<int type>0</int type>

Interval type is a single digit value. Only 0 or 1 is valid:

- 1 Checkback Hours of the day
- 0 Periodic checkback select

#### Hours Of The Day

(Valid only when 'Hours of the Day' is selected)

<time1>5</time1>

<time2>10</time2>

<time3>15</time3>

<time4>20</time4>

Hours of the day 0-23 in a 24 hour clock format. This indicates the hours of the day checkback needs to run.

#### Periodic Checkback

(Valid only when 'Checkback Hours' is selected)

<test period>8</test period>

Periodic Checkback is 0 - 99. This indicates the number of hours to wait before the next Checkback test will run.

#### Carrier Recovery

<reco enab>0</reco enab>

Carrier Recovery is a single digit value. Only 0 or 1 is valid:

- 1 Enable Carrier Recovery
- 0 Disable Carrier Recovery

#### Recovery Window

<recovery time>10</recovery time>

Recovery Window is a number between the range of 0-24 hours. It specifies how long a UPLC-II<sup>TM</sup> will be in Recovery Mode before indicating a Delayed Alarm.

#### Recovery Period

February 2018 Page C-7



<reco\_time>30</reco\_time>

Recovery Period number between the range of 5 – 60 minutes. It specifies the time between Master initiated Checkback tests when the UPLC-II<sup>TM</sup> is in Recovery Mode.

#### **Loopback Duration**

<loop\_time>10</loop\_time>

Loopback Duration is 4-60 seconds. It specifies how long a UPLC-II<sup>TM</sup> will key its transmitter at high and low power during a Loopback test.

#### Synchronize Clock Automatically

<sync\_enab>1</sync\_enab>

Synchronize Clock Automatically is a single digit value. Only 0 or 1 is valid:

- 1 Enable Automatic Synchronization
- 0 Disable Automatic Synchronization



# **Appendix D: User Management Interface (UMI)**

#### Introduction

The Universal Power Line Carrier device is network enabled allowing access to the settings and measured values via standard network interfaces and protocols. The UPLC-II contains a web server and allows a user to administer, configure, and view the near real-time status of the system while in operation. An authenticated user can use a standard browser to view and change the configuration of the system.

In addition to the web server interface, the UPLC can support either IEC61850 or DNP protocols for automated operation in the substation.

Prior to the UPLC-II management interface the only way to perform administrative changes was through the web server interface. Because of the new requirements requiring system operators to periodically change user passwords, it can be a time consuming task to access all the UPLC-IIs in the sub-stations as it currently requires a user to log in via a browser, make the changes and apply them on a unit by unit basis.

This interface provides a more automated method to make management changes to the UPLC-II that is:

- 1. Not HTML based
- 2. Provide services that are not necessarily supported by DNP or IEC61850
- 3. Management oriented similar to Administrative functionality
- 4. Uses the standard TCP/IP port 80 and HTTP for transport control.

A key feature of this management interface is that it is automation friendly. This means it does not use graphics and the response data is in clear text for easier parsing by an automated user agent. In addition, responses from the UPLC are delivered in XML format, allowing for easier parsing by the requesting agent.

The following services are supported:

1. Retrieve the user list on the UPLC-II.

- 2. Verify that a user/password combination is a valid user on the system.
- 3. Create a user account on the system.
- 4. Change the password of an already existing user.
- 5. Delete a user from the user list on the system.
- 6. Retrieve the UPLC-II settings in XML format.

In order to allow a user agent to perform these services, it is necessary to create a "management" user. This user type is the only type of user that can access the management interface. It is necessary for a user agent to be authenticated on the UPLC-II before the interface will respond.

### Creating a Management User (Fig. D-1)

Creating a management user is similar to creating any other user on the UPLC-II. A user becomes a management user through the use of permission settings presented on the Admin >Add User web page.

**Note:** Only Administrators or Super Users can create new user accounts on this page.

Once created, a management user is displayed in the normal user list, but with a "Management" role.

A management user differs from any other user role (e.g. permissions) on the UPLC-II in the following ways:

- 1. Only management users can access the management services.
- 2. A management user is not restricted from accessing the UPLC-II if another user is logged in.
- 3. A management user cannot access the web pages.
- 4. There can only be one management user in a given UPLC-II.

February 2018 Page D–1





Figure D-1. Creating a Management User

### **Basics of Management Services**

The main purpose of the management user is to be able to access web services on the UPLC-II directly, rather than go through interactive graphically oriented web pages to accomplish tasks.

The web services are built around the basic HTTP interface. For those services requiring parameters, the parameters are added to the request URL in a HTTP query string. This means that appended to the URL separated by a ? are a series of name/value pairs that become the parameters (the input data) to the service.

For more information on query strings, please see http://en.wikipedia.org/wiki/Query string

Following are the web services implemented on the current version of UPLC-II firmware and descriptions for use.

In the following descriptions, the form represents the input as typed into a web browser.

Since the UPLC-II system enforces basic authorization for access to these services, it is necessary to supply the management users' credentials when using the browser as the access device.

For automated user agents, it is possible to establish a connection to the UPLC and access the service

directly, supplying the credentials as part of the get request as "Authorization: Basic <uuencoded credentials>".

The user credentials are in the form username:password, and then encoded.

The form of the get request aside from the addition of Basic Authorization is beyond the scope of this document. All required parameters for the get request must be included.

**Note:** The following examples are derived from using Internet Explorer to access the management interface. This is done for clarity. The design of this interface allows access from other user agents such as .NET or other programmatic interfaces.

#### Authentication

For all management interface accesses, the request must include the username and password of the management user as part of the request.

If the username and password are not included as part of the request, or the username and password are not correct, the UPLC-II returns the standard HTTP 1.1 message: "401 Unauthorized - User authentication is required."



**Note** that this response is not formatted in xml as it is part of the HTTP implementation on the UPLC-II and such responses are standardized per rfc2616.

See http://www.w3.org/Protocols/ and in particular http://www.w3.org/Protocols/rfc2616/rfc2616-sec10.html

#### **Management Services/Commands**

## 1. Get User List (Fig. D-2)

Form: (*italicized bold text* is specific customer input data)

http://*uplc ip address*/manage\_get\_user\_list.htm Returns: The current user list stored on the UPLC-II unit. Errors: None.

#### 2. Verify User (Figs. D-3 to D-6)

Verify if a given user exists on the target system by supplying the user name and password of the user.

Form: (*italicized bold text* is specific customer input data)

http://uplc ip address/ manage\_verify\_user.htm?username=user name&password=user password

Returns Fig. D-3.

TRUE if user exists in the user list AND the password is correct

Screen shot (sample user with username "b" and password of "b" shown)

**Warning:** Please note that using this service via a browser requires that the username and password must be typed in clear text. Be sure to clear the browser cache if using this service via a browser.

#### Errors:

If Password is not correct, see Fig. D–4.

If user doesn't exist, see Fig. D-5.

If the parameters in the query string do not exist, or do not have the correct syntax, see Fig. D–6.

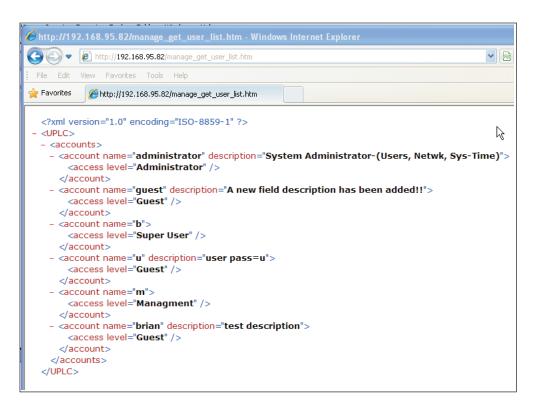


Figure D-2. Get User List



Figure D-3. Verify User - Successful Return



Figure D-4. Verify User - Incorrect Password

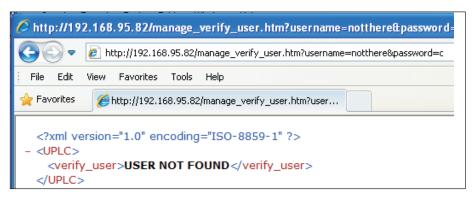


Figure D–5. Verify User – Invalid User



Figure D-6. Verify User - Invalid Parameter List



### 3. Create New User (Fig. D-7 to D-10)

Create a new user on the target UPLC-II.

Form: (*italicized bold text* is specific customer input data)

http://uplcipaddress/manage\_create\_user.htm?user name=newman&password=n&permissions=GUE ST&description=test

(The command above creates a new user on the UPLC-II with a user name of "newman" and a password of "n", as a GUEST user and an optional description of "test".)

Allowed user permissions values (must be exact):

GUEST USER ADMINISTRATOR SUPERUSER

**Note:** The management user interface is restricted to one management user in the UPLC-II. Therefore, it

is not possible to create a management user using this interface.

For the parameters "username" and "password", the length of the value is restricted to 32 characters. Any excess characters are truncated.

For the parameter "description", the length of the value is restricted to 100 characters.

**Warning:** Please note that using this service via a browser requires that the username and password must be typed in clear text. Be sure to clear the browser cache if using this service via a browser.

Verification of the new user creation via the normal web interface returns Fig. D–8.

To create a new user, it is required that the parameters "username", "password" and "permissions" are supplied. The parameter "description" is optional and may be omitted.

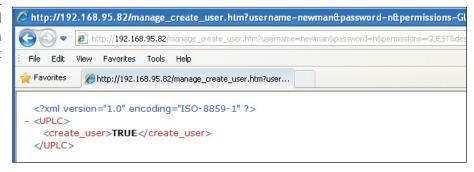


Figure D-7. Create User - Verification Return



Figure D-8. Create New User





Figure D-9. Create User – User Already Exists Error



Figure D-10. Create User - Parameters Not Supplied Error

#### Errors:

If user to be created already exists (Fig. D–9).

If all of the required parameters are not supplied or incorrect in some way (Fig. D-10).



#### 4. Change Password for Existing User

Form: (italicized bold text is specific customer input data)

http://uplcipaddress>/manage\_change\_password.htm?username=newman&password=newpassword Warning: Please note that using this service via a browser requires that the username and password must be typed in clear text. Be sure to clear the browser cache if using this service via a browser.

Successful return (Fig. D–11) Errors: User does not exist (Fig. D–12) Bad parameter list (Fig. D–13)

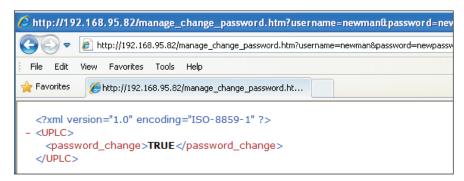


Figure D-11. Change Password - Successful Return



Figure D–12. Change Password – User Does Not Exist



Figure D–13. Change Password – Bad Parameter Error



#### 5. Delete User

The user account in the UPLC-II that matches the username will be removed.

Form: (italicized bold text is specific customer input data)

http://uplcipaddress>/manage\_delete\_user.htm?username=user name to be removed Successful return (Fig. D-14).

Note: upon success, the user name is returned as well for verification.

Errors:

Incorrectly formed request (Fig. D–15).

A user matching the supplied name is not in the UPLC-II list of accounts (Fig. D–16)



Figure D-14. Delete User - Successful Return



Figure D-15. Delete User - Bad Parameter Error



Figure D-16. Delete User - User Not Found Error



## 6. Get UPLC-II Settings

This returns the UPLC-II settings in xml format. Form: http://uplcipaddress>/manage\_get\_uplc\_set.htm See XML report at the end of this appendix. Errors: None

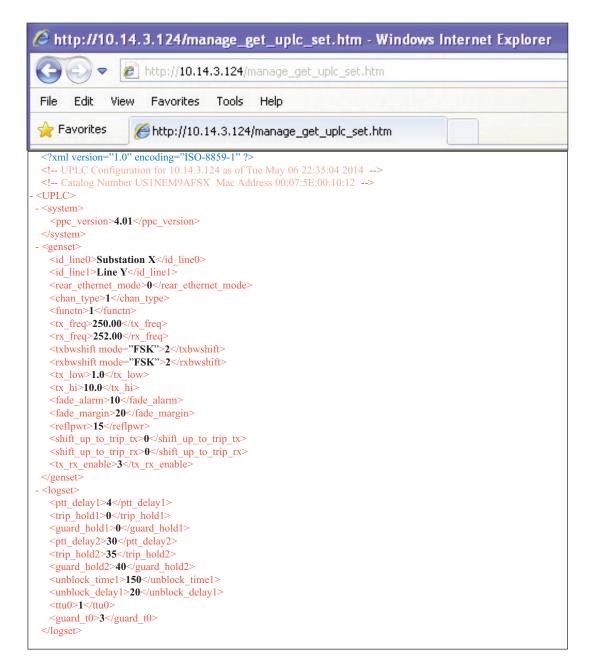


Figure D-17. Get UPLC-II™ Settings - Settings XML Report



```
<ioset>
  <in1_hold>0</in1_hold>
   <in1_selection>0</in1_selection>
  <in1_active_state>0</in1_active_state>
  <in2 hold> o</in2 hold>
  <in2_selection>0</in2_selection>
  <in2 active state>0</in2 active state>
  <in3_hold>0</in3_hold>
  <in3 selection>0</in3 selection>
  <in3_active_state>0</in3_active_state>
  <in4_hold>\bar{0}</in4_hold>
   <in4 selection>0</in4 selection>
  <in4_active_state>0</in4_active_state>
  <in5 hold>0</in5 hold>
  <in5_selection>0</in5_selection>
  <in5 active state>0</in5 active state>
 </inputs>
<tdoutputs>
  <em1_selection>0</em1_selection>
  <\!\!em2\_selection\!\!>\!\!0\!\!<\!\!/em2\_selection\!\!>
   <em3 selection>0</em3 selection>
  <em4_selection>0</em4_selection>
 </tdoutputs>
<lloutputs>
   prog1_selection>0/prog1_selection>
  prog1_active>
  prog1_action>0</preg1_action>
  cprog2_selection>0/prog2_selection>
  prog2_active>
   prog2_action>0/prog2_action>
  cprog3_selection>0/prog3_selection>
   g3_active>0</preg3_active>
  prog3_action>0</preg3_action>
  prog4_selection>0/prog4_selection>
  prog4_active>0</prog4_active>
  oq4_action>0
  cprog5_selection>0/prog5_selection>
  prog5_active>0</preg5_active>
   prog5_action>0</preg5_action>
  cprog6_selection></prog6_selection>
   prog6 active>0d active>
  prog6_action>0/prog6_action>
  <\!\!prog7\_selection\!\!>\!\!\hat{\boldsymbol{0}}\!\!<\!\!/prog7\_selection\!\!>
  <\!\!prog7\_active\!\!>\!\!0\!\!<\!\!/prog7\_active\!\!>
  prog7_action>0</preg7_action>
  prog8_selection>0/prog8_selection>
  prog8_action>0/prog8_action>
   prog9_selection>0/prog9_selection>
  prog9_action>0/prog9_action>
   prog10 selection>0/prog10 selection>
  prog10_action>0/prog10_action>
 </ioset>
<trip test>
   <tttype>0</tttype>
  <auto_test>0</auto_test>
   <int type>0</int type>
  <time1>6</time1>
  <time2>12</time2>
  <time3>18</time3>
  <time4>0</time4>
  <test_period>8</test_period>
 </trip test>
 </UPLC>
```

Figure D-17. (cont'd) Get UPLC-II™ Settings - Settings XML Report



# **Appendix E: Sequence of Events (SOE) Listing**

#### **Access Events**

<User name> Logged off

<User name> Logged on

Front panel logoff

Front panel logon

User logged in

User logged out

#### **Hardware Events**

DC power down

DC power up

General alarm

General alarm reset

I/O board failed

I/O board restored

Main power supply failed

Main power supply restored

Main TX power low

Main TX power OK

Novram settings restored from flash memory of <Date>

Power amp failed

Power amp restored

Redundant power amp failed

Redundant power amp restored

Redundant power supply failed

Redundant power supply restored

Redundant TX power low

Redundant TX power OK

Battery Failure

#### **Firmware Events**

All UPLC<sup>TM</sup> settings initialized to default values

DSP checksum mismatch

Ethernet settings restored from flash memory

Ethernet settings restored from flash memory of <Date>

Ethernet settings set to default values

SOE file system repaired

Software Watchdog reset occurred (x)

Events cleared



#### **Calibration Events**

Local transmitter calibrated

Local transmitter failed calibration

Receiver calibrated to distant transmitter

Receiver calibrated to local transmitter

Receiver failed distant transmitter calibration

Receiver failed local transmitter calibration

#### **LAN Communications Events**

Ethernet interface 1 not detected

Ethernet interface 2 not detected

Ethernet link lost

Ethernet link restored

Redundant ethernet link lost

Redundant ethernet link restored

#### **Administration Events**

<User name>: User account deleted from the system

<User name>: User account modified

New user added to the system

Settings changed by <User name>

Settings changed via front panel

Settings file uploaded to the system

### **Events Caused by External Stimulus**

IRIG signal acquired

IRIG signal lost

User event 1 - reset

User event 1 - set

User event 2 - reset

User event 2 - set

User event 3 - reset

User event 3 - set

### System Events in All Modes

#### **Receiver Functions**

Fade alarm off

Fade alarm on

#### Transmitter Functions

RF powered off

RF powered on



## System Events for ON/OFF Mode

#### Receiver Functions

Carrier off

Carrier on

#### Transmitter Functions

Low level key

Low level key reset

TX start key

TX start key reset

TX stop key

TX stop key reset

#### **Checkback Events**

<current module name> received timed CB

<current module name> sent high power CB to <module name>;

<current module name> sent low power CB to <module name>

<current module name> failed <module name>'s high power coded test

<current module name> failed <module name>'s low power coded test

<current module name> passed <module name>'s high power CB

<current module name> passed <module name>'s low power CB

<current module name> passed <module name>'s high power coded CB

<current module name> passed <module name>'s low power coded CB

<current module name> received <module name>'s high power coded CB

<current module name> received <module name>'s low power coded CB

<Current Module Name> received timed CB

<current module name> sent high power coded CB to <module name>;

<current module name> sent high power timed CB to <module name>;

<current module name> sent low power coded CB to <module name>;

<current module name> sent low power timed CB to <module name>;

<module name> Alarms cleared

<module name> Checkback event counts cleared

<module name> failed high power CB

<module name> failed low power CB

<module name> failed high power coded CB

<module name> failed high power timed CB to <module name>;

<module name> failed low power coded CB

<module name> failed low power timed CB to <module name>;

<module name> passed high power coded CB

<module name> Passed high power test



<module name> passed high power timed CB to <module name>;

<module name> passed low power coded CB

<module name> Passed low power test

<module name> passed low power timed CB to <module name>;

Auto checkback tests disabled

Auto checkback tests enabled

Carrier recovered

CB Alarms Cleared

CB event counts cleared

Communications error

Delayed alarm reset

Delayed alarm set

Local carrier failed

Major alarm cleared

Major alarm set

Minor alarm cleared

Minor alarm set

Remote <module number> requested CB

Starting carrier recovery mode

## System Events for FSK Mode

#### Receiver Functions

Channel lost

Channel restored

Noise detected

Noise reset

### Transmitter Functions

Boost key reset

Boost key set

### 2-Frequency DTT/POTT/Unblock

### Receiver Functions

Guard

Loss of guard

Trip

Trip reset

Unblock trip

Unblock trip reset

#### Transmitter Functions

Trip key



Trip key reset

## 3-Frequency Mode

#### **Receiver Functions**

DTT guard

Loss of DTT guard

DTT trip

DTT trip reset

LR guard

Loss of LR guard

LR trip

LR trip reset

#### Transmitter Functions

LR trip key

LR trip key reset

DTT trip key

DTT trip key reset

## **Phase Comparison**

### Receiver Functions

Trip negative off

Trip negative on

Trip positive off

Trip positive on

#### **Transmitter Functions**

PC Key Off

PC key on

## **Trip Test Events**

Failed Trip Test

Passed Trip Test

Received CB Trip Test request

Received real Trip Test request

Request CB Trip Test

Request real Trip Test

### 4-Frequency Mode

## Receiver Functions

Trip A

Trip A Reset

Loss of Guard A

Guard A

Loss of Guard B

Guard B

Unblock A

Unblock A Reset

Unblock B

Unblock B Reset

Both Trip A & B

Both Trip A & B Reset

Guard A & B

Guard A & B Reset

#### Transmitter Functions

A key

B key

A & B key



## **USER NOTES**



# Appendix F: Changing the Cat. No. on a UPLC-II™

- 1. Login to the UPLC-II<sup>TM</sup> with either the administrator or superuser account. (Default administrator login is "administrator" and password is "pulsar".)
- 2. On the left-hand side navigator, click on "Admin". This should take you to a page with four tabs across the top.
- 3. Select the "Catalog Number" Tab. You will see a "Submit Key" box at the bottom with a field in which to type in the provided hexadecimal key code(s) to update the catalog number. These codes are MAC address specific. The MAC address of the UPLC-II<sup>TM</sup> you are logged into is shown at the top of the screen.
- 4. Locate the appropriate key code for the MAC address and insert the key code in the box provided. If you have an electronic copy of the key codes, you can copy and paste the key code into the box to help eliminate errors.

- 5. Hit the "Submit Key" to start the process to update the catalog number. You will see a description of the catalog number you are about to install. It should read as shown in Figure 42, with the exception of the receive-only chassis or dual-power-amp chassis, which will change appropriately.
- 6. Should you get a message to contact Pulsar Sales, you may have used the wrong key code with the MAC address you are trying to update. Re-check the key code and the MAC address and try again.
- 7. Click the "Continue" button.
- 8. You will receive a message window about logging out from the UPLC-II<sup>TM</sup> and rebooting it. Click "OK" to continue.
- 9. The system will reboot and the UPLC-II<sup>TM</sup> is now updated. Settings should not have changed during this process but a quick check would be in order.

You have completed the update.

ser Admin	Firmware	Protocol	Catalog Number
System Confi	guration		
Mac Address	00 07 5E	00 10 12	
Catalog No.	US1NEI	M9AFSX	
Configuration	Single T	ransceiver	
Main Power Sup	oply 110/125	/250 Vdc	
Redn. Power Su	pply None		
Outputs		d Outputs w/ Trip Duty	
Logic	Standar	-	
Ethernet Ports (		ant/Daisy Chain 2 RJ-45	(10/100 BaseT)
Protocols	DNP 3.0		
Front Port		1/RS-232	ula was
Testing		Checkback Test / FSK T	•
Power Amp Fea	tures improve Power	Improved Power Amp with Freq Selectivity for Refl Power	
			Submit Key

UPLC-II™ Catalog Number Update



## **USER NOTES**



# Appendix G: Upgrading the firmware in a UPLC-II™

# NOTE: Never downgrade to a lower firmware version.

## General Firmware Upgrade Procedure

(Specific instructions for a particular firmware version are provided with each firmware release on the www.ametekpower.com website.)

Cautions when upgrading to later firmware versions:

- Protection system must be out of service and all trip circuits opened, in order to upgrade the firmware.
- Reconfirm all settings and calibrations prior to putting back in service.
- Upgrading from previous firmware versions usually will revert the settings to the factory default of an ON/OFF unit. You will need to then reload your settings.
- If the transceiver board hardware revision is less than revision 7, please contact the factory for a replacement board. The revision can be identified on the administration page under the "Firmware" tab when you are connected to the unit or through the front panel keypad SET button menu (Configure/View Revisions).
- Check what version of Internet Explorer you are using before starting to upgrade. If using IE9 or higher then you must be in 'compatibility view' to avoid issues. IE8 and older versions will work fine.

#### **Upgrade Process**

- 1. Log in using the Ethernet port (faster port) or RS-232 (slower port) on the UPLC-II<sup>TM</sup> with an administrator or super-user account. See chapter 5 for details.
- 2. If not previously done, save the settings configuration file as a "xml" file (remembering to add the .xml extension to the file name) and as a "report" file (.txt). The SOE file (.csv) may also be saved if desired.

- [NOTE: If you do not get a pop up window asking you where to save this file, then try continuously holding down the control key (CTRL) before clicking the "save configuration" button and keeping it held down until the window pops up, then release the key.]
- 3. Take the UPLC-II<sup>TM</sup> system out of service by powering it down, removing the coax from the rear of the chassis and loading the transmitter output (J1) with a 50 or 75 ohm non-inductive resistor, whichever is the applicable load. Power the unit back up.
- 4. Two files make up the upgrade process if updating from Version 2.0x to later versions. The code loader (UPLCL1\_5.mem) file must be uploaded to the UPLC-II<sup>TM</sup> unit first. (If updating from Version 3.0x or higher the code loader file is not required, so skip to step 7). This will prepare the unit to accept the actual firmware file (UPLCVx\_xx.mem). Copy these two files to a directory on the computer that you will be using for upgrading the UPLC-II<sup>TM</sup>.
- 5. Log back onto the system as in step 1 prior. On the left hand side of the web page, click on "Admin". This will take you to the administration page. Click on the tab labeled "Firmware". There you will see a browse button for locating the needed files. Click on the button and navigate to where you have stored the files in Step 4. Select the code loader file (UPLCL1 5.mem), then click on "update code". The system will go through several steps. DO NOT TURN UNIT OFF during this process. Click on the Continue and OK button, when prompted to do so in order to continue the process. When complete, the UPLC-II<sup>TM</sup> front panel will display the words "CODE LOADER" to indicate that it is non-functional and ready to be updated to latest firmware.



- 6. Close the browser and log back onto the system as in step 1.
- 7. You will be directed to the firmware update page automatically. (If you have skipped step 5 and 6, then Log into the system as in Step 1 before continuing with this step.) On the left hand side of the web page, click on "Admin". This will direct you to the administration page. Click on the tab labeled "Firmware." There you will see a browse button for locating the needed files. Click on the button and navigate to where you have stored the files in Step 4. Select the firmware file (UPLCVx xx.mem), then click on "update code". The system will go through several steps. Hit "continue" and OK when prompted.
- 8. If the unit does not see new code as shown in Figure 1, and you have waited at least 10 minutes, cycle the power and try again. Once the unit sees the new code, it will check several files (as shown in Figure G-1) and prepare the unit for upgrading.
- 9. At that point you should see a web page similar to Figure G– 2.
- 10. After you have hit the "continue" button, DO NOT

User Admin Firmware Protocol **Catalog Number Software Update Status** Validating UPLCv4\_06.mem Checking .reset Checking .version Checking .secinfo Checking .text

Figure G-1



Figure G-2

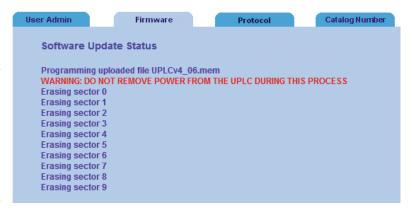


Figure G-3

- TURN THE UNIT OFF during this process. You should see something like Figure G–3.
- 11. Reload the settings files saved in Step 2. Reconfirm the desired settings. The Trip Duty outputs may need to be reprogrammed according to the desired settings. Recalibrate the transmitter & receiver per chapter 5.



# Page numbers are hyperlinked.

2-Frequency	Computer (PC), Windows XP
Alarms, Checkback       6–9         Alarms, Fade Alarm       3–39, 5–17, 5–34         Alarms, Fail Safe       5–27         Alarms, Front Panel       4–2         Alarms, FSK Mode       3–38         Alarms, General       3–15         Alarms, Good Channel       3–39         Alarms, Main RF Output       3–39         Alarms, ON/OFF Mode       3–15	Direct Transfer Trip (DTT) 3–28, 3–29, 3–35 Directional Comparison Blocking (DCB) 3–1 Display Board (Module) 2–14 DNP3 7–1 Downloads, Report File 5–15 Downloads, Settings 5–14 Downloads, SOE's 5–33 Downloads, XML File 5–14
Backplane	EM Relay3–9, 3–10, 3–11, 3–13, 3–14 Ethernet Board (Module)2–20 Ethernet Cable5–10 Ethernet, IP Address5–10
Calibration	Fade Alarm       3-39, 5-17, 5-34         Fade Margin       5-17, 5-34         Firmware, Version       5-16, 5-36         Frequency Spacing       2-3         Frequency Specifications       2-1         Front Display Alarm Codes       4-2         Front Display RX States       5-36         Front Panel, Parameters       5-36         Front Panel, Password       5-36         Front Panel, Set Menu       5-36         Front Panel, Test Menu       5-37         G       G
Computer (PC), RS-2325–11, A–1, A–2 Computer (PC), Setup5–10 Computer (PC), Windows 7A–2	Hot Swappable2–1 Hybrids3–40

Index



# Page numbers are hyperlinked.

I	S
IEC61850	Settings (Logic), Guard Before Trip5–21 Settings (Logic), ON/OFF5–21 Settings (Logic), Pre-Trip Delay5–21 Settings (Logic), Unblock Timer5–21 Settings, Downloads5–14 Spare Modules2–5
Jumpers	Terminal Blocks, Connections
Keying Logic2–25, 2–26, 2–27, 2–28	•
Log In, Ethernet	Unblock (DCUB) System3–17 Users, Administrator5–13 Users, Management User5–14, D–1 Users, Super User5–13
Outputs, EM Contacts (Low Level)5–27 Outputs, Settings	
Passwords, Front Panel	
Receiver Sensitivity5–17, 5–34	